# On the evolution of neural decisions from uncertain visual input to uncertain actions

Running title: Visuomotor transformation and decision

Alessandro Tomassini<sup>1\*</sup>, Darren Price<sup>1</sup>, Jiaxiang Zhang<sup>2</sup>, James B Rowe<sup>1, 3</sup>

- 1. Medical Research Council Cognition and Brain Sciences Unit, University of Cambridge, CB27EF, UK
- 2. Cardiff University Brain Research Imaging Centre, School of Psychology, University of Cardiff, CF2 2AT, UK
- Department of Clinical Neurosciences, University of Cambridge, CB2 0SZ, UK

\* Corresponding author: alessandro.tomassini@mrc-cbu.cam.ac.uk

#### 1 Abstract

2 Everyday behaviors are governed by decisions, about what we see and which actions 3 to take. Here we present a model of the evolution of decisions from visual perception 4 to voluntary action, in humans. We combine accumulation-to-threshold modelling of 5 visuomotor decisions under different levels of uncertainty, with electro-/magneto-6 encephalographic recording, to trace the sequence of localised decision processes, 7 separately encoded in beta and gamma frequency ranges, and the flow of information 8 through cortical networks. We show that evidence accumulation in motor and prefrontal 9 cortex, to resolve action uncertainty, begins within 100ms from the onset of visual 10 evidence accumulation, before the threshold in sensory regions is reached suggesting a 11 continuous (rather than sequential) processing of information from perception to action. 12 Moreover, the direction of flow of information between sensory, motor and association 13 cortices, is opposite in beta and gamma frequency bands. The frequency, temporal and spatial distributions of the decision processes reveal widespread hierarchical 14 information processing networks through which we resolve trial-by-trial action 15 16 decisions despite environmental uncertainty.

#### 17 Introduction

Human behaviors are the result of many decisions, from early or automatic perceptual inferences about our environment to complex goal-directed choices between alternate courses of action. Three broad lines of research have made separate contributions to understanding such decisions. First, the psychophysical analysis of visuomotor task performance and reaction times, in health <sup>1</sup> or in the presence of focal <sup>2</sup> and degenerative brain lesions <sup>3</sup>.

Second, the functional anatomical analysis of decision making using brain imaging and neurophysiology, including paradigms that manipulate visual uncertainty <sup>4</sup>, action selection <sup>5</sup>, or outcome evaluation <sup>6</sup>. Third, the development of computational models of how decisions can be reached, at the level of neuronal ensembles <sup>7</sup> or groups of individuals <sup>8</sup>.

It remains a challenge however, to bring these separate lines of enquiry together in a unified model of neurophysiologically informed decision process, embedded in a functional anatomical framework, that can together explain the transformation of noisy visual inputs to alternative motor outputs. The anatomical framework has an additional requirement, which is to accommodate the evidence for functional segregation between sensory and motor areas at the same time as allowing the flow of information through hierarchical and distributed brain networks.

Here we develop an integrated account of visuomotor decision-making, as summarised
in Figure 1, working from a novel visuomotor task that adjusts sensory and action
uncertainty during functional brain imaging by combined electro/magnetoencephalography (MEEG).

40 A long tradition in mathematical psychology has argued that decisions and their 41 latencies are controlled by when cumulative evidence in favour of a choice reaches a 42 criterion decision threshold <sup>9</sup>. We identify the accumulation-to-threshold of latent 43 variables representing sensory evidences, based on the transformation of visual signals 44 into evidence about the behaviorally relevant stimulus features (perceptual 45 decisions,<sup>10,11</sup>); and the analogous 'evidence' for motor schema, which have been 46 termed motor intentions (action decisions <sup>12,13</sup>).

Previous studies of visuomotor tasks typically focus on either perceptual decisions (e.g. judgement of motion direction) or on action decisions (e.g. choice of a motor response), whereas in real-world scenarios agents are required to use the outcome of their perceptual deliberations to inform decisions between alternate responses. This distinction can be lost in experimental paradigms where perceptual decisions are rigidly mapped onto motor responses <sup>14,15</sup>, potentially conflating perceptual and action decisions or attributing variance to one or other process <sup>16</sup>.

Rather than arbitrarily divide visual from motor transformations, we investigated their associated decision processes by separately manipulating uncertainty in the identity of visual features (perceptual uncertainty, by variable motion coherence) and range of possible actions (action uncertainty, by variable number of response options). While many studies have used two-alternate forced choice paradigms with differential rewards, we adopted a n-way decision task to study decisions made between equivalent outcomes<sup>17</sup> (**Figure 2**).

61 Several brain regions have been identified that accumulate perceptual evidence<sup>10,11</sup> and 62 motor intentions<sup>12,13</sup>. However, it is also necessary to understand how a network of 63 accumulator regions orchestrates their activity for the critical transformation between 64 perceptual and action decisions.

Specifically, we sought to distinguish (i) a serial process  $^{18}$  where perceptual decisions 65 are complete and their output passed to motor accumulators, from (ii) a continuous flow 66 67 of information <sup>19</sup>, through perceptual to associative and motor regions before completion of perceptual analysis. A serial process would be robust to error, but 68 69 continuous flow would enable faster action decisions. To differentiate these 70 alternatives, we mapped the modelled temporal profile of evidence accumulation to 71 neurophysiological signatures, trial-by-trial. The temporal evolution of predicted 72 evidence was based on behaviorally optimized generative linear ballistic accumulator 73 model of the decision (Figure 3f).

We exploited the temporal resolution of MEEG to measure spatiotemporal variance of
the induced power<sup>20</sup>. We focused on the beta and gamma band power as the candidate
correlates of the evidence for three reasons.

First, the growing evidence for separate functions of gamma and beta in the feedforward and feedback of information respectively in hierarchical brain networks <sup>21,22</sup>. Second, that the accumulation of evidence for perceptual choices correlates with gammafrequency oscillations <sup>23</sup>. Third, that the processes underlying the deliberation between alternate actions have been associated with beta power modulation <sup>24–26</sup>.

The use of MEEG affords a source model of cortical generators <sup>27</sup> and enables the functional segregation of sensory and motor area, as well as areas where sensory-motor transformations occur. Complementary connectivity measures (phase transfer entropy<sup>28</sup>) reveal the flow of information between areas, orchestrating the emergence of decision-evidences across decision networks.

We show that evidence accumulation in motor and prefrontal cortex begins very soon after visual cortex, and before perceptual decisions are concluded. We further demonstrate that the timing of evidence accumulation and the direction of flow of information between widespread sensory, motor and association cortices differ between Beta (13-30Hz) and Gamma (31-90Hz) frequency range. An early sweep of Gamma activity across an occipito-parietal-frontal network precedes the gradual arising of Beta mediated decision signals.

94 These signals emerge progressively in a lateralized caudo-rostral cascade unfolding 95 along the dorsal stream. The cascade is mainly driven by a lateralized and continuous 96 flow of information from posterior visual areas to distant anterior action control 97 regions. Crucially, the strength of the information flow (as measured by phase-transfer entropy) determines the speed of progression throughout all stages of information 98 99 processing from perception through action as reflected by a positive relationship 100 between connectivity and both faster model accumulation-rates and shorter reaction-101 times. This provides an important formal link between behaviour, established models 102 of decision-making, and connectivity measures. Taken together, the results reveal a 103 continuous flow of information transmitted and integrated through a hierarchical 104 network that transforms decision-making from perception to action.

105

#### 107 **Results**

#### 108 Behavior

To functionally segregate computations mediating visual and action decisions, we used a novel decision-making task to separately manipulate uncertainty in the identity of visual features (perceptual uncertainty), and actions (action uncertainty). The task combined elements of the classic motion discrimination task<sup>29</sup> with a response selection task<sup>13</sup>. Noisy visual stimuli indicated the one or more response options, which were executed by pressing a corresponding button (**Figure 2** and **Methods**).

Uncertainty in perceptual and action decisions was manipulated by varying the noise in the option stimuli and manipulating the number of permitted responses in a full factorial design. The noise in the visual stimuli introduces perceptual uncertainty<sup>11,29</sup>. The variable number of permitted response options introduced action uncertainty<sup>13,30</sup>.

Previous work has shown that the uncertainty associated with both the stimulus motion and the number of available choices systematically influences the parameters of models of decision-evidence accumulation <sup>11,13,30</sup>. Therefore, by manipulating motion coherence in the random dots stimuli and the number of offered choices, we sought to isolate the neural signatures of decision-evidence accumulation for perceptual and action decisions, respectively.

Participants performed the task first in a training session where individual motion
thresholds were estimated for both low and high action uncertainty levels (Figure 3a).
Subsequently, participants performed the task with the motion thresholds that
standardized performance, while undergoing MEEG scan.

129 During training, participants where slower and less accurate when motion coherence 130 was lower (Figure 3a). Similarly, during the scan session (Figure **3b** and 131 **Supplementary Figure 1**) responses were slower under high perceptual (low = 0.77s 132  $\pm 0.1$ ; high = 0.88s $\pm 0.1$ ; F(1,17) = 158.17 p < 0.0001; post-hoc p < 0.0001) and action 133 uncertainty (low =  $0.80s \pm 0.13$ ; high =  $0.85s\pm0.1$ ; F(1,17) = 6.28 p = 0.022; post-hoc 134 p = 0.022; 2-by-2 repeated measures ANOVA; Tukey-Kramer correction). In summary, 135 behavior scaled with levels of perceptual and action uncertainties, confirming the 136 efficacy of our manipulations.

137 To verify that participants' choices were substantially independent over trials,

138 Shannon's equitability index was calculated for sequential choice pairs <sup>13</sup>. The

139 Shannon's equitability index for all participants had mean 0.77 (SD  $\pm$  0.016) and did

140 not differ significantly from the index generated by random permutations of trial

141 order (see Supplementary Figure 2) confirming that subjects' choices were not

- 142 biased by previous responses.
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# 144 Uncertainty modulates the rate of evidence accumulation

Summary statistics of behavioral data cannot adequately explain the mechanism by which uncertainty slows decisions. We adopted formal models of decision-making to decompose the behavioral performance into cognitively relevant latent variables. We fitted accumulation-to-threshold models (Linear Ballistic Accumulator, LBA, <sup>31</sup> to each participant's reaction time and accuracy data.

150 The LBA model of decisions is more tractable than drift-diffusion models for n-way 151 decisions while still remaining physiologically informative <sup>32</sup>. In the LBA each 152 decision was represented by an accumulator that integrated decision-evidence up to a 153 boundary. When the accumulated evidence crosses the boundary a decision is 154 **3c**). Instead of adopting a two-stage model, which assumes a committed (Figure 155 discrete serial process between perceptual and action decisions, we opted for a 'unitary' 156 model where both perceptual and action uncertainty concur in determining participant's 157 performance in a given trial. The factorial design of the experiment enabled us to 158 divorce perceptual and action decision processes using connectivity metrics (see 159 below).

160 Uncertainty can slow responses by reducing the speed of information accumulation 161 (accumulation-rate), increasing response caution (decision boundary), stretching the 162 time required by perceptual and motor processes not directly related to the decision 163 process (non-decision time), or by a combination thereof.

164 To differentiate these competing mechanisms, we fitted all possible combinations of 165 free parameters in a set of 15 LBAs. We compared the goodness-of-fit of each model 166 using random-effects Bayesian model comparison <sup>33,34</sup>. The model comparison 167 revealed that changes in the accumulation-rate alone (model number 2; Figure 3d top 168 panel) accounted parsimoniously for the effects of uncertainty on behavior. The 169 goodness-of-fit of the winning model was further confirmed by posterior predictive 170 checks (Figure 3d bottom panel), performed by simulating data under the winning 171 model and then comparing these to the observed data.

172 In the winning model (henceforth, the LBA model), high uncertainty is associated with 173 comparatively slow accumulation rates. This relationship between uncertainty and 174 accumulation rate held for both perception (z = 3.723, p = 0.00019; Wilkoxon sign rank 175 test) and action (z = 3.723, p = 0.00019; Wilkoxon sign rank test) uncertainty, as well 176 as for each subject (**Figure 3e**), in accord with previous studies <sup>11,30</sup>.

177 Non-decision time ( $t_0$ ), encompassing sensory delays and motor execution, was 178 estimated to be 370ms on average (see **Supplementary table 1**), which is within the 179 plausible range of non-decision times for humans <sup>35,36</sup>.

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# 181 Localization of decision-evidence accumulation

182 To localize neural signatures of decision-evidence represented across the brain, we 183 derived temporally resolved estimates of neuronal population activity from the winning 184 model, which we fitted to a combined MEG and EEG signal, inverted to source space 185 using the L2-Minimum Norm<sup>27</sup>.

We reduced the dimensionality of the MEEG data by parcellating the cortical surface into a set of 96 regions of interest (ROIs) defined using the Harvard-Oxford cortical atlas (FSL, FMRIB, Oxford) and by representing the dynamic of each ROI with a single time-course, obtained using principal component analysis<sup>37</sup>. Dimensionality reduction allows for improved computational efficiency. Further, it reduces multiple comparisons issues and increases statistical power, while retaining the maximum amount of information<sup>38</sup>.

193The temporal evolution of the spectral power (power envelope) in each region served194as the signal for our analysis in beta (13-30Hz) and gamma (31-90Hz) bands. The time

195 onset of evidence accumulation across ROIs was identified by optimizing the split of

the non-decision time before and after the accumulation period using Spearman correlation to the MEEG power envelope (Figure 3f, see Supplementary Figure 3 for the statistical map). This allows one to depict in space and time the emergence of decision-evidence accumulation.

200 Traditionally, evidence accumulation is associated with increased activity (e.g. firing 201 rates) during decisions. However, recent studies indicate that both increasing and non-202 increasing activity can mediate evidence accumulation<sup>39–41</sup>. In agreement with this idea, 203 we found significant (negative) correlations between the LBA model predictions and 204 the MEEG oscillations in beta and gamma bands<sup>20</sup> (Figure 4). Specifically, for both 205 beta and gamma, neural activity after coherence onset desynchronized in a graded 206 fashion and peaked approximately before response suggesting a form of threshold mechanism (Figure 4a)<sup>42-44</sup>. 207

In the beta band, desynchronization was strongly modulated by uncertainty in good agreement with our predictions. As the decision unfolds, the accumulated decisionevidence will ramp quickly with low perceptual uncertainty, and slowly with high perceptual uncertainty. Accordingly, desynchronization of beta power-envelopes averaged across trials and ROIs was larger (p < 0.0001, cluster corrected random permutations) for low than high perceptual uncertainty<sup>22,42</sup>.

When a response is chosen between multiple options, the race underlying the selection of each alternative is characterized by an overall larger amount of decision-evidence summed across all he racing accumulators by the time of  $response^{13,30}$ . Accordingly, desynchronization of beta power-envelopes averaged across trials and ROIs was larger for high than low action uncertainty (p < 0.0001, cluster corrected random permutations). Gamma power-envelopes, showed a similar trend, but the effects were statistically insignificant.

To locate activity related to decision-evidence accumulation, the time course of powerenvelopes was correlated (Spearman) to time-varying model predictions in a trial-totrial fashion. This allows one to take advantage of inter-trial variability. Statistical significance of the resulting z-transformed correlation values was assessed for each ROI by comparisons against a null distribution created from correlating the model predictions with single trial power-envelopes scrambled by phase (10<sup>4</sup> permutations).

This analysis revealed a brain-wide network displaying decision-related dynamics expressed in the beta range (Fig3b, mean across significant ROIs: sign-test  $z = -3.15 \pm$ 0.48, p = 0.00065 ± 0.0016, FDR corrected). These observations agree with previous human EEG work suggesting that evidence accumulation might correlate with widespread low-frequency desynchronization<sup>45</sup>.

In the gamma band we observed a more localized mosaic of ROIs including contralateral motion sensitive areas (inferior lateral occipital region), bilateral extrastriate areas and bilateral frontal motor regions (comprising premotor areas and supplementary motor area; mean across significant ROIs: sign-test  $z = -2.27 \pm 0.27$ ,  $p = 0.0058 \pm 0.003$ , FDR corrected).

In addition, we compared the z-transformed correlation values for each of the four levels of our manipulations in isolation and confirmed that the quality of fit and the results did not vary across trials types (p>0.05, FDR corrected).

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# 242 A continuous flow of information

243 We traced the spectrally resolved temporal evolution of decisions through the visuo-

244 motor hierarchy, finding that decision-evidence accumulation emerges with distinct

spatio-temporal profiles between beta and gamma (Figure 4b).

An early wave of accumulation begins at ~120ms from coherence onset within the

sparse network oscillating at gamma frequency. It is followed by a second wave

248 mediated by Beta at ~160ms from coherence onset (Figure 4c; Conjunction of

significant ROIs in beta and gamma, median latency across participants, z = 5.53,

250 p<0.0001, Wilkoxon rank test). No difference in latencies was found between

251 hemispheres across frequency bands.

252 The latency maps (Figure 4b) show an accumulation gradient towards the precentral

253 gyrus. We fitted a piecewise regression model with a free internal knot to the mean

latencies of ROIs located along the dorsal path (Figure 4d), a critical system for

255 visuomotor decisions $^{26,46}$ .

In keeping with our observations the model (**Figure 4e** left top-bottom panels) identified the precentral gyrus (comprising primary motor cortex and part of the premotor cortex) as the point of convergence of two linear functions ( $R^2 = 0.734$ , p < 0.0001) and outperformed a single regression model (piecewise  $R^2_{adj} = 0.681$ ; linear  $R^2_{adj} = 0.649$ ; adjusted  $R^2$  penalizes extra free parameters in favor of simple models).

Interestingly, in the gamma band (**Figure 4d** bottom left panel) we found a mirrorsymmetric trend with increasing accumulation latencies while proceeding from the precentral gyrus to more posterior and anterior regions ( $R^2 = 0.245$ , p = 0.042). Thus, accumulation starts with gamma at ~120ms from coherence onset in the precentral gyrus and at ~160ms in the occipital and frontal poles.

The onset of the accumulation in beta overlaps with gamma in the occipital pole at ~160ms from coherence onset <sup>47</sup>. The interval from earliest onset of accumulation to last onset, is only ~100ms and the onset in precentral gyrus is on average ~570ms before a motor response <sup>44</sup>. The delay from motion onset to the beginning of the accumulation on the occipital pole (~160ms), and the delay from action decision to movement initiation in precentral gyrus (~100ms) are close to the sensory (~200ms) and motor (~80ms) delays measured from neural recordings on macaque <sup>11,48</sup>.

These patterns, albeit with lower spatial resolution, were also found at the sensor level (**Supplementary Figure 4**). As a note of caution for the piecewise regression, the fit of the LBA model for some of the ROIs within the dorsal path was not significant in the gamma band, reducing the accuracy of their latency estimates.

An important observation is that the latest ROIs in the gradient for both beta and gamma starts accumulating decision-evidence before the earliest ROI (e.g. the occipital lobe for beta) has reached its decision boundary (**Figure 4e** right top-bottom panels). This suggests that decisions are made on the basis of a continuous flow of information, rather than a serial sequence of discrete decisions.

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#### 285 From perception to action

The above analyses identified a flow of information across a widespread visuomotor network. To functionally segregate accumulators sub-serving perceptual and action decisions, and to reveal the influx and efflux of information across them we measured the phase-transfer entropy, a data-driven measure of information flow that is robust to signal leakage<sup>28</sup>.

291 The analyses focused on regions whose activity significantly fitted the LBA model's 292 prediction. We first identified ROIs that preferentially accumulated evidence for 293 perception or action decisions. We reasoned that in a continuous flow of information, 294 the amount of information transferred between perceptual and action accumulators is 295 expected to co-vary with the rate of the accumulating process. Since the estimated 296 accumulation-rates scale with uncertainty, the amount of information sent by a given 297 region should also scale with uncertainty. This relationship enables one to identify 298 regions where the amount of information varies systematically with the levels of either 299 perceptual or action uncertainty.

**Figure 5a** shows, for the beta band, the regions modulated by action uncertainty (Action decision regions,  $p_{corrected} < 0.0005$  in all ROIs) and perceptual uncertainty (Perceptual decision regions,  $p_{corrected} < 0.0005$  in all ROIs). Action decision regions include ipsilateral cingulate and paracingulate cortex <sup>49</sup>, contralateral frontopolar cortex, ventromedial cortex, insula, supplementary motor cortex, inferior parietal lobule and medial parietal cortex<sup>13,50</sup>. Of notice, bilateral precentral gyri were identified as action decision regions which replicates previous findings<sup>13,51</sup>.

307 Perceptual decision regions in the contralateral hemisphere include posterior areas 308 typically associated with decisions about motion direction. These include lateral 309 occipital cortex (including motion area MT-complex), superior temporal cortex 310 (comprising the superior temporal sulcus) and the superior parietal lobule comprising the superior intraparietal sulcus<sup>52</sup> along with the dorsomedial frontal cortex<sup>4,53</sup>. 311 Interestingly, two areas along the dorsal path on the left hemisphere were sensitive to 312 313 both perceptual and action uncertainty manipulations (superior frontal gyrus, middle 314 frontal gyrus, lateral occipital cortex superior division (comprising V2 and V3; 315  $p_{corrected} < 0.0005$  in all ROIs).

In the gamma band, we observed bilateral involvement of the superior frontal gyrus<sup>54</sup> and inferior frontal gyrus pars triangularis<sup>5</sup>, along with contralateral frontal medial cortex (Rowe et al, 2010) and ipsilateral paracingulate gyrus in action decisions ( $p_{corrected} < 0.005$  in all ROIs). Perceptual decision areas ( $p_{corrected} < 0.0005$  in all ROIs) included bilateral superior temporal areas (comprising the superior temporal sulcus; Pesaran and Freedman, 2016), cuneal cortex, and subcallosal cortex which has been linked to early encoding of confidence for perceptual decisions<sup>55</sup>.

- The dominant direction of information transfer between ROIs was estimated using the directed phase-transfer entropy (Hillebrand et al, 2016). The average direction of information flow for each ROI was computed resulting in a single estimate of preferred direction of information flow (either inflow or outflow). Based on these estimates, we calculated a posterior-anterior index (Hillebrand et al., 2016; PAx) to quantify the direction of flow between caudal and rostral ROIs.
- Figure 5b show the smooth global pattern of preferential information flow in the beta range with caudal ROIs preferentially sending information to anterior regions. This pattern is similar to that reported by Hillebrand et al. 2016 in human resting state, except that our results show a task-related lateralization, with the contralateral PAx almost twice the size of the ipsilateral one (left: p = 0.0002, PAx = 0.47; right: p = 0.0051; PAx = 0.27).

It can be seen from **Figure 5b-c** that, for beta, the strongest information flow was from the left lateral occipital cortex to the left middle frontal gyrus and the frontopolar cortex. This accords with previous reports of beta-synchronization between primate MT and frontal regions during motion discrimination<sup>56</sup>. No significant effect was seen for the gamma range in either hemisphere which might reflect the shorter range of gamma interactions<sup>57</sup>.

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#### 345 Integration of behavioral, computational and physiological evidence

To highlight the behavioral relevance of the integrated account of visuomotor decisionmaking, we explored the relationships between connectivity, accumulator model parameters and behavior. To account for multiple-comparisons, we used Holm-Bonferroni correction over eight tests.

350 In the beta range, the caudo-rostral gradient of evidence-accumulation is matched by a 351 gradual transition from perception to action decisions, as shown by a positive 352 correlation between regional specificity to the type of uncertainty and the estimated accumulation latencies (Figure 6a top left panel, r = 0.27,  $p_{corrected} = 0.044$ ). Moreover, 353 354 the information flow is aligned with the caudo-rostral gradient of accumulation since 355 the flow proceeds from perceptual-decision regions to action-decision regions (Figure 356 6a bottom left panel, correlation between regional specificity and direction of 357 information flow: r = -0.37,  $p_{corrected} = 0.0016$ ).

In contrast, for the gamma band we found there was neither significant relationship between region specificity and accumulation latency (**Figure 6a** top right panel, r = 0.19,  $p_{corrected} = 0.759$ ) nor significant evidence of flow of information from perception to action decision regions (**Figure 6a** bottom right panel, r = -0.37,  $p_{corrected}$ = 0.068).

Finally, we hypothesized that in a continuous flow of information the amount of information transferred between perceptual and action accumulators co-varies with the rate of accumulation. Faster progression from perception through action should be correlated with phase transfer entropy and model accumulation rate, but negatively with reaction-times.

This was the case in the beta range where strong flow was associated with short reaction times (**Figure 6b** top left panel, repeated-measures correlation:  $r_{rm}$ = -0.378,  $p_{corrected} = 0.03$ , CI [-0.588, -0.12]) and accumulation rates (**Figure 6b** bottom left panel,  $r_{rm}$ = 0.356,  $p_{corrected} = 0.045$ , CI [0.096, 0.572]). No significant correlation was observed in gamma (**Figure 6b** top-bottom right, reaction times vs information flow:  $r_{rm}$ = -0.079  $p_{corrected} = 0.564$ ; accumulation-rate vs information flow:  $r_{rm} = 0.113$ ,  $p_{corrected} = 0.816$ ).

#### 375

# 376 Conclusions

There are two principal results from this study that illuminate the interaction between neural systems for perception and action. The first is that decisions in regions sensitive to motor precision do not wait until sensory decisions are completed. Instead, the accumulation of evidence in motor decisions begin within 100ms soon after the initiation of evidence accumulation in the first sensory regions. This indicates a continuous flow or cascade of information and its gradual transformation from sensory evidence to motor 'intention'<sup>58</sup>.

384 The second is that the correlates of evidence-accumulation in the beta and gamma 385 frequency ranges have distinct spatiotemporal profiles, and opposite dominant 386 directions of flow. This spectral directionality is predicted by hierarchical cortical networks for prediction and inference in visuomotor control <sup>22,59–61</sup>. In the beta band, 387 there is not only a spatial gradient in the timing of accumulation-to-threshold between 388 389 occipital and pre-central cortex, but also a qualitative change in the accumulated 390 signals: from sensitivity to visual uncertainty to sensitivity to response uncertainty. 391 Moreover, the more sensitive a region is to action uncertainty (vs. perceptual 392 uncertainty), the later its onset of beta accumulation, and the greater its bias to inflow 393 (vs. outflow) as measured by phase transfer entropy (Figure 6). These effects were not 394 confined to classical visual and motor regions, or even to the 'dorsal stream', but were 395 identified throughout much of the cortex.

396 We set out to integrate the analysis of information flow, with decision-making 397 implemented by the accumulation of evidence, and their joint influence on trial-to-trial 398 variation in behavior (see Figure 1). Independent manipulation of perceptual and 399 action uncertainty was coupled with the decomposition of performance into latent 400 variables in a parsimonious linear ballistic accumulator model <sup>31</sup>, which accurately 401 generated the response distributions in each task condition including the expected effects of task variance on response latencies <sup>11,30</sup>. The model predictions of within-trial 402 403 accumulation were correlated with change in beta and gamma power after the onset of 404 stimulus coherence. Beta desynchronization has been shown to scale with uncertainty <sup>51</sup>, but here we show its interaction with the temporal evolution of decision making over 405

406 sub-second intervals. The observed desynchronization displays two signatures of the

- 407 accumulation-to-threshold class of models: accumulation of decision-evidence over
- 408 time and the consistent bound reached shortly before each movement 10,42-44.

Beta and gamma desynchronization have previously been correlated with behavioural performance. For example, in direct recording from non-human primates during working memory<sup>62</sup> and sensory discrimination<sup>25</sup>, the beta band desynchronization was greater for accurate trials compared with inaccurate trials. Such beta power encoding of decision outcomes is supramodal in many cortical areas<sup>63</sup>. The change in beta power followed the change in gamma power as in the current study: we found an early wave of gamma followed by a second wave of beta.

416 Although gamma and beta rhythms have been observed to occur together or in close 417 succession<sup>64,65</sup>, the temporal relationship is functionally relevant. For hierarchical cortical networks, message passing between regions is a function of the laminar 418 asymmetry of afferent vs. efferent connections<sup>59</sup>, and the properties of columnar 419 420 circuitry which preferentially generates gamma rhythms superficially, and lower frequencies from deep layers<sup>66,67</sup>. This promotes predictive feedback connectivity in 421 422 beta and lower frequencies, and preferential feedforward 'error' signalling in 423 gamma<sup>22,61</sup>. The beta band's lower frequency makes it inherently more suitable for 424 coordination of information processing over longer conduction delays than gamma<sup>46</sup>.

As seen in **Figure 4**, where changes in spectral power were predicted by the LBA model, the latency to accumulation was confirmed as shorter for gamma than beta. Indeed, the spatial distribution of beta latencies in the dominant hemisphere (**Figure 4e**) also shows a gradient from occipital, to parietal and prefrontal, and lastly motor cortex. The motor cortex is also a region of strong net influx of beta (**Figure 5b**), even more than premotor cortex, consistent with the active inference model of motor control<sup>22,61</sup>.

The spatial gradient of gamma latencies is reversed, with earliest changes observed in precentral cortex, before occipital cortex, and later gamma latencies in time with beta responses in occipital cortex. This may be because of the difference between predicting when a response may be required and what that response should be<sup>68</sup>. The sensory stimulus change (visual coherence) in our task is not the result of the participant's own

437 response, but is predictable a second after the onset of the non-coherent display. The 438 participant can predict when an action is required, but not which actions are permitted 439 or specified. An increase in localized and predominantly short-range interactions in 440 gamma range may therefore be a permissive of information required for the beta-441 mediated decision between action alternatives<sup>69</sup>.

442 Despite the similarity of onset of beta and gamma accumulation in occipital cortex, the 443 connectivity analyses indicated distinct channels routing information at longer and 444 shorter spatial scales, respectively. The pattern of net efflux *vs.* influx of beta (**Figure** 445 **5b**) shows a clear division between frontal cortex and posterior lobes. In other words, 446 there was a cascade of overlapping accumulators and information flow along a rostro-447 caudal axis from perceptual to motor regions for beta, at least in the hemisphere 448 contralateral to the response hand.

449 Lateralized beta activity during a decision-making task reflects not just movement 450 preparation, but has also been related to a dynamic decision process with updating of a motor plan as a decision evolves 42-44,51. The beta power lateralization in motor areas 451 was correlated with the state of decision-evidence. Crucially, these earlier MEG and 452 453 EEG studies used a fixed-mapping between decisions outcomes and categorical 454 behavioural responses, without choice or independence of perception and action 455 decisions. When this fixed mapping between perceptual decisions outcome and motor 456 responses is removed, sensorimotor beta lateralization disappears<sup>15</sup>. Our findings 457 complement this work by directly revealing a lateralized progression of evidence 458 accumulation from posterior perceptual regions to anterior motor areas.

459 Moreover, previous pioneering work on visuomotor decisions have focused on 460 processes occurring at the final choice stage, leaving unresolved the question of 461 whether evidence accumulation is coordinated throughout the whole cortex or just in 462 specific regions. Our findings rest on a generalized model in which accumulation-to-463 threshold provides a canonical mechanism evolving throughout all layers of a 464 visuomotor transformation (Figure 3a) and suggest that evidence accumulation is not 465 a limited (perceptual) process with a single cortical focus, but distributed<sup>70,71</sup> and applicable to non-sensory evidence or intentions. This multi-focal property of evidence 466 accumulation resonates with results from animal optogenetic<sup>70</sup> and pharmacological<sup>71</sup> 467

studies showing that inactivation of local cortical areas carrying decision-relatedactivity did not affect decision-making performance.

470 Taken together, our observations support the hypothesis that the beta band response 471 links sensory evidence to motor plans, throughout a widespread network<sup>72</sup>. We 472 propose that an early neural signalling regarding the need for a response is followed 473 by a second phase that integrates a continuous flow of information to make a decision 474 between them<sup>73</sup>. In this second phase, decisions unfold on the basis of a continuous 475 flow of information (Figure 4d), rather than sequential completion of intermediate 476 decisions at the population level. However, this hypothesis refers to the population 477 level, and we cannot exclude the possibility that within each region, a subsection of 478 neurons completes the relevant decision and forwards this outcome to the next level in 479 the hierarchy, while others in that region continue to accumulate.

480 The fluctuations in the strength of information flow caused by changes in uncertainty are behaviourally relevant, in their positive correlation with accumulation-rate and 481 482 negative correlation with reaction times. This establishes an important formal link 483 between behaviour, models of decision-making, and physiological connectivity. Fast 484 accumulating-rates of the linear ballistic accumulator model are associated with a 485 more effective information flow throughout the visuo-motor processing hierarchy, 486 resulting in faster decisions and responses. This relationship could be exploited to 487 investigate clinical conditions in which the ability to use sensory inputs to guide 488 actions is impaired.

489 In summary, our analytical approach explains visuomotor decisions through the 490 combination of computational modelling of behaviour to derive latent decision 491 variables that are identified by their neurophysiological signatures in distributed 492 cortical networks. Variations of beta and gamma power reflect the temporal and 493 spatial dynamics of the accumulation and transfer of decision-evidence, with a 494 continuous flow of information between regions rather than sequential discrete 495 decisions. During this flow, there is a gradual transition from the resolution of sensory 496 uncertainty to resolution of response uncertainty enabling goal-directed actions in the 497 face of sensory uncertainty.

#### 498 Methods:

### 499 Participants

Twenty healthy volunteers (9 females, 11 males, age range 18-39 years) took part in this study, after providing informed consent. Inclusion criteria included age 18-40 years, right-handed, and screening for neurological or psychiatric illness. Two subjects failed to reach the requisite performance criterion during training and were excluded, leaving 18 subjects in all subsequent behavioral and neural analyses. Experimental protocols conformed to the guidelines of the Declarations of Helsinki and were approved by the local research ethics committee.

507

#### 508 Stimuli

509 Stimuli were presented using Matlab and the Psychotoolbox routines in a sound-proof 510 and dimly lit room. For the psychophysical training stimuli were displayed on a CRT 511 monitor at 60cm, and for the scan session stimuli were projected on a screen through a 512 projector at 130cm (both with a 60Hz refresh rate) with equivalent pixel resolution of 513 0.03°.

514 Stimuli were four random dot kinematograms <sup>29</sup> displayed within four circular apertures 515 (4° diameter) positioned along a notional semi-circular arc (3.4° eccentricity) on a black 516 background (100% contrast). 200 dots were displayed during each frame and spatially 517 displaced in the next frame to introduce apparent downward motion (6°/sec velocity). 518 To manipulate motion strength (i.e. motion coherence) between trials, on each frame 519 only a certain proportion of dots moved downward whilst the rest of the dots where 520 randomly reallocated. Motion coherence level was kept constant throughout the trial.

Since abrupt stimulus onset and offset could elicit large sensory-evoked potentials
which might mask decision processes, the 1.5 seconds long coherent motion interval
was preceded and followed by intervals of zero-coherence levels lasting 1sec and
0.5sec, respectively.

525

# 526 Task and procedures

Participants performed a finger-tapping task adapted from previous studies <sup>13,30</sup>. Their 527 528 goal was to detect the onset of coherent motion and to press the button corresponding to one of the downward moving stimuli (coherent stimuli). The number of coherent 529 530 stimuli defined two trial types: Low action uncertainty trials, where a single coherent 531 stimulus commanded which button to press; and high action uncertainty trials, where 532 three coherent stimuli required the participants to make a simple choice and press any 533 one of the three corresponding buttons (a "fresh choice, regardless of what you have done in previous trials"<sup>30</sup>). Equal emphasis was placed on the speed and accuracy of 534 535 the responses. Participants were instructed to fixate on a central red mark throughout 536 the trial. Eye-tracking data collected during the first six scanning sessions confirmed 537 participants were able to successfully perform the task while maintaining fixation (see 538 supplementary results). Each trial started with the presentation of the fixation mark 539 and stimuli onset ensued after a variable interval comprised between 0.5sec and 1sec. 540 The imaging session was preceded by one training psychophysical session and one test 541 session scheduled on separate days; the scanning session was conducted a maximum of 542 four days after the psychophysical training, depending on the availability of the 543 participants.

544

#### 545 *Psychometric calibration*

546 Participants were firstly familiarized with the finger-tapping task during a short practice 547 session where 100% coherent stimuli were adopted. The familiarization phase was 548 completed when participants reached 90% accuracy across all trial types. In the 549 following psychophysical training, motion coherence was randomly varied between trials to estimate individual motion thresholds. Eight logarithmically spaced motion 550 551 coherence levels (0 0.5 0.10....0.9) were used (32 trials per level) following extensive 552 piloting to ensure coverage of a wide range of individual motion sensitivity. Each 553 training session comprised 16 blocks of 32 trials. Feedback was provided for 554 correctness of responses as well as for too early or too late responses (100ms and 2.5s 555 from motion coherence onset, respectively).

556 To ensure that participants perceived all the available options (i.e. coherent stimuli) 557 before committing to a decision, occasionally (p = 0.2) after a correct choice they had 558 to perform a secondary match-to-sample task: a set of grey discs replaced the stimuli 559 and participants had to report whether their locations matched the location of the 560 previously displayed coherent stimuli. They had to press any button to report a match 561 and withhold any response otherwise. A trial was considered as correct only when both 562 choice and matching were correct. Trials with un-matching responses were discarded 563 and repeated within the session.

To tailor the sensory evidence to the participants' individual motion sensitivity across number of options, the discrimination accuracy of each trial type in each training session was fitted using a maximum likelihood method, with a Log-Quick function defined as

568 
$$F_{log} = 1 - 2^{-10^{\beta(x-\alpha)}},$$
 (1)

569 where  $\alpha$  is the threshold,  $\beta$  is the slope and x is the coherence level. To obtain the

570 proportion correct for each trial type, the Log-Quick function was scaled by,

571 
$$P = \gamma + (1 - \gamma - \lambda)F_{log}, \qquad (2)$$

572 where  $\gamma$  is the guess rate and  $\lambda$  is the lapse rate controlling the lower and upper

asymptote of the psychometric function, respectively.

574 Individual low and high perceptual uncertainty levels for each trial type were estimated 575 as the 75<sup>th</sup> and 90<sup>th</sup> percentile of the psychometric functions from the last session. The 576 reason for adopting these thresholds was twofold: firstly, participants need to perceive 577 all the available options before committing to a decision. Secondly, supra-threshold 578 trials are best suited for investigating neural correlates of evidence accumulation<sup>74</sup>.

579

## 580 *Test and scan sessions*

581 Test and scan sessions were scheduled on separate days; the scanning session was 582 conducted a maximum of four days after the psychophysical training, depending on the 583 availability of the participants. The test session was to ensure that the participants were 584 able to perform well under the individually adjusted motion thresholds. In the test and 585 scan sessions, coherence levels were fixed to the individual thresholds corresponding 586 to high and low levels of perceptual uncertainty, the match-to-sample task was 587 removed, and no feedback was provided except for too late or too long responses. 588 Levels of perceptual and action uncertainty where randomly interspersed across trials. 589 Each session consisted of 10 blocks (total 720 trials per participant) separated by a short rest. Trials on which responses were made before 0.1-sec or after 2-sec (on average
1.3% of total trials) were excluded from subsequent analyses.

592

## 593 MEG and EEG data acquisition and processing

An Elekta Neuromag Vectorview System simultaneously acquired magnetic fields from 102 magnetometers and 204 paired planar gradiometers, and electrical potential from 70 Ag-AgCl scalp electrodes in an Easycap extended 10-10% system. Additional electrodes provided a nasal reference, a forehead ground, paired horizontal and vertical electro-oculography (EOG), electrocardiography (ECG) and neck electromyography (EMG). All data were recorded and digitized continuously at a sample rate of 1kHz and high-pass filtered above 0.01 Hz.

601 Before scanning, head shape, the locations of five evenly distributed head position 602 indicator coils, EEG electrodes location, and the position of three anatomical fiducial 603 points (nasion and left and right pre-auricular) were recorded using a 3D digitizer 604 (Fastrak Polhemus Inc., Colchester, VA). The initial impedence of all EEG electrodes 605 was optimized to below 10 k $\Omega$ , and if this could not be achieved in a particular channel, 606 or if it appeared noisy to visual inspection, it was excluded from further analysis. The 607 3D position of the head position indicators relative to the MEG sensors was monitored 608 throughout the scan. These data were used by Neuromag Maxfilter 2.2 software, to 609 perform environmental noise suppression, motion compensation, and Signal Source 610 Separation.

611 Subsequent analyses were performed using in-house Matlab (Mathworks) code,
612 SPM12 (<u>http://www.fil.ion.ucl.ac.uk/spm</u>) and EEGLab (Swartz Center for

613 Computational Neuroscience, University of California San Diego). Separate 614 independent component analysis was computed for the three sensor types and 615 artifactual components were rejected. For EEG data, components temporally and 616 spatially correlated to eye movements, blinks and cardiac activity were automatically 617 identified with EEGLab's toolbox ADJUST. For MEG data, components were 618 automatically identified that were both significantly temporally correlated with 619 electrooculography and electrocardiography data, and spatially correlated with 620 separately acquired topographies for ocular and cardiac artifacts. Artifactual 621 components were finally projected out of the dataset with a translation matrix.

The continuous artefact-corrected data were low-pass filtered (cut-off = 100Hz,
Butterworth, fourth order), notch filtered between 48 and 52Hz to remove main power
supply artifacts, down-sampled to 250Hz, and epoched from -1500 to 2500ms relative
to motion coherence onset. EEG data were referenced to the average over electrodes.

626

#### 627 *MEEG source reconstruction*

628 MEG and EEG data were combined before inversion into source space <sup>27</sup>. The forward 629 model (lead field) was estimated from a single shell canonical cortical mesh with >8000 630 vertices of each participant's anatomical T1-weighted MRI image. Lead fields were 631 calculated over a window from -1500 to 2500ms relative to motion coherence onset. 632 The cortical mesh was co-registered to the MEEG data using the digitised fiducial and 633 scalp points. We computed the inverse source reconstruction for single trials using the 634 minimum norm algorithm as implemented by SPM12. All conditions were included in 635 the inversion to ensure an unbiased linear mapping. The source images were spatially 636 smoothed using an 8 mm FWHM Gaussian kernel.

637

# 638 Dimensionality reduction

639 To address the problem of multiple comparisons and reduce the computational load 640 when comparing the model predictions with the source-localized time series, we 641 applied a parcellation-based dimensionality reduction to our data following the procedure described by Colclough and colleagues <sup>37</sup>. First the whole-brain surface was 642 643 parcellated into 96 anatomical regions of interest (ROIs) as defined by the Harvard-644 Oxford cortical brain atlas. Then we represented the dynamic of each ROI with a single 645 time-course, obtained using principal component analysis. The reconstructed sources 646 within each ROI were first bandpass-filtered. The coefficients of the principal 647 component accounting for the majority of the variance of the vertices within each ROI, 648 were then taken as an appropriate representation of source activity for that region.

649

### 650 Accumulator model of perceptual and action decisions

651 Behavioral data were analyzed using a variant of the linear ballistic accumulator (LBA) 652 model which has been previously applied to a finger tapping task to model fMRI 653 evidence accumulation <sup>13,30</sup>. According to this class of models, a decision about when 654 and which action to select is dictated by a 'race' competition among independent 655 accumulators. Each accumulator linearly integrates the decision-evidence (or the 656 intention) over time in favor of one action, and the decision is made when the 657 accumulated activity reaches threshold. In our task possible actions correspond to a 658 button press from one of four fingers, each modeled by independent accumulators 659  $i \in \{1, 2, 3, 4\}$ . When three valid actions are available, three accumulators are engaged 660 with activation starting at levels independently drawn from a uniform distribution 661 [0, c0], and increasing linearly over time with an accumulation rate (*v*) drawn from an 662 independent normal distribution with mean  $\mu_i$  and standard deviation  $\sigma_i$ .

A response is triggered once one accumulator wins the 'race' and reaches a decision bound *b*. When only one action is available, only the accumulator corresponding to the available action is engaged. Predicted reaction time (RT) is given by the duration of the accumulation process for the winning accumulator, plus a constant non-decision time  $t_0$  representing the latency associated with stimulus encoding and motor response initiation <sup>31</sup>.

669

# 670 Parameter estimation and model selection

671 To identify the combinations of free parameters that best accounted for the observed 672 behavioral data we firstly fitted 15 variants (i.e. all possible combinations without repetition) of the LBA. Each variant was characterized by a unique combination of *free* 673 parameters allowed to vary across trials. We followed the former procedure <sup>30</sup> to 674 675 estimate the model prediction of reaction times quantiles and selection probabilities of 676 each condition. The best-fitting parameters for each model variant were used to 677 calculate the Bayesian Information Criterion (BIC), which penalize extra free 678 parameters in favor of simpler models. BIC values were then used to compare the goodness-of-fit of each variant using random-effects Bayesian model comparison <sup>33,34</sup>. 679 680 In this comparison, each model variant is treated as a random effect that could differ 681 between participants. The critical statistical quantity is the probability that any given 682 model outperforms the other variants most of the time (exceedance probability).

683

# 684 Estimation of expected neural activity

685 We generated predictions of decision-related activity from the LBA model to locate 686 neural signatures of decisions-evidence accumulation in single-trial analyses of MEEG data. For multiple options, the LBA model assumes multiple active accumulators, one 687 for each finger option. Let  $\tilde{\mu}_W$  be the accumulation rate of the winning option (i.e. the 688 one reaching response threshold b), sampled from the normal distribution  $N(\mu_W, \sigma_W^2)$ . 689 Let  $\tilde{\mu}_{L1}$  and  $\tilde{\mu}_{L2}$  be the sampled accumulation rates of the alternative options (i.e. the 690 losers), sampled from normal distributions  $N(\mu_{L1}, \sigma_{L1}^2)$ ,  $N(\mu_{L2}, \sigma_{L2}^2)$ , respectively. If 691 692 the reaction time of a given trial is RT, the latency of the accumulation process is  $RT - t_0$ , such that the expected accumulation of the winning option is: 693

694 
$$E[\tilde{\mu}_W] = \frac{b - c_0/2}{RT - t_0}$$
 (3)

Since the losing accumulators have not reached the threshold by the time of the response RT, the expected values of  $\tilde{\mu}_{L1}$  and  $\tilde{\mu}_{L2}$  are smaller than  $\tilde{\mu}_{W}$ . Therefore, the losing accumulation rates have truncated normal distributions with an upper bound of  $\tilde{\mu}_{W}$  and with expected values of:

$$699 \quad \begin{cases} E[\tilde{\mu}_{L1}|\tilde{\mu}_{L1} < \tilde{\mu}_{W}] = \mu_{L1} - \sigma_{L1} \left[ \frac{\varphi(\frac{\tilde{\mu}_{W} - \mu_{L1}}{\sigma_{L1}})}{\varphi(\frac{\tilde{\mu}_{W} - \mu_{L1}}{\sigma_{L1}})} \right], \\ E[\tilde{\mu}_{L2}|\tilde{\mu}_{L2} < \tilde{\mu}_{W}] = \mu_{L2} - \sigma_{L2} \left[ \frac{\varphi(\frac{\tilde{\mu}_{W} - \mu_{L2}}{\sigma_{L2}})}{\varphi(\frac{\tilde{\mu}_{W} - \mu_{L2}}{\sigma_{L2}})} \right], \end{cases}$$
(4)

701 where 
$$\varphi(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$
 and  $\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-x^2/2} dx$ .

The sum of the winning and losing accumulation rates gives an estimation of total

accumulation activity for single trials. For trials with only one available option, the

accumulation activity is determined by the only active accumulator.

705

# 706 Single-trial analysis

707 To identify the spatio-temporal profile of decision-related accumulation over the brain 708 we derived model-predicted signals for each trial to compare with neural oscillations in 709 theta (4 - 8 Hz), alpha (8-12 Hz), beta (12-30 Hz) and gamma (31-90 Hz) frequency 710 bands. To estimate the power of oscillations on a single-trial basis, stimulus-locked 711 epochs from 500 ms before to 1500ms after coherence onset. Next, we extracted 712 frequency-specific signal envelope modulations using a Hilbert transform of the source 713 data from each reconstructed ROI. The Hilbert's envelope is a convenient measure of 714 how the power of the signal varies over time in the frequency range of interest, and thus 715 particularly suited to capture relatively slow fluctuations associated to the instantaneous 716 accumulation of evidence/intentions. The power estimates of individual participants 717 were down-sampled to 100Hz and normalized by their baseline (from 400ms to 100ms 718 before coherence onset).

We estimated the maximum lagged absolute Spearman correlation between the model predicted activity and the signal envelope in a trial-by-trial fashion. The lagged correlation was used to optimally split the non-decision time before and after the accumulation period to determine the time delay between the neural signal and the model predictions. The time before accumulation provides a measure of the temporal separation between coherence onset and accumulation onset.

725 If the model prediction x is a lagged version of the neural signal y so that

726 
$$y(t) = x(t + \tau_0)$$
 (5)

Where  $\tau_0$  is a time delay that can vary from 0ms to the individual non-decision time ( $t_0$ ) with steps of 10ms, then the maximum absolute lagged correlation between xand y is defined as

730 
$$\rho_{xy}(t) = \max|corr(y(t), x(t - \tau_i))|,$$
 (6)

731 where 
$$i = [0, 10, 20 \dots t_0]$$
.

With the peak value of  $\rho_{xy}(t)$  occurring when  $\tau_i = \tau_0$  which allows us to determine 732 733 the time delay. We estimated the largest absolute lagged correlation value for each ROI 734 and individuals by comparing concatenated epochs and model predictions. This choice 735 permits to measure accumulation lags specific to each ROI, under the assumption that 736 they differ across brain regions for each participant. The strength of the Fisher-737 transformed maximum lagged correlations for each ROI was then quantified (z-score) 738 using a one-sample sign-test. To provide a conservative estimate of significant 739 correlations between model prediction and neural activity, we repeated the above 740 procedure 10.000 times, each iteration using a different phase-randomized version of 741 the original MEEG signal, to obtain a distribution of correlations under chance. Two-742 tailed statistical significance was assessed by computing the proportion of absolute 743 values of the distribution of correlations generated by chance exceeding the correlation 744 between model predictions and the original MEEG signal. The resulting p-values were 745 corrected for multiple comparisons (False Discovery Rate) across ROIs and frequency 746 bands.

747

# 748 Connectivity analysis

To explore the direction of the information flow we employed phase-transfer entropy,

a data-driven effective-connectivity measure robust to signal leakage <sup>28</sup>. The preferred

751 direction of information between ROIs whose activity best matched with model's

752 predicted activity was estimated using the directed phase-transfer entropy.

753 To identify the ROIs that preferentially accumulated evidence for perception or action 754 decisions, the average information flow (quantified by phase transfer entropy) sent by each ROI was calculated for each subject and condition. The difference of information 755 756 flow between uncertainty levels for perception and action is compared at the ROI level 757 with a surrogate distribution generated by flipping the condition labels for a random 758 number of participants (10.000 iterations). Since significance was estimated separately 759 for perception and action, the critical value for the FDR correction was halved to 760  $\alpha = 0.025.$ 

761 To quantify the direction of information flow, we calculated a posterior to anterior 762 index (PAx) as implemented by Hillebrand et al, 2016. A positive PAx indicates 763 preferential flow from posterior regions toward anterior regions. ROIs were split into 764 anterior and posterior region with respect to the precentral gyrus (see Table S1). 765 Significance was assessed with permutation testing where the average directional 766 phase-transfer entropies were shuffled across ROIs and PAx was estimated. This 767 procedure was repeated 10.000 times to generate a surrogate distribution of PAx values 768 against which the observed PAx values were tested (p<0.025 to account for multiple 769 comparisons).

For the correlations in Figure 6a, we first confirmed homoscedasticity of our data
and then calculated bootstrapped Pearson's correlations. For the correlations in
Figure 6b we used repeated-measures correlation (as implemented in the rmcorr
package in R) which accounts for non-independence among observations due to
multiple measurements per participant. The resulting p-values were corrected for
multiple comparisons by applying Holm-Bonferroni correction.

# 776 Hypothesis testing

777 Differences in reaction times were tested with a 2-way repeated measures ANOVA

778 (Low/High Uncertainty x Action/Perception). All other hypothesis tests used non-

parametric tests or random permutation methods that do not rely on specific

assumptions about the distributions of data values. All tests were evaluated at the

p<0.05 level (two-tailed), correcting for multiple comparisons where appropriate.

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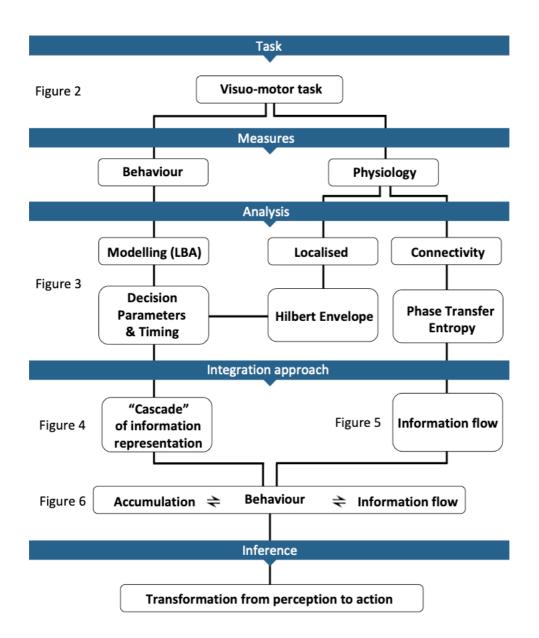
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- Figure 1: Overview of the study. We combined behavioural, computational, and
  neuroimaging approaches to provide an integrated perspective of the decision
  processes linking perception to action. Each section is expanded in a subsequent
- 976 figure, as directed.

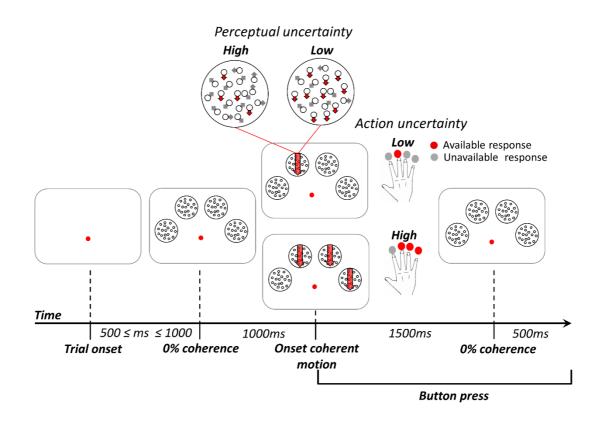
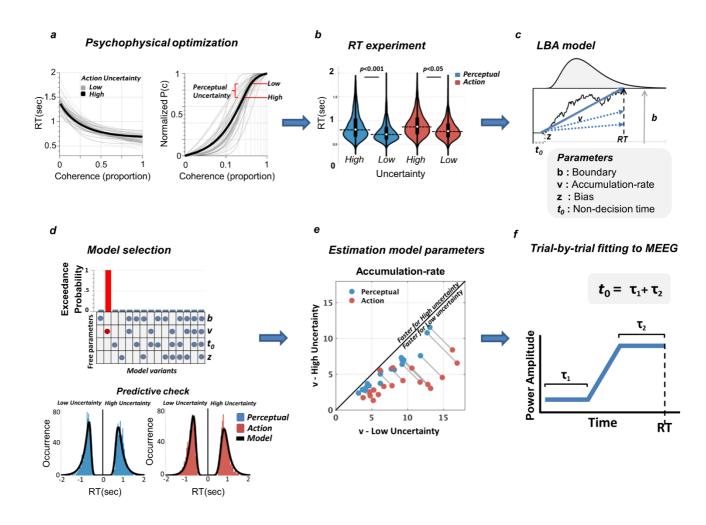


Figure 2: Experimental manipulation of perceptual and action uncertainty. 977 978 Participants pressed the button corresponding to the coherent stimulus (red downward 979 arrow). When there were more than one coherent stimulus, they selected one response 980 and pressed the corresponding button. Perceptual uncertainty was manipulated by 981 changing the coherence of dot motion (i.e. by changing the motion strength), whereas 982 action uncertainty was manipulated by changing the number of available options (i.e. 983 the number of coherent stimuli to choose from). Perceptual and action uncertainty 984 varied across trials in a 2 by 2 factorial design.

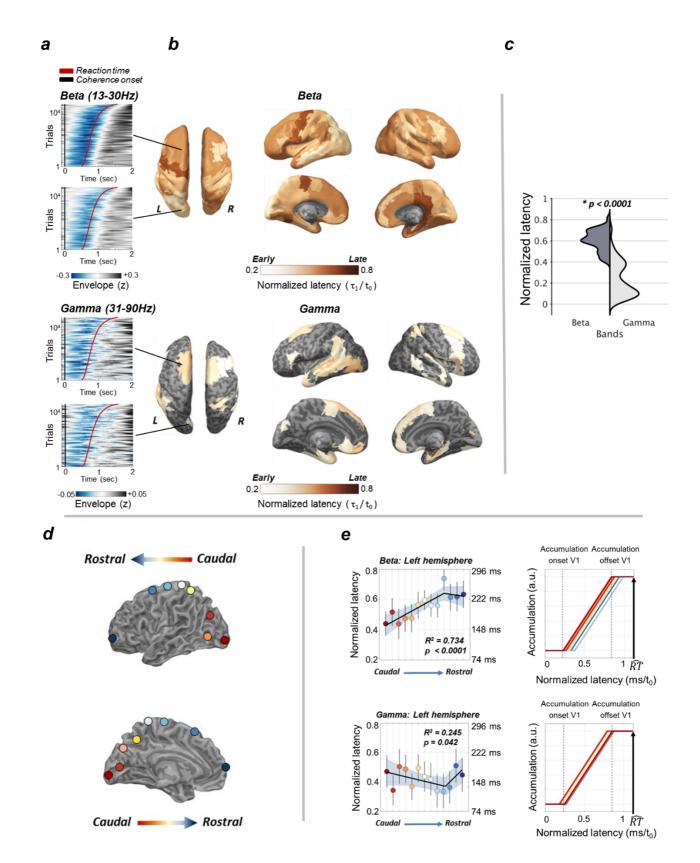


#### 985 Figure 3: Uncertainty modulates reaction times and the speed of decision

evidence accumulation. a Decision evidence was titrated to the participants' 986 987 individual motion sensitivity: Individual motion thresholds for each trial type was 988 measured on a session preceding the scan. Reaction times (left panel) and accuracy 989 (right panel) varied with motion strength (grey lines: individual data, black tick lines: 990 mean data). Low and High perceptual uncertainty were estimated at the 75% and 90% 991 accuracy levels, respectively. **b** During the experiment, reaction times were 992 modulated by both perceptual and action uncertainty, confirming the efficacy of our 993 manipulations (aggregated data for uncertainty type, rm-ANOVA on log-transformed 994 reaction times). c The task was modelled using a race accumulation model (Linear 995 ballistic accumulator, LBA). In this model, noisy evidence is integrated over time at a 996 given rate (v) up to an absorbing decision bound (b). Each option is represented by 997 one accumulator racing to reach the bound. The fastest accumulator (thick blue arrow) 998 determines the choice. Non-decision time linked to sensorial and motor processes (t0) 999 sums to the evidence accumulation time to produce reaction-times. **d** Bayesian model

1000 comparison revealed that changes in the sole drift-rate best accounted for the

- 1001 behavioral data. The quality of fit is also seen in the comparison of empirical reaction
- 1002 time distributions for each condition, against data simulated using the optimal model
- 1003 and its parameters. **e** The model predicted faster accumulation of decision evidence
- 1004 when uncertainty is low for both action and perceptual uncertainty (grey lines
- 1005 connects data points from each participant). **f** Model predicted activity was fitted to
- 1006 the power envelope of the MEEG signal in a trial-by-trial fashion to identify
- 1007 accumulators of decision evidence. Non decision time (t0) was decomposed into pre-
- 1008 accumulation (tau1) and post-accumulation (tau2) time reflecting perceptual and
- 1009 motor processes, respectively. This allowed us to identify the latencies of different
- 1010 accumulators across the brain and to draw time-resolved maps of the flow of
- 1011 information from perception to action.

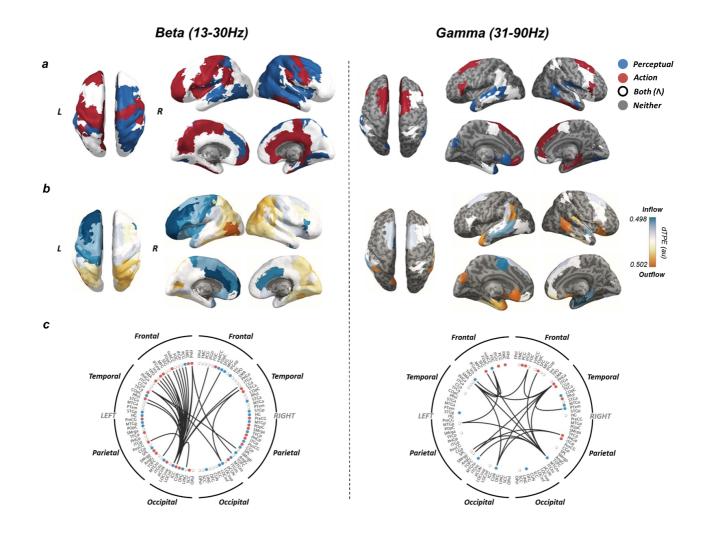


# 1012 Figure 4: Temporal cascade of information-representation revealed by

# 1013 comparing trial-by-trial MEEG power envelopes to model's predictions.

- 1014 **a** Power plots ranked by reaction-times showing the temporal relationship between
- 1015 signal power envelope (z-scored with regard to each individual's baseline average)

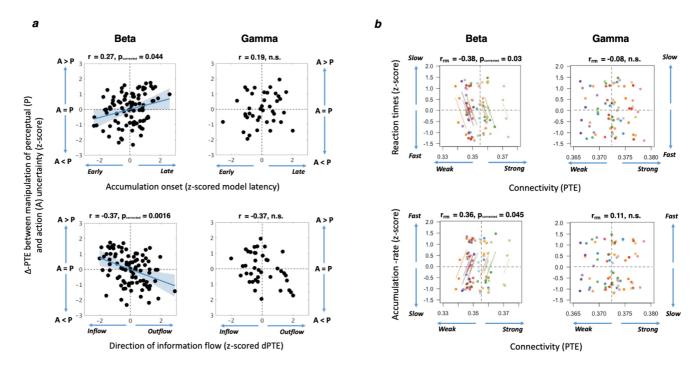
1016 and reaction times (red curve) at representative ROIs showed separately for Beta band 1017 (top row) and gamma band (bottom row). The ordinate of each plot represents 1018 individual trials pooled across participants and sorted according to reaction times. The 1019 black line indicates motion coherence onset. **b** Latency maps showing the normalized 1020 latencies (each accumulation onset time divided by individual non-decision time) of 1021 decision-evidence accumulation across anatomical regions where correlations 1022 between power-envelopes and model's predictions survived random permutation 1023 testing (see Methods). c Decision-evidence accumulation in the gamma band precedes 1024 beta (top panel). ROIs along the dorsal path color-coded with respect to their position along the caudo-rostro axis **d** ROIs along the dorsal path are ranked based on their y-1025 1026 coordinate value. e Decision-evidence accumulation mediated by beta follows a caudo-rostral gradient along the dorsal path of the contralateral hemisphere. A 1027 piecewise regression (top left panel) best describes the gradient showing that latencies 1028 increase from visual areas up to M1 in the precentral gyrus and decrease afterwards 1029 1030 suggesting two separate converging flows (Error bars indicate SEM, shaded area 1031 covers bootstrapped 95% regression CI). The pattern is inverted for gamma where 1032 latencies increase while proceeding from M1 to posterior and anterior ROIs. Despite 1033 the differences in latencies along the gradient, the cascade of information-1034 representation is quasi-parallel. The right panels show that the latest ROI in the 1035 gradient starts accumulating decision-evidence before the earliest ROI (e.g. V1 for 1036 beta) has reached the decision boundary. RT hat is the mean reaction time (across 1037 trials and participants) normalized by the mean non-decision time (t0).



#### 1038 Figure 5: Sensitivity to uncertainty and information flow, show distinct

#### 1039 spatiotemporal gradients. a Differences in phase transfer entropy between

- 1040 manipulations of perceptual and action uncertainty for beta (left column) and gamma
- 1041 (right column) allows to define regions accumulating information specific to
- 1042 perception and action decision. **b** Information flow (directional phase transfer
- 1043 entropy) shows a clear rostro-caudal gradient in beta with MT-complex and the
- 1044 frontal regions being the strongest sender and receiver of information, respectively. c
- 1045 Thresholded connectivity plots. Beta activity reflects transmission of information
- 1046 across distant cortical regions mostly within the left hemisphere. Gamma shows a
- 1047 more local activity with no clear lateralization. The full names of the ROIs are given
- 1048 in the **Supplementary Table 2**.



1049 Figure 6: Information flow is stronger under low uncertainty and associated 1050 with faster reaction times and larger model accumulation-rates. a Specificity to uncertainty manipulations correlated with model latency (top row) and direction of 1051 1052 information flow (bottom row). Perceptual regions tend to show shorter latencies and 1053 to drive information transmission more than action regions. Points show z-scores of 1054 median values across subjects for each ROI (96 beta ROIs, 40 gamma ROIs). Shaded area covers bootstrapped 95% CI b Repeated-measures correlations. Reaction times 1055 1056 (top-row) and accumulation-rates (bottom row) correlated with phase transfer entropy in the beta (left column) and gamma (right column) band. Points show median values 1057 for the four tested conditions. Data from the same participant are displayed in the 1058 1059 same color, with the corresponding lines showing the individual fit of the repeated-1060 measures correlation.