

1 **Maximum likelihood estimation of the geometric**
2 **niche preemption model**

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9

Abstract

10 The geometric series or niche preemption model is an elementary eco-
11 logical model in biodiversity studies. The preemption parameter of this
12 model is usually estimated by regression or iteratively by using May's equa-
13 tion. This article proposes a maximum likelihood estimator for the niche
14 preemption model, assuming a known number of species and multinomial
15 sampling. A simulation study shows that the maximum likelihood estimator
16 outperforms the classical estimators in this context in terms of bias and pre-
17 cision. We obtain the distribution of the maximum likelihood estimator and
18 use it to obtain confidence intervals for the preemption parameter and to de-
19 velop a preemption t test that can address the hypothesis of equal geometric
20 decay in two samples. We illustrate the use of the new estimator with some
21 empirical data sets taken from the literature and provide software for its use.

22 *Key words:* geometric series; preemption t test; broken stick model; rank-abundance
23 plot; robustness;

24 **1 Introduction**

25 The statistical modeling of the relative abundance of a set of species in an ecolog-
26 ical community has a longstanding history (Wilson, 1991). Classical elementary
27 models are MacArthur's (1957) broken stick model, Fisher's (1943) log series, the
28 geometric model (Motomura, 1932) and the log-normal model (Preston, 1962).
29 Magurran (2004) provides an excellent introduction to these models. Over the last
30 decades, many more refined models have been proposed (Tokeshi, 1990, 1996).
31 Notwithstanding, the most elementary models such as the broken stick model and

32 the geometric series form important references and are widely applied (Fattorini,
33 2005); they are usually the ones that are first fitted before more complicated al-
34 ternatives are considered. In this article we focus on the geometric series, also
35 known as the *niche preemption hypothesis*. This model assumes each species suc-
36 cessively exploits a fraction k of the available resources, such that the first species
37 exploits fraction k of the total resources, the second species fraction k of the re-
38 maining $1 - k$ resources, and so on. The exploited fraction is reflected by the
39 relative abundance of the species in the community. Mathematically, the model is
40 described by

$$\frac{n_i}{N} = \frac{k(1-k)^{i-1}}{1-(1-k)^S} \quad i = 1, \dots, S, \quad (1)$$

41 where N is the total number of individuals found, S the total number of species, n_i
42 the abundance of the i th species, and k the niche preemption parameter. In our no-
43 tation, we will use $n_{(i)}$ to refer to the ordered abundances, such that $n_{(1)}$ and $n_{(S)}$
44 represent the most and least abundant species respectively. Doi and Mori (2013)
45 gives more historical background on the geometric series. Though the geometric
46 model is regarded as deterministic (Magurran, 2004), we note that the right hand
47 side of Eq. (1) corresponds to the probability function of a truncated geometric dis-
48 tribution. This model implies that the logarithm of the relative abundance decays
49 linearly with the rank of the species, as illustrated in a logarithmic rank-abundance
50 plot in Figure 1 for various values of k .

51 The geometric model has been found adequate for species-poor assemblages,
52 resource-poor environments (Fattorini, 2005) and has also been advocated for
53 ecosystems that suffer from anthropogenic disturbance (Caruso and Migliorini,

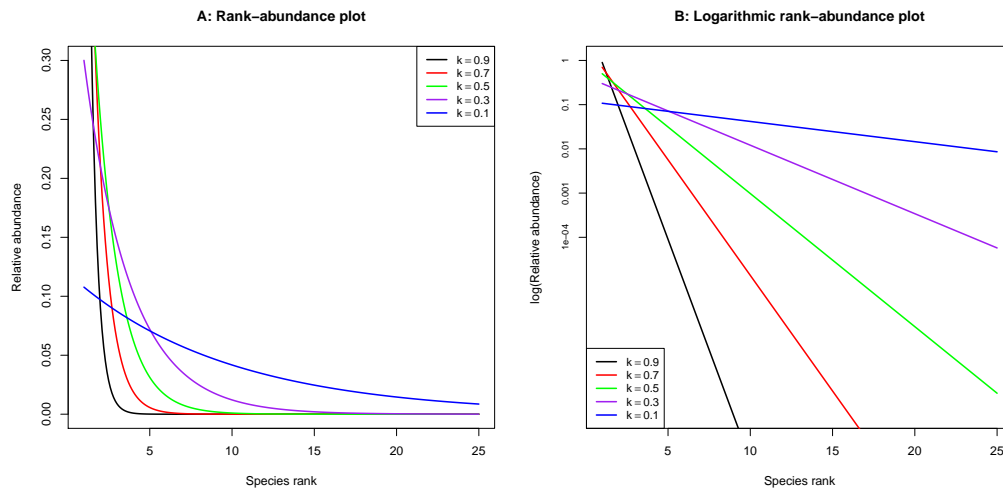


Figure 1: Rank-abundance plots for varying k of the geometric model with $S = 25$, with relative scale (panel A) and logarithmic scale (panel B).

54 2006) or that exhibit strong dominance of a few species (Keeley and Fothering-
55 ham, 2003). Several estimators for k have been proposed in the literature. He
56 and Tang (2008) used several estimators and observed that they provide similar
57 estimates of k . However, a statistical study that compares the different estimators
58 assessing their precision and bias seems not available. The main goal of this article
59 is to present a new estimator based on maximum likelihood (ML), and to compare
60 the different estimators in terms of bias and precision. The structure of the article
61 is the following. In Section 2 we review existing estimators for the niche preemp-
62 tion parameter, develop the ML estimator and present the preemption t test. In
63 Section 3 we compare the different estimators in a simulation study. Section 4
64 shows some applications using ecological datasets taken from the literature. We
65 finish with a discussion of the different estimators.

66 **2 Preemption parameter estimation and the preemp-** 67 **tion t test**

68 We briefly summarise some popular estimators for k , and develop the maximum
69 likelihood estimator. May (1975) proposed to estimate k by solving the equation

$$\frac{n_{(S)}}{N} = \frac{k(1-k)^{(S-1)}}{1-(1-k)^S}. \quad (2)$$

70 This result is obtained by applying Eq. (1) to the minimum abundance with rank
71 $i = S$. This equation can easily be solved on a computer by applying an algorithm
72 searching for the root of a non-linear equation. He and Tang (2008) used both the
73 minimum and maximum abundance, and proposed the estimator

$$\hat{k}_{HT} = 1 - \left(\frac{n_{(S)}}{n_{(1)}} \right)^{1/(S-1)}, \quad (3)$$

74 which follows from the fact that successive abundances have a constant ratio. The
75 least-squares regression estimator (He and Tang, 2008), \hat{k}_{LS} , is obtained by noting
76 that the logarithm of the relative abundance is linear in the rank i of the species
77 with slope $b_1 = \ln(1-k)$;

$$\ln\left(\frac{n_i}{N}\right) = \ln\left(\frac{k}{(1-k)(1-(1-k)^S)}\right) + \{\ln(1-k)\}i \quad (4)$$

78 By transforming the slope, we have:

$$\hat{k}_{LS} = 1 - e^{b_1}, \quad (5)$$

79 where b_1 is the least squares estimator for the slope obtained by simple linear re-

gression of $y_i = \ln\left(\frac{n_i}{N}\right)$ on rank i . We note here that \hat{k}_{May} and \hat{k}_{HT} do not assume
a statistical model for the data, but employ the geometric series in a completely de-
terministic manner. The geometric series is considered to be a deterministic niche
apportionment model (Magurran, 2004, p. 47). Consequently, there is no esti-
mation of a measure of uncertainty for these estimators. The regression estimator
 \hat{k}_{LS} assumes that deviations from geometric decay follow a normal distribution
and therefore an expression of the uncertainty of the estimate can be obtained by
back-transforming the limits of the confidence interval for β_1 :

$$CI(k) = \left(1 - e^{b_1 + t_{\alpha/2} s_{b_1}}, 1 - e^{b_1 - t_{\alpha/2} s_{b_1}}\right), \quad (6)$$

where s_{b_1} is the standard error of the slope, and $t_{\alpha/2}$ the upper percentile of a
Student t distribution with $S - 2$ degrees of freedom. We proceed by developing
the maximum likelihood estimator. If the number of species S is considered fixed,
then the data consists of counts in a limited number of S categories, which can be
probabilistically modeled by the multinomial distribution, given by.

$$L(\theta|\mathbf{n}) = \frac{N!}{\prod_{i=1}^S n_i!} \prod_{i=1}^S \theta_i^{n_i} = \frac{N!}{\prod_{i=1}^S n_i!} \prod_{i=1}^S \left(\frac{k(1-k)^{i-1}}{1-(1-k)^S}\right)^{n_i}. \quad (7)$$

Under the geometric model, the parameters of this multinomial distribution are
restricted, such that the parameter θ_i is given by the truncated geometric distri-
bution given by the right hand side of Eq. (1). Maximizing the log-likelihood
analytically, we find no closed form solution for k . The ML estimator \hat{k}_{ML} must

97 be found by numerically solving the equation

$$N - k \sum_{i=1}^S i \cdot n_i - (1 - k)^S \left(N(1 + kS) - k \sum_{i=1}^S i \cdot n_i \right) = 0 \quad (8)$$

98 for k . For communities with few dominant species (large k), the last term in
 99 Eq. (8) will generally be small, and the ML estimator can be approximated, in
 100 closed form, by

$$\hat{k}_{ML} \approx \frac{N}{\sum_{i=1}^S i \cdot n_i} = \frac{n_1 + n_2 + \dots + n_S}{n_1 + 2n_2 + 3n_3 + \dots + Sn_S}, \quad (9)$$

101 which is the total abundance divided by the abundance-weighted sum of the ranks.
 102 Eq. (9) can be used as initial estimate for the fast resolution of Eq. (8). By devel-
 103 oping the second derivative of the log-likelihood function, the variance of the ML
 104 estimator is obtained as

$$V(\hat{k}_{ML}) = \frac{k^2(1 - k)^2 C_k^2}{N(1 - 2k)C_k^2 + NkC_k(1 - (1 - k)^S\{1 + kS\}) + NSk^2(1 - k)^S(C_k - S)}, \quad (10)$$

105 with $C_k = 1 - (1 - k)^S$, and this variance can be estimated by substituting \hat{k} for
 106 k . Because the ML estimator is asymptotically unbiased, efficient, and normally
 107 distributed (Casella and Berger, 2002, Chapter 10), we can construct a $100(1 - \alpha)$
 108 percent confidence interval for k which is given by

$$CI_{(1-\alpha)}(k) = \hat{k}_{ML} \pm z_{\alpha/2} \cdot \sqrt{V(\hat{k}_{ML})}. \quad (11)$$

109 The limits of this confidence interval allow for hypothesis testing with k , and they
 110 can also be used to show the uncertainty in the estimate of k in a rank-abundance

111 plot (See Figures 3 and 4) by painting a corresponding grey area around the line
112 of decay. We study the statistical properties of the new ML estimator and its clas-
113 sical counterparts in a simulation study in Section 3.

114

115 Many biodiversity studies are of comparative nature. It is often of interest to
116 compare two (or more) independent samples with respect to some measure of di-
117 versity. Such tests have been developed for the Shannon index (Hutcheson, 1970)
118 and for Simpson's index (Brower et al., 1998), but are apparently not available
119 for the preemption parameter of the geometric series. To test the null hypothesis
120 $k_1 = k_2$ against $k_1 \neq k_2$, we can use the test statistic

$$T = \frac{\hat{k}_1 - \hat{k}_2}{\sqrt{V(\hat{k}_1) + V(\hat{k}_2)}}. \quad (12)$$

121 The development of this test is analogous to a standard two-sample t test for equal-
122 ity of means without assuming equality of variances for the two groups (DeGroot,
123 1986), using the Welch modification. Under the null, statistic T follows a student
124 t distribution with degrees of freedom (df) given by:

$$\text{df} = \frac{\left(V(\hat{k}_1) + V(\hat{k}_2)\right)^2}{V(\hat{k}_1)^2/N_1 + V(\hat{k}_2)^2/N_2}. \quad (13)$$

125 We refer to this test as the *preemption t test*. Some examples are given in Section 4
126 below. In practice, N_1 and N_2 are large, and the standard normal distribution can
127 be used for the calculation of the p-value.

128 **3 Monte Carlo simulations**

129 We simulate species counts by drawing samples from the multinomial distri-
130 bution given by Eq. (7), for given N, S and a considering a sequence of val-
131 ues $(0.1, 0.2, \dots 0.9)$ for preemption parameter k . We repeat simulations 10,000
132 times, computing all four estimators presented in the previous section. Boxplots
133 of the values of the estimators obtained in the simulations are shown in Figure 2.
134 This figure shows the ML estimator has the smallest variance for all values of k .
135 All other estimators typically have more bias than the ML estimator. Table 1 sum-
136 marizes the results of the simulation, quantifying bias, variance and mean squared
137 error (MSE) for all estimators and different values of k .

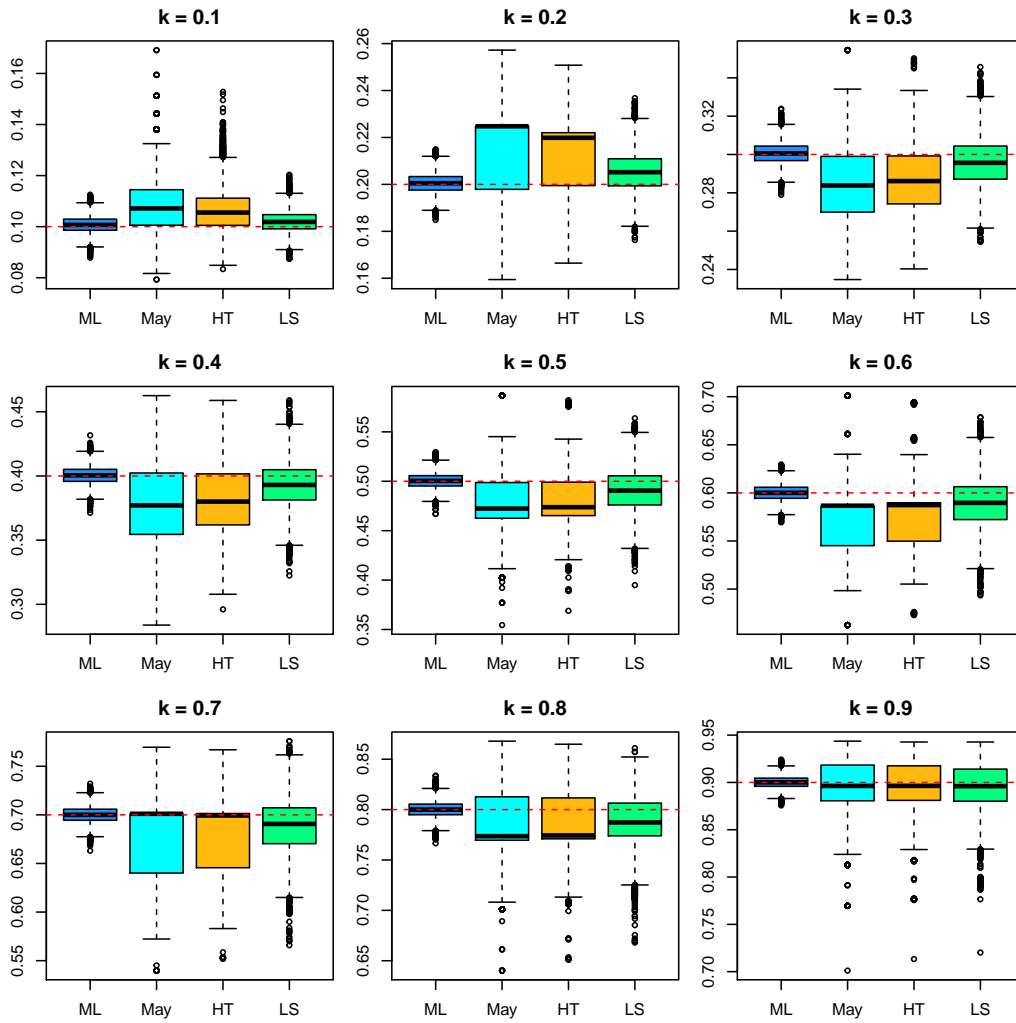


Figure 2: Monte Carlo simulations for the geometric series. Distribution of the different estimators for $N = 2,000$, $S = 25$ and various values of k .

138 For small value of k (≤ 0.20) the estimators of May, He and Tang, and the regres-
139 sion estimator have positive bias, and for larger values they have negative bias.
140 Table 1 shows that the ML estimator has the smallest bias, variance and MSE in
141 all settings, and is clearly the estimator with the best statistical properties. The
142 least-squares estimator has generally less bias than the estimators of May and He
143 and Tang. The estimator of May has the largest variance, and also presents more
144 outliers. Similar results were obtained for larger and smaller values of N (results
145 not shown).

k	Method	mean	bias	var	mse
0.1	ML	0.1007	0.0007	0.00001	0.00001
	May	0.1084	0.0084	0.00012	0.00019
	HT	0.1063	0.0063	0.00007	0.00011
	LS	0.1020	0.0020	0.00002	0.00002
0.2	ML	0.2005	0.0005	0.00002	0.00002
	May	0.2156	0.0156	0.00025	0.00049
	HT	0.2132	0.0132	0.00018	0.00035
	LS	0.2053	0.0053	0.00007	0.00010
0.3	ML	0.3006	0.0006	0.00003	0.00003
	May	0.2862	-0.0138	0.00035	0.00054
	HT	0.2879	-0.0121	0.00027	0.00041
	LS	0.2959	-0.0041	0.00016	0.00018
0.4	ML	0.4005	0.0005	0.00005	0.00005
	May	0.3813	-0.0187	0.00068	0.00103
	HT	0.3834	-0.0166	0.00053	0.00081
	LS	0.3930	-0.0070	0.00031	0.00035
0.5	ML	0.5005	0.0005	0.00006	0.00006
	May	0.4792	-0.0208	0.00102	0.00145
	HT	0.4814	-0.0186	0.00082	0.00117
	LS	0.4907	-0.0093	0.00047	0.00056
0.6	ML	0.6001	0.0001	0.00007	0.00007
	May	0.5788	-0.0212	0.00127	0.00172
	HT	0.5808	-0.0192	0.00106	0.00143
	LS	0.5894	-0.0106	0.00063	0.00074
0.7	ML	0.7002	0.0002	0.00007	0.00007
	May	0.6798	-0.0202	0.00137	0.00178
	HT	0.6815	-0.0185	0.00117	0.00151
	LS	0.6891	-0.0109	0.00072	0.00084
0.8	ML	0.8001	0.0001	0.00006	0.00006
	May	0.7829	-0.0171	0.00129	0.00158
	HT	0.7841	-0.0159	0.00114	0.00139
	LS	0.7895	-0.0105	0.00075	0.00086
0.9	ML	0.9001	0.0001	0.00004	0.00004
	May	0.8896	-0.0104	0.00072	0.00083
	HT	0.8902	-0.0098	0.00066	0.00076
	LS	0.8924	-0.0076	0.00048	0.00054

Table 1: Mean, variance, bias and mean squared error for different estimators of preemption parameter k .

146 **4 Analysis of empirical data sets**

147 In this section we apply the different estimators to some empirical datasets taken
148 from the ecological literature. Many data sets are available at the Ecological Reg-
149 ister (Alroy, 2015). We use Australian bird abundances (Fattorini, 2005; Magur-
150 ran, 1988) and Indian dung beetles (Ganeshiah et al., 1997; Magurran, 2004) to
151 illustrate the difference between estimators of the preemption parameter. We use
152 the dung beetle data from Mehrabi et al. (2014) to illustrate the preemption t -test.

153 **4.1 Australian bird abundances**

154 The abundances of $S = 31$ bird species in wet sclerophyll forest, totalling $N =$
155 834 individuals were recorded. Figure 3 shows the rank-abundance plot of this data,
156 with a fitted line for each of the four estimators discussed in Section 2. The numer-
157 ical estimates of the preemption parameter are very similar for all four estimators
158 (See Table 2) and by visual inspection the geometric model is seen to fit the data
159 very well. The grey zone in the plot is determined by the confidence limits for the
160 ML estimator. All other estimators give values inside this confidence interval, and
can be considered not to differ significantly from the ML estimate.

Estimator	\hat{k}	se	95% CI
May	0.149	-	-
HT	0.146	-	-
LS	0.142	-	(0.136, 0.148)
ML	0.143	0.0051	(0.133, 0.153)

Table 2: Estimates of the preemption parameter for the Australian bird data ac-
cording to different methods (se = standard error, CI = confidence interval).

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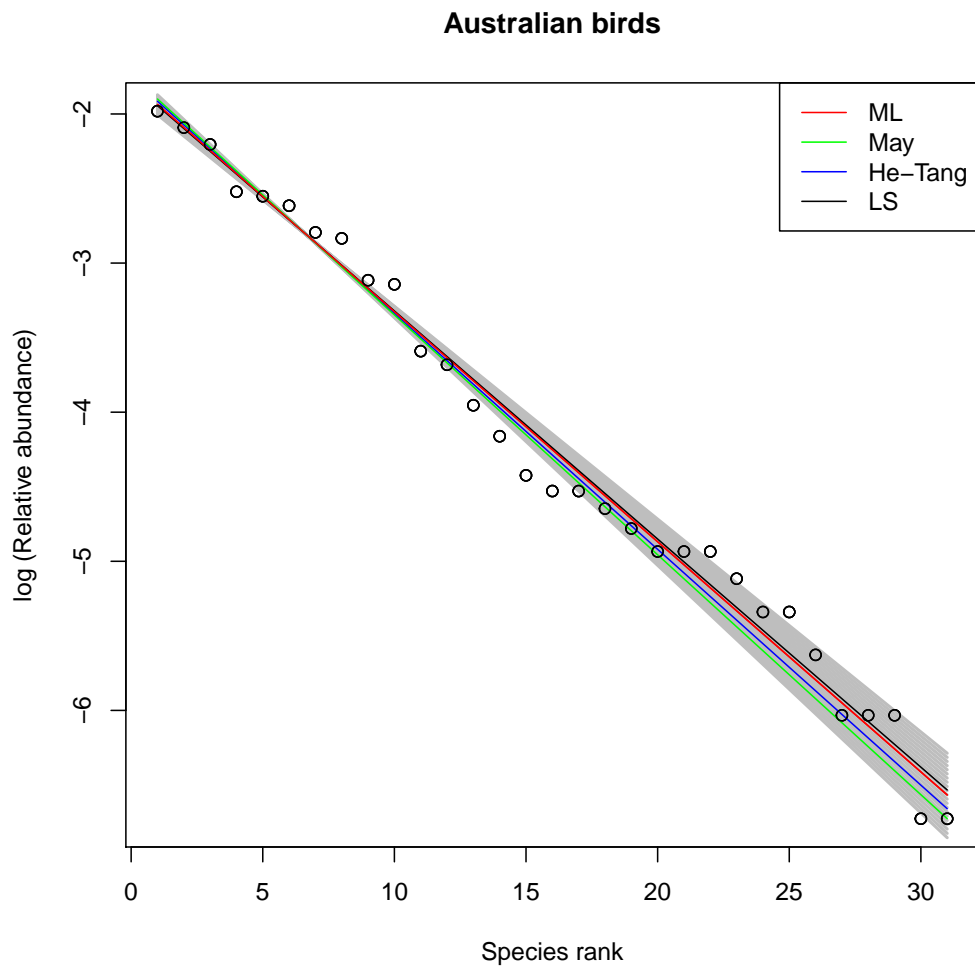


Figure 3: Rank-abundance plot of Australian birds in wet sclerophyll forest. Fitted lines represent geometric models estimated by maximum likelihood (ML), May's equation (May), He-Tang's estimator and least-squares regression (LS).

162 **4.2 Indian dung beetles**

163 Figure 4 shows the rank-abundance plot of the Indian dung beetle data. Note that
164 there is a considerable difference between May's classical estimator and the ML
165 estimate. The ML estimator is 31% larger. Expected relative frequencies (in the
166 log scale) have been calculated and plotted in Figure 4 to show the fit of all es-
167 timators. This shows May's estimator underestimates the frequency of the most
168 abundant beetle, and overestimates the frequencies of almost all other species.
169 The ML estimator fits the abundant species much better and is seen to underesti-
170 mate the rare species. The values of the different estimators are given in Table 3.
171 We note that May's classical estimator, He-Tang's estimator and the regression
172 estimator are all outside the confidence interval of the ML estimator. There is
173 clearly a significant difference between the ML estimator and its alternatives, the
174 ML estimator suggesting a stronger decay.

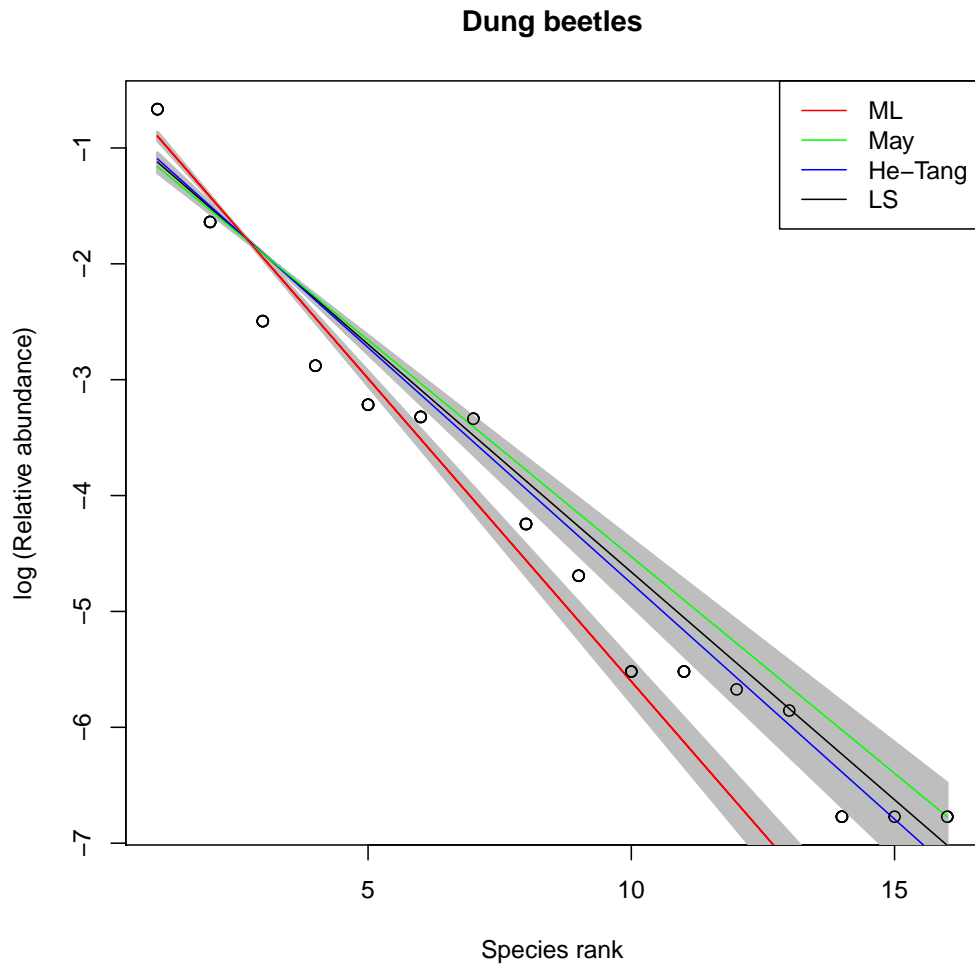


Figure 4: Rank-abundance plot of Indian dung beetles. Lines represent geometric decay according to four different estimators. Grey areas indicate the confidence regions for the ML and LS estimators.

Estimator	\hat{k}	se	95% CI
May	0.312	-	-
HT	0.334	-	-
LS	0.325	-	(0.296, 0.353)
ML	0.407	0.0076	(0.392, 0.422)

Table 3: Estimates of the preemption parameter for the Indian dung beetles according to different methods.

175 **4.3 Preemption t test with Costa Rican dung beetles**

176 Mehrabi et al. (2014) performed a comparative biodiversity study, where the counts
177 of dung beetles, an important indicator taxon, were registered along eight tran-
178 sects under two conditions, micro-habitat standardized placement (treatment) and
179 random placement (control) of baited traps. We use the transect level counts ob-
180 tained by summing over traps sampled under the same condition. It is of interest
181 to compare estimates of diversity parameters under the two conditions. Figure 5
182 shows the rank-abundance plots for the eight transects where the preemption pa-
183 rameter has been estimated for both conditions. Table 4 shows the ML estimates
184 of the preemption parameter, and the results of the preemption t test described in
185 Section 2. Figure 5 shows overlapping confidence intervals for transect pairs C-D,
186 I-J, K-L and M-N. The preemption t test results in Table 4 show non-significant
187 differences and overlapping confidence intervals for the first three of these, and
188 a borderline p-value for transect M-N. All other transect pairs have very small
189 p-values, indicating significant differences in the preemption parameter for the
190 two conditions. For these transects, the ML estimator gives a faster decay for the
191 control transects. This corroborates the finding of Mehrabi et al. (2014) that the
192 micro-habitat standardized transects were more diverse.

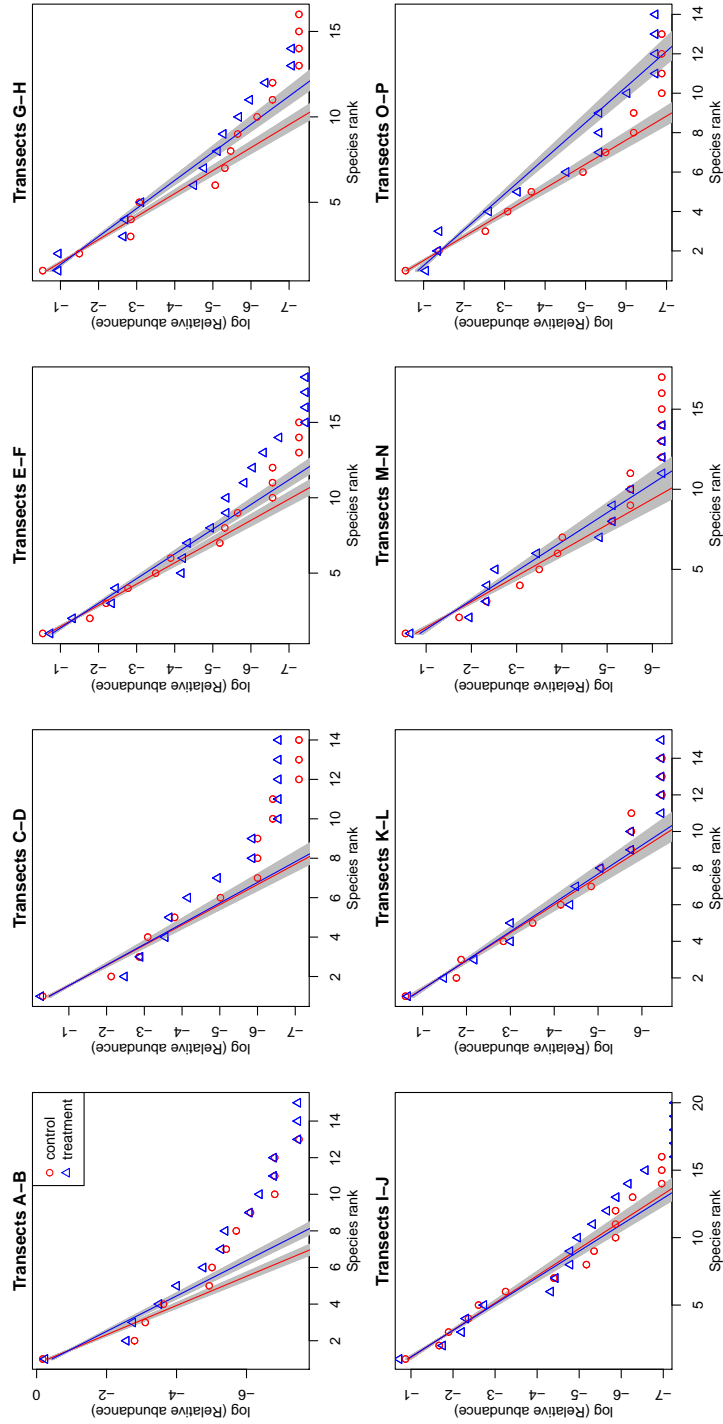


Figure 5: Rank-abundance plots of Costa Rican dung beetles. Lines represent geometric decay for the ML estimators for two transects, one in blue (treatment) and one in red (control). Grey areas indicate the confidence regions for the ML estimators.

Transects	\hat{k}_1	$CI(k_1)$	\hat{k}_2	$CI(k_2)$	T	p -value
A-B	0.715	(0.697 , 0.732)	0.644	(0.626 , 0.662)	5.480	0.000
C-D	0.623	(0.601 , 0.644)	0.615	(0.587 , 0.643)	0.414	0.679
E-F	0.508	(0.490 , 0.527)	0.457	(0.441 , 0.473)	4.113	0.000
G-H	0.525	(0.506 , 0.544)	0.456	(0.437 , 0.475)	5.012	0.000
I-J	0.391	(0.373 , 0.409)	0.400	(0.384 , 0.416)	-0.704	0.481
K-L	0.480	(0.453 , 0.507)	0.471	(0.444 , 0.498)	0.475	0.635
M-N	0.464	(0.434 , 0.494)	0.423	(0.394 , 0.451)	1.979	0.048
O-P	0.559	(0.536 , 0.582)	0.424	(0.402 , 0.446)	8.256	0.000

Table 4: ML estimates (\hat{k}_1, \hat{k}_2) of preemption parameter k for eight pairs of transects under two conditions, T -statistic and p -value of a preemption t -test.

193 **5 Conclusions and discussion**

194 We have developed a maximum likelihood estimator for the niche preemption pa-
195 rameter of the geometric model. In this work, we assume the number of species
196 S to be known, such that multinomial sampling with a fixed number of categories
197 applies. In empirical studies, fixing S maybe reasonable if the community of
198 interest has been exhaustively surveyed, and the number of species is known in
199 advance. The geometric model has been found adequate for species-poor com-
200 munities (Magurran, 2004) such as those in process of colonization (He and Tang,
201 2008). In such circumstances, the number of competing species may indeed very
202 well be known, and fixing S then seems reasonable. Importantly, in such a de-
203 sign, zero abundances are admitted, because not all species are observed, due to
204 the fact that some are rare, or not present in the sample by mere chance. The
205 proposed ML estimator can deal with zeros, as the latter arise naturally under the
206 multinomial distribution. May's classical estimator cannot cope with zeros, as
207 these lead to $k = 0$ or $k = 1$. He and Tang's estimator can neither be used, be-
208 cause it will always produce $k = 1$ if a zero is present. Estimation by regression
209 with log transformed relative abundances neither works for giving $\ln(0) = -\infty$
210 for zero counts. Indeed, to sensibly apply all the classical estimators, zeros must
211 first be discarded, and S reduced correspondingly. For the ML estimator, zeros
212 are unproblematic. The approximate form (Eq. (9)) gives the same estimate with
213 and without zeros, and the exact form (Eq. (8)) typically shows only minor vari-
214 ation due to different S under removal or inclusion of zeros. In future work, the
215 maximum likelihood approach presented here could be extended to the double ge-
216 ometric model from Alroy (2015).

217

218 In comparative biodiversity studies, multiple samples of similar communities are
219 often obtained. In order to sensibly do so, the same set of species is typically de-
220 termined for all samples. It easily occurs that some of the rarer species are absent
221 in some of the sampled sites. In order to apply the classical estimators, the zeros
222 must be discarded, and consequently S starts to vary over the samples. To keep
223 the same S constant, one can subset the analysis to those species that appear in
224 all samples, but this obviously entails a loss of information. The ML estimator
225 is based on the multinomial distribution and admits zeros, neatly avoiding these
226 problems.

227

228 The least-squares regression estimator (He and Tang, 2008; Caruso and Miglior-
229 ini, 2006; Fattorini, 2005) is popular, and intuitively appealing, but it suffers from
230 certain inconsistencies. Importantly, the geometric model has, for given N and
231 S , only one parameter, the preemption parameter k . However, linear regression
232 estimates two parameters, slope β_1 and intercept β_0 . Eq. (5) estimates k from the
233 slope, but that may be considered arbitrary. Because β_0 also depends on k (see
234 Eq. (4)), an alternative estimator for k , which will typically give a different point
235 estimate, can be obtained from the intercept. Drawing a standard least-squares
236 regression line with intercept b_0 and slope b_1 in the rank-abundance plot will often
237 give a line that visually fits the data well, but it amounts to *overfitting* because
238 the model of interest has in fact only one parameter. May's, He-Tang's and the
239 proposed ML estimator are more coherent for estimating a single parameter.

240

241 We also note that the line fitted by May's methods always passes through

242 $(S, \ln(n_{(S)}/N))$, thereby always artificially fitting the most rare species without
243 error. Consequently, May's method capitalizes on the rare species. The prob-
244 abilities of occurrence of the rare species are poorly estimated, because only a
245 few individuals of them have been observed. Describing the geometric decay
246 with an ordinary least squares regression (Eq. (4)) gives the *same weight* to
247 highly abundance species whose proportion is determined with small relative
248 error as to rare species whose proportion is determined with high relative error,
249 and that looks at least questionable. The proposed ML estimator capitalizes on
250 the abundant species and is less affected by the rare ones. The ML estimator
251 therefore focusses on those measurements that have less relative error, which
252 is a desirable property. If one singleton of an additional species is found, the
253 numerator of Eq. (9) increases by 1 and the denominator by $S + 1$, which will in
254 general hardly affect the ML estimate of k , showing clearly its *robustness* to the
255 inclusion or deletion of some rare species.

256

257 There are many ecological studies in which the preemption parameter of the ge-
258 ometric series is estimated and reported, but a quantification of the uncertainty in
259 the estimate is almost never given. The derivation of the ML estimator and its dis-
260 tribution in this article enable, by means of confidence intervals, the expression of
261 the uncertainty in the estimation of the preemption parameter, and the comparison
262 of such estimates by means of the preemption t test.

263 **6 Software**

264 An R package (R Development Core Team, 2004) named `MLpreemption` has
265 been written providing functions for estimation of the preemption parameter by
266 maximum likelihood and other methods. The package also includes the preemp-
267 tion t test and the datasets analysed in this paper, and is available on CRAN and
268 on the author's homepage.

269 **7 Acknowledgements**

270 This work was partially supported by grants RTI2018-095518-B-C22 of the Span-
271 ish Ministry of Science, Innovation and Universities and the European Regional
272 Development Fund, and by grant R01 GM075091 from the United States National
273 Institutes of Health.

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