¹ Maximum likelihood inference of pathogen population size history from

² a phylogeny

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10 ABSTRACT

Inference of effective population size from genomic data can provide unique information about 11 demographic history, and when applied to pathogen genetic data can also provide insights into 12 epidemiological dynamics. Non-parametric models for population dynamics combined with molecular 13 clock models which relate genetic data to time have enabled phylodynamic inference based on large sets 14 of time-stamped genetic sequence data. The theory for non-parametric inference of effective population 15 size is well-developed in the Bayesian setting, but here we develop a frequentist approach based on 16 non-parametric latent process models of population size dynamics. We appeal to statistical principles 17 based on out-of-sample prediction accuracy in order to optimize parameters that control shape and 18 smoothness of the population size over time. We demonstrate the flexibility and speed of this approach 19 in a series of simulation experiments and apply the models to genetic data from several pathogen data 20 sets. 21

22 INTRODUCTION

Past fluctuation in the size of a population are reflected in the genealogy of a sample of individuals 23 from that population. For example, under the coalescent model, two distinct lines of ancestry coalesce 24 (ie find a common ancestor) at a rate that is inversely proportional to the effective population size at 25 any given time (Kingman 1982; Griffiths and Tavare 1994; Donnelly and Tavare 1995). More coalescent 26 events are therefore likely when the population size is small compared to when the population size is 27 large. This causal effect of population size on genealogies can be reversed in an inferential framework 28 to recover past population size dynamics from a given pathogen genealogy. This approach to inference 29 of past demographic changes was first proposed 20 years ago (Pybus et al. 2000, 2001; Strimmer and 30 Pybus 2001) and has been fruitfully applied to many disease systems (Pybus and Rambaut 2009; Ho 31 and Shapiro 2011; Baele et al. 2016). 32

Population size analysis is often performed within the Bayesian BEAST framework (Suchard et al. 2018; 33 Bouckaert et al. 2019) which jointly infers a phylogeny and demographic history from genetic data. Here 34 we focus on an alternative approach in which the dated phylogeny is inferred first, for example using 35 treedater (Volz and Frost 2017), TreeTime (Sagulenko et al. 2018) or BactDating (Didelot et al. 2018), 36 and demography is investigated on the basis of the phylogeny. Although potentially less powerful, this 37 approach has the advantage of scalability to very large sequence data sets and allows more focus on 38 models and assumptions involved in the demographic inference itself as previously noted in studies 39 following the same post-processing strategy (Lan et al. 2015; Karcher et al. 2017; Volz and Didelot 40 2018). However, some of the methodology and results we describe here should be applicable in a joint 41 inferential setting too. 42

The reconstruction of past population size dynamics is usually based on a non-parametric model, since the choice of any parametric function for the past population size would cause restrictions and be hard to justify in many real-life applications (Drummond et al. 2005; Ho and Shapiro 2011). However, even if a non-parametric approach offers a lot more flexibility than a parametric one, it does not fully circumvent the question of which demographic model to use as the basis of inference. For example, the *skygrid* model considers that the log population size is piecewise constant, with values following a Gaussian Markov chain, in which each value is normally distributed around neighbouring values and standard deviation determined by a precision hyperparameter (Gill et al. 2013). This model can be

⁵¹ justified as the discretisation of a continuous *skyride* model in which the log population size is ruled ⁵² by a Brownian motion (Minin et al. 2008). Alternatively, the *skygrowth* model is a similar Gaussian ⁵³ Markov chain on the growth rate of the population size (Volz and Didelot 2018). Both models can be ⁵⁴ conveniently extended to explore the association between population size dynamics and covariate data ⁵⁵ (Gill et al. 2016; Volz and Didelot 2018).

The *skyarid*, *skyarowth* or other similar models can be assumed when performing the inference of 56 the demographic function, and the effect of this model choice has not been formally investigated. 57 Furthermore, these discretised non-parametric models require to select the number of pieces in the 58 demographic function, the location of boundaries between pieces, and the prior expectation for the 59 difference from one piece to another, all of which can have significant effect on the inference results. 60 Here we propose several statistical procedures to automatically select the best values for some of these 61 variables. In particular, the parameter controlling the smoothness of the population size function 62 is usually assumed to have an arbitrary non-informative prior distribution in a Bayesian inferential 63 setting (Minin et al. 2008; Gill et al. 2013), whereas we show here that it can be selected using a 64 frequentist statistical approach based on out-of-sample prediction accuracy. We tested the effect of 65 these procedures on simulated datasets, where the correct demographic function is known and can be 66 used to assess the relative value of inference under various conditions. We also reanalysed real datasets 67 from recent studies on viral and bacterial infectious diseases, and show that the new methods can lead 68 to improved epidemiological insights. 60

70 MATERIALS AND METHODS

71 Non-parametric Models

⁷² Let the demographic function $N_{\rm e}(t)$ be piecewise linear with R pieces of equal lengths h. Let γ_i denote ⁷³ the log of the effective population size in the *i*-th piece. In the *skygrid* model (Gill et al. 2013), the ⁷⁴ values of γ_i follow a Gaussian Markov chain, with the conditional distribution of γ_{i+1} given γ_i equal ⁷⁵ to:

$$\gamma_{i+1} \sim \mathcal{N}(\gamma_i, h/\tau) \tag{1}$$

⁷⁶ By contrast, the *skygrowth* model (Volz and Didelot 2018) is defined using the effective population size ⁷⁷ growth rates ρ_i which are assumed constant in each interval and are equal to:

$$\rho_i = \frac{\exp(\gamma_{i+1}) - \exp(\gamma_i)}{h\exp(\gamma_i)} \tag{2}$$

78 These growth rate values form a Gaussian Markov chain, with:

$$\rho_{i+1} \sim \mathcal{N}(\rho_i, h/\tau) \tag{3}$$

⁷⁹ We also define a new model which we call *skysigma* based on the values σ_i of the second order differences

⁸⁰ of the log of the effective population size:

$$\sigma_{i} = (\gamma_{i+1} - \gamma_{i}) - (\gamma_{i} - \gamma_{i-1}) = \gamma_{i+1} - 2\gamma_{i} + \gamma_{i-1}$$
(4)

81 Once again we consider a Gaussian Markov chain in which:

$$\sigma_{i+1} \sim \mathcal{N}(\sigma_i, h/\tau) \tag{5}$$

Each of the models above defines a demographic function $N_{\rm e}(t)$ from which the likelihood of the genealogy \mathcal{G} can be calculated. Let *n* denote the number of tips in \mathcal{G} , let $s_{1:n}$ denote the dates of

the leaves and $c_{1:(n-1)}$ denote the dates of the internal nodes. Let A(t) denote the number of extant

 $_{ss}$ lineages at time t in \mathcal{G} which is easily computed as the number of leaves dated after t minus the number

so of internal nodes dated after t:

$$A(t) = \sum_{i=1}^{n} \mathbb{1}[s_i > t] - \sum_{i=1}^{n-1} \mathbb{1}[c_i > t]$$
(6)

This quantity is important because in the coalescent model, each pair of lineages coalesces at rate $1/N_{\rm e}(t)$, so that the total coalescent rate at time t is equal to:

$$\lambda(t) = \begin{cases} \frac{A(t)(A(t)-1)}{2N_{\rm e}(t)}, & \text{if } A(t) \ge 2\\ 0, & \text{otherwise.} \end{cases}$$
(7)

The full likelihood of the coalescent process is therefore computed as (Griffiths and Tavare 1994; Donnelly and Tavare 1995):

$$L(\mathcal{G}|N_{\rm e}(t)) = \exp\left(-\int_{-\infty}^{\infty} \mathbb{1}[A(t) \ge 2] \frac{A(t)(A(t)-1)}{2N_{\rm e}(t)} \mathrm{d}t\right) \prod_{i=1}^{n-1} \frac{1}{N_{\rm e}(c_i)}$$
(8)

This computation is straightforward for the models considered here where the demographic function $N_{\rm e}(t)$ is piecewise constant.

⁹³ Selection of the precision parameter

The precision parameter (also called the 'smoothing' parameter) τ controls how much subsequent values of the Markov $N_{\rm e}$ will vary when data is uninformative. The selection of this parameter is therefore shaped by competing aims of maximizing explanatory power while reducing overfitting. In frequentist statistics, a standard approach to selecting smoothing parameters is to minimize out-ofsample prediction error. Here, we pursue a k-fold cross-validation strategy where genealogical data is partitioned into k sets, k-1 of which are used for fitting, and the last one is used for prediction. This

procedure is equivalent to maximizing the following objective function:

$$f(\tau) = \prod_{j=1}^{k} P(\mathcal{G} \setminus X_j | \hat{N}_{\mathbf{e}}(X_j, \tau)),$$
(9)

where $\hat{N}_{e}(X_{j}, \tau)$ is the maximum likelihood estimates of N_{e} on the partial data $X_{j} \subset \mathcal{G}$ and assuming the precision parameter is τ . In this case $X_{j=1:k}$ represents a subset of the sample times and internal node times of the genealogy \mathcal{G} .

This is a standard formulation of the cross-validation method, but the implementation depends on how genealogical data is partitioned. We use the strategy of discretizing the coalescent likelihood (Equation 8) into intervals bordered by the time of nodes (tips s_i or internal nodes c_i of the tree) and/or the R-1times when the piecewise-constant N_e changes value. Given R-1 change points, n tips, and n-1internal nodes of \mathcal{G} , there are R+2n-3 intervals ($\iota_1, \cdots, \iota_{R+2n-3}$). Each cross-validation training set is formed by taking a staggered sequence of intervals and collecting the genealogical data contained in each, so that $X_k = {\iota_j | \text{modulo}(j, k) \neq 0}.$

¹⁰⁴ Selection of the grid resolution

Before any of the non-parametric models described above can be fitted, the number R of pieces in the piecewise demographic function needs to be specified. Setting R too low may lead to an oversimplified output that does not capture all the information on past population changes suggested by the genealogy, whereas setting R too high can lead to overfitting. We therefore propose to use well established statistical methods to select the optimal value of R. First the model is fitted for multiple proposed values of R, and then for each output we compute the Akaike information criterion (AIC), which is equal to:

$$AIC_R = 2R - 2\log(L_R) \tag{10}$$

where L_R is the maximum value of the likelihood when using R pieces. The value of R giving the smallest value of AIC_R is selected. We also implemented the Bayesian information criterion (BIC), which are respectively equal to:

$$BIC_R = R\log(n-1) - 2\log(L_R) \tag{11}$$

¹¹⁵ However, we found that the BIC was often overly conservative in the choice of the resolution as ¹¹⁶ previously noted (Kuha 2004; Weakliem 1999), and therefore we focus here in the use of AIC.

¹¹⁷ Simulation of testing data

In order to test the accuracy of our methodology, we implemented a new simulator of coalescent 118 genealogies given sampling dates and a past demographic function $N_{\rm e}(t)$. When the demographic 119 function is constant, the simulation of coalescent genealogies is equivalent to simulating from a 120 homogeneous Poisson process, in which the waiting times from one event to the next are exponentially 121 distributed. To extend this to the situation where the demographic function is non-constant requires 122 to simulate from an equivalent non-homogeneous Poisson process. The approach we used to achieve this is to consider a homogeneous Poisson process with a population size $N_{\rm m}$ which is lower than any 124 value of $N_{\rm e}(t)$, ie $\forall t, N_{\rm e}(t) \geq N_{\rm m}$. We simulate this process using exponential waiting times, but filter 125 an event happening at time t according to the ratio $N_{\rm m}/N_{\rm e}(t)$. Specifically, we draw $u \sim {\rm Unif}(0,1)$ and 126 if $u < N_{\rm m}/N_{\rm e}(t)$ the event is accepted and otherwise rejected. The resulting filtered Poisson process 127 simulates from the non-homogeneous Poisson process as required (Ross 2014). The disadvantage of 128 this approach over other methods of simulations is that there may be many rejections if $N_{\rm e}(t)$ takes 129 small values so that $N_{\rm m}$ needs to be small too. This is therefore not the most efficient method of 130 simulation. However, efficiency of simulation is not important for our purpose here, and this method 131 has the advantage to avoid the computation of integrals on the $N_{\rm e}(t)$ function which other methods 132 would require. 133

¹³⁴ Implementation

¹³⁵ We implemented the simulation and inference methods described in this paper into a new R package ¹³⁶ entitled *mlesky* which is available at https://github.com/emvolz-phylodynamics/mlesky . If ¹³⁷ multiple CPU cores are available, these resources are exploited within the procedure of selection of ¹³⁸ the smoothing parameter where the computation can be split between the different cross values in the ¹³⁹ cross-validation. Multicore processing is also applied in the procedure of selection of the grid resolution ¹⁴⁰ where computation can be split between different values of the number R.

141 **RESULTS**

¹⁴² Application to simulated dataset with constant population size

A dated phylogeny was simulated with 200 tips sampled at regular intervals between 2000 and 2020, 143 and a constant past population size function $N_{\rm e}(t) = 20$ (Figure 1). To illustrate the importance of 144 the resolution R and precision τ parameters, we inferred the demographic function under the *skyqrid* 145 model (cf Equation 1) for a grid of values with $R \in \{5, 20, 50\}$ and $\tau \in \{1, 10, 20\}$ (Figure 2). The 146 results look quite different depending on the parameters used, and in particular when R is large and τ 147 is small, fluctuations in the population size are incorrectly inferred. When applying the AIC procedure 148 to this dataset, the correct value of R = 1 was inferred for which the parameter τ becomes irrelevant. 149 In these conditions the effective population size was estimated to be 19.65 with confidence interval 150 ranging from 17.10 to 22.57 which includes the correct value of 20 used in the simulation. We repeated 151 the AIC procedure for 100 different phylogenies all which had been simulated under the same constant 152 population size conditions described above. For 65 of these phylogenies the AIC procedure selected 153 R = 1, with the third quartile falling on R = 3 and only one simulation giving R > 10. 154

¹⁵⁵ Application to simulated dataset with sinusoidal population size

Next we simulated a dated phylogeny with the same number and dates of the tips as before, but using 156 a demographic function $N_{\rm e}(t)$ that was sinusoidal with minimum 2 and maximum 22, with period 6.28 157 years. Figure 3 shows both the demographic function used and the resulting simulated phylogeny. We 158 attempted to reconstruct the demographic function based on the phylogeny under the three models 159 skygrid, skygrowth and skysigma described in Equations 1, 3 and 5, respectively. For each model 160 the precision parameter τ was optimised using our new cross-validation procedure and the number of 161 pieces was set to be R = 20 for ease of comparison. The results obtained in these conditions were 162 very similar under the three models (Figure 4). This suggests that when the precision parameter is 163 optimised using the cross-validation method, the choice between these three models becomes relatively 164 unimportant. The choice of using one model rather than another is therefore mostly guided by the 165 presence of covariate data and whether these are expected to correlate with the effective population 166

¹⁶⁷ size directly or some other function of it such as the population growth rates (Gill et al. 2016; Volz
¹⁶⁸ and Didelot 2018).

¹⁶⁹ Application to simulated dataset with bottleneck in population size

We simulated another dated phylogeny with the same and dates of the tips as before, but using a bottleneck function for $N_{\rm e}(t)$ which was equal to 10 at all times except between 2005 and 2010 when it was equal to 1. Figure 5 shows both this bottleneck function and the phylogeny simulated accordingly. We reconstructed the demographic function using the *skygrid* model. The lowest value of the AIC was obtained for R = 14, and the precision parameter was optimised using the cross-validation procedure to $\tau = 0.87$. The inferred demographic function is shown in Figure 5, where the bottleneck between 2005 and 2010 has been accurately detected.

177 Application to HIV dataset

We analyzed 399 HIV-1 sequences from Senegal between 1990 and 2014 (Nascimento et al. 2020). All 178 sequences are subtype CRF02_AG. We used treedater (Volz and Frost 2017) to reconstruct a dated 179 phylogeny (Figure 6). This phylogeny has a common ancestor around 1972 and the number of lineages 180 through time having rapid change in the early 1980s when the HIV epidemic was expanding. We 181 applied the AIC procedure to determine the optimal number of pieces to be used for the demographic 182 function, which was found to be R = 35. The optimal value of the precision parameter was determined 183 using the cross-validation procedure, and found to be $\tau = 4.40$. The demographic function inferred 184 using these values of R and τ is shown in Figure 6. The whole analysis took less than 30 seconds on 185 a standard laptop computer. 186

¹⁸⁷ Application to cholera dataset

We applied our methodology to a previously described collection of 260 genomes from the seventh pandemic of *Vibrio cholerae* (Didelot et al. 2015). A genealogy was estimated in this previous study using an early version of BactDating (Didelot et al. 2018), and it is reproduced in Figure 7. We applied

the AIC procedure to determine that the demographic function would be modelled using R = 16 pieces. 191 The precision parameter was optimised to a value of $\tau = 1.84$ using the cross-validation procedure. 192 The whole analysis took less than 20 seconds on a standard laptop computer. The result is shown in 193 Figure 7. A first peak was detected in the 1960s, followed by a second peak in the 1970s and finally a 194 third peak in the 1990s. This demographic function follows closely on the previously described three 195 "waves" of cholera spreading globally from the Bay of Bengal (Mutreja et al. 2011; Didelot et al. 2015; 196 Weill et al. 2017). However, these three waves had previously been described based on phylogeographic 197 reconstructions of the spread of the pandemic around the world. The fact that we found a similar 198 wave pattern in our analysis which did not include any information about the geographical origin of 199 the genomes provides further support for the validity of this phylodynamic reconstruction. 200

201 DISCUSSION

Non-parametric phylodynamic inference of population size dynamics is usually carried out in a Bayesian 202 framework (Minin et al. 2008; Gill et al. 2013; Volz and Didelot 2018). Here we presented methods 203 for performing such inference in a frequentist setting with a particular view towards model selection 204 and reducing over-fitting. Optimal smoothing can be obtained in a natural way using standard cross-205 validation methods, and the optimal resolution of the discretised demographic function is achieved 206 using the well-established AIC criterion. This approach can be advantageous when prior distributions 207 are difficult to design or results are sensitive to arbitrarily chosen priors. Methods based on likelihood 208 maximization is also quite fast and scalable to data sets much larger than is conventionally studied 209 with Bayesian methods, and the selection of smoothing parameters does not require arbitrarily chosen 210 hyperparameters. Conventional AIC metrics also alleviate the difficulty of model selection. In most of 211 our simulations, we find relatively little difference in our estimates when parameterizing the model in 212 terms of $N_{\rm e}(t)$ (Equation 1), or the growth rate of $N_{\rm e}(t)$ (Equation 3) or its second order variation of 213 $N_{\rm e}(t)$ (Equation 5). 214

Our methodology assumed that a dated phylogeny has been previously reconstructed from the genetic data. It is therefore well suited for the post-processing analysis of the outputs from *treedater* (Volz and Frost 2017) or *TreeTime* (Sagulenko et al. 2018). A key assumption of our method, as with its Bayesian counterparts, is that all samples in the phylogeny come from a single population ruled by a unique demographic function. To ensure that this is indeed the case, complementary methods are emerging that can test for the presence or asymmetry or hidden population structure in dated phylogenies (Dearlove and Frost 2015; Volz et al. 2020).

Past variations in the effective population size of a pathogen population can reveal key insights into past 222 epidemiological dynamics and help make predictions about the future. It is important to note that the 223 effective population size is not generally equal to or even proportional to the number of infections over 224 time (Volz et al. 2009; Dearlove and Wilson 2013). On the other hand, the growth rate of the effective 225 population size (Equation 2) can be used to estimate the basic reproduction number over time R(t)226 which represents the average number of secondary infections caused by an infected individual (Volz 227 et al. 2013; Volz and Didelot 2018). Having good estimates of this quantity is especially important for 228 assessing the effect of infectious disease control measures (Fraser 2007), and phylodynamic approaches 229

230 provide a useful complementary approach to more traditional methods of estimation based on case

²³¹ report data (Cori et al. 2013).

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Figure 1: Simulated dataset using a constant past population size function.



Figure 2: Result on simulated dataset shown in Figure 1 using the skyline model, from top to bottom R = 5, 20, 50 and from left to right $\tau = 1, 10, 20$.



Figure 3: Simulated data using a sinusoidal past population size function.



Figure 4: Result of applying the three different models to the phylogeny shown in Figure 3.



Figure 5: Demographic function (top), phylogeny (middle) and inferred demographic function (bottom) for a simulated dataset under a bottleneck model.



Figure 6: Analysis of the HIV dataset. Top: Dated phylogeny used as the starting point of past population size inference. Bottom: Demographic function reconstructed based on the phylogeny above.



Figure 7: Analysis of the seventh pandemic of *Vibrio cholerae*. Top: Dated phylogeny used as the starting point of past population size inference. Bottom: Demographic function reconstructed based on the phylogeny above.