

1 **Discriminating bacterial phenotypes at the population and single-cell level:** 2 **a comparison of flow cytometry and Raman spectroscopy fingerprinting**

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12 **Abstract:**

13 **Background:**

14 Investigating phenotypic heterogeneity can help to better understand and manage microbial
15 communities. However, characterizing phenotypic heterogeneity remains a challenge, as there
16 is no standardized analysis framework. Several optical tools are available, such as flow
17 cytometry and Raman spectroscopy, which describe properties of the individual cell.

18 **Results:**

19 In this work, we compare Raman spectroscopy and flow cytometry to study phenotypic
20 heterogeneity in bacterial populations. The growth stages of three replicate *E. coli* populations
21 were characterized using both technologies. . Our findings show that flow cytometry detects
22 and quantifies shifts in phenotypic heterogeneity at the population level due to its high-
23 throughput nature. Raman spectroscopy, on the other hand, offers a much higher resolution
24 at the single-cell level (i.e. more biochemical information is recorded). Therefore, it is capable
25 of identifying distinct phenotypic populations in an automated way when coupled with analyses
26 tailored towards single-cell data. In addition, it provides information about biomolecules that
27 are present, which can be linked to cell functionality.

28 **Conclusions:**

29 We propose a workflow to distinguish between bacterial phenotypic populations using Raman
30 spectroscopy and validated this approach with an external dataset. We recommend to apply
31 flow cytometry to quantify phenotypic heterogeneity at the population level, and Raman
32 spectroscopy to perform a more in-depth analysis of heterogeneity at the single-cell level.

33 **Keywords:**

34 *E. coli*; Flow cytometry; phenotypic heterogeneity; Raman spectroscopy; single-cell
35 technology; microbial ecology; growth phase

36 Background

37 Single-cell phenotypic differences arise even in genetically identical cultures (Govers et al.
38 2017). A definition of a phenotypic population is an observed cellular state within a given
39 genetic and environmental background. It arises due to epigenetic variations, stochastic gene
40 expression, cellular age or oscillations such as the cell cycle. This is one of the strategies that
41 bacteria use to adapt to a changing environment, as well as to divide the labour within the
42 community (Avery 2006; Ackermann 2015).

43 Phenotypic heterogeneity in laboratory cultures is well-documented. For example, it has been
44 studied in bacterial subpopulations that could tolerate antibiotics (known as 'persisters') (Dhar
45 and McKinney 2007), in the production of cytotoxin K in *Bacillus cereus* (Ceuppens, Boon, and
46 Uyttendaele 2013) or in the differential expression of flagellin in *Salmonella typhimurium*
47 (Stewart et al. 2011). The challenge remains to find tools to measure and quantify this
48 heterogeneity (i.e. phenotypic populations), in order to be able to link heterogeneity with
49 bacterial functionality. This would allow to manage - and potentially steer – microbial
50 communities in order to optimize bioprocesses.

51 Several tools are available for single-cell phenotyping (Davis and Isberg 2016). Imaging
52 techniques are popular, but they require tagged bacterial cells or a probe to visualize the
53 bacteria or the molecule of interest (Taniguchi et al. 2010; Anetzberger, Schell, and Jung
54 2012), making them less suitable to study environmental communities. There are other
55 techniques that do not require a probe, such as intrinsic fluorescence (Georgakoudi et al. 2007)
56 or the detection of autofluorescent NAD(P)H (Bhattacharjee et al. 2017). However, the amount
57 of information that can be gathered is limited compared to other techniques, such as
58 transcriptomics, flow cytometry or spectroscopy techniques. Single-cell transcriptomics are
59 also an option for bacterial phenotyping, but a few hundred cells are needed and only about
60 15 - 25% of the expressed mRNAs can be detected (Tang, Lao, and Surani 2011). This

61 analysis requires for bacteria to be lysed, and it was found in *E. coli* that a single cells' protein
62 and mRNA copy numbers are uncorrelated for any given gene (Taniguchi et al. 2010).

63 A more high-throughput option for single-cell analysis is flow cytometry, which can measure
64 thousands of bacterial cells per second. Individual cells pass through a laser, after which
65 detectors collect information on the scattered laser light (forward scatter, FSC, and side scatter,
66 SSC) and on fluorescent emissions of specific probes (Davey and Kell, 1996). To detect
67 bacteria, general nucleic acid stains (such as SYBR Green I or DAPI) can be used (Koch et al.
68 2018). This technique allows to quantify cells, and also to identify different phenotypes in
69 bacterial populations. For example, this technique allowed Sanchez-Romero and Casadesus
70 (2014) to find a differential expression of a GFP-tagged gene related to antibiotic resistance in
71 a *Salmonella enterica* population, and Cronin and Wilkinson (2008) to detect a heterogeneous
72 response of *Bacillus cereus* endospores to different heat treatments. Furthermore, the
73 information derived from the FCM measurements can be transformed into a fingerprint, and
74 used to calculate inter- and intra-species variations in bacterial populations (De Roy et al. 2012;
75 Props et al. 2016; Koch et al. 2014). Flow cytometry can also be used for bioprocess
76 monitoring, as it allows to quantify the number of cells present in a reactor, their viability and
77 activity, as well as their membrane potential over time (Díaz et al. 2010). When this technique
78 is coupled to cell sorting (also known as FACS, or FCM Activated Cell Sorting), a follow-up
79 analysis on the subpopulations can be made. For example, by doing a proteomic analysis to
80 link these phenotypes to a certain functionality (Jahn et al., 2013), to further culture the cells,
81 or by doing single-cell microscopy analysis (Nebe-von-Caron et al., 2000).

82 Raman spectroscopy is another single-cell technology that has been proposed to study
83 phenotypic heterogeneity. It does not require labelling and is non-destructive. The laser excites
84 individual cells, which leads to inelastic scattering, which in turn is collected in the form of
85 Raman spectra. It is less throughput compared to flow cytometry: even when enhancing the
86 signal with metals (known as Surfaced-Enhanced Raman Spectroscopy or SERS), each cell
87 takes 1-3 seconds to measure (Liu et al. 2016). The resulting spectrum contains biochemical

88 information of the molecules that are present in the cell – e.g. lipids, carbohydrates, nucleic
89 acids and proteins- and can be used to classify bacteria according to phylogeny (Goodacre et
90 al., 1998). This information can be quantitative if an internal standard for the molecule(s) of
91 interest is made -for example, (Cowcher, Xu, and Goodacre 2013) quantified the dipicolinate
92 (DPA) biomarker for *Bacillus* spores; or (Samek et al. 2016) quantified polyhydroxyalkanoates
93 produced by *Cupriavidus necator* H16)-. Raman spectroscopy can also be linked to cell sorting
94 -known as RACS or Raman Activated Cell sorting- to further study phenotypes (Zhang 2015a).
95 Raman spectroscopy can be used for the monitoring of bioprocesses, as it can measure over
96 time compounds present in the supernatant such as glucose, protein production or others (Lee
97 et al. 2004), as well as some Raman reactive compounds present in the bacteria, such as
98 chlorophylls, carotenoids and other pigments (Jehlička, Edwards, and Oren 2014). Although
99 this technique is used for bacterial identification (Huang et al., 2010; Almarashi et al. 2012;
100 Strola et al. 2014; Pahlow et al. 2015), the study of phenotypic heterogeneity by Raman
101 spectroscopy bacterial fingerprint remains relatively little explored.

102 Both flow cytometry and Raman spectroscopy give rise to data that need specific pre-
103 processing and analysis (O'Neill et al. 2013; Saeys, Gassen, and Lambrecht 2016; García-
104 Timermans et al. 2018; Ryabchykov, Guo, and Bocklitz 2018). While microbial flow cytometry
105 is rather limited in its phenotypic resolution (i.e., only a few properties are measured per cell),
106 Raman spectroscopy characterizes many more biochemical properties of bacterial cells. It
107 therefore requires analysis of high-dimensional data, which can be challenging, but it allows to
108 characterize phenotypic heterogeneity at a much higher resolution.

109 In this work, we analysed bacterial cells from nine phenotypic populations –with a different
110 growth stage and/or from a different replicate- using flow cytometry and Raman spectroscopy.
111 We demonstrate how these populations can be automatically retrieved using data-specific
112 algorithms. We also demonstrate how metabolic inference can be performed based on Raman
113 spectroscopy in a data-driven way. Finally, the advantages and disadvantages of these tools

114 for microbial phenotyping are discussed. We will motivate that, in its current form, microbial
115 flow cytometry can be used to quantify phenotypic heterogeneity and describe community-
116 level dynamics, while Raman spectroscopy can be applied to describe single-cell
117 heterogeneity and possibly identify separated phenotypic populations. We include a
118 recommendation for microbiologists on how to employ Raman spectroscopy and flow
119 cytometry in future phenotyping studies.

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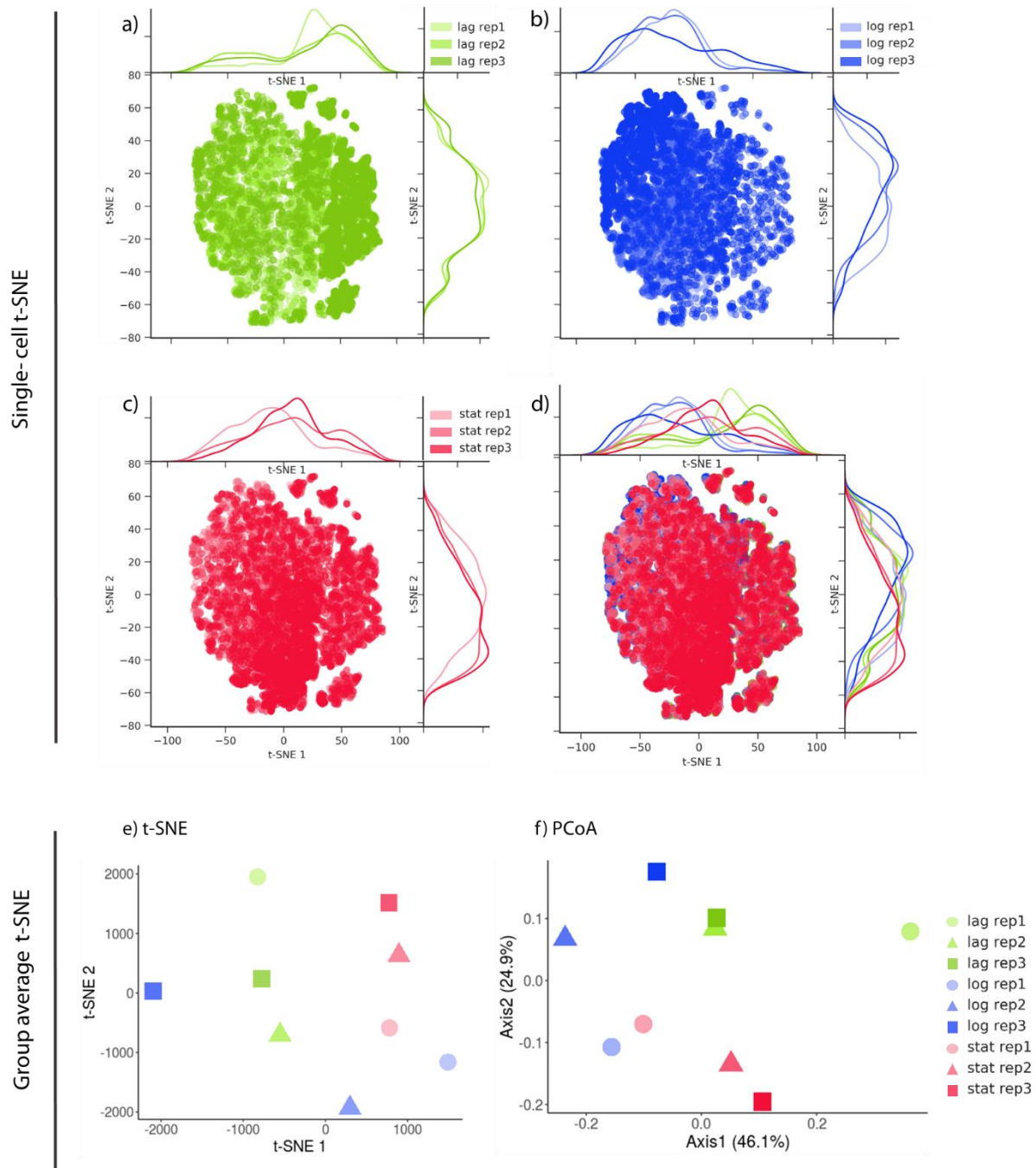
122 Results

123 Throughout this paper, we define a 'phenotypic population' as a group of bacteria grown under
124 the same environmental conditions (i.e. cells from the same biological replicate at a certain
125 growth stage). This population will share morphological and/or metabolic traits that can be
126 detected by flow cytometry and Raman spectroscopy. Samples of *E. coli* DSM 2092 were
127 measured in the lag, log and stationary phase. For every condition, triplicates of the cell culture
128 were made. Thus, we expected to retrieve 9 phenotypic populations. As it will be argued in the
129 discussion, this is not to say that there might not be other subpopulations in each of these
130 'phenotypic populations'.

131 Flow cytometry

132 Three biological replicates of *Escherichia coli* DSM 2092 were measured in the lag, log and
133 stationary phase through flow cytometry (Fig. S1). Data was analysed at two levels: (a) the
134 single-cell level (i.e., cells were analysed as individual instances) (b) the cell population level
135 (i.e., cytometric fingerprints were constructed to describe population dynamics) (Fig. 1). t-
136 distributed stochastic neighbourhood embedding (t-SNE) and principal component analysis
137 (PCA) were used to visualize the data at the single-cell level (Fig. 1a-d, Fig. S3). Principal
138 coordinate analysis (PCoA) was applied to visualize the differences of the phenotypic
139 populations based on Bray-Curtis dissimilarities (Fig. 1f). As a validation, t-SNE was performed
140 on the population level as well (Fig. 1e).

141



142

143 Fig. 1: *E. coli* measured with flow cytometry and analyzed at the single cell level (a-d) and population level (e and
144 f). t-SNE was performed on the aggregation of all samples (d), and visualized separately for each growth phase,
145 to allow for easier interpretation (a-c). Distributions on the side represent the t-SNE distributions separately
146 visualised for each growth phase/replicate to allow for easier interpretation. (e-f) Visualization of cytometric
147 fingerprints at the sample level, using t-SNE (e) or PCoA (f).

148 No separated subpopulations could be distinguished based on cytometric single-cell data
149 (Fig. 1a-d). Yet, shifts in the distribution of cells were clear, both between different growth
150 phases and replicates, as can be seen from the marginal distributions. Therefore, by creating
151 cytometric fingerprints, which are vectorizations of the cell counts per bin, these differences

152 could be quantified and visualized at the community level (Fig. 1e-f). Differences between
153 fingerprints were calculated using the Bray-Curtis dissimilarity. Average dissimilarities per
154 growth phase and replicate were summarized in Table 1. The average Bray-Curtis dissimilarity
155 between samples within the same growth phase is smaller compared to samples that
156 originated from the same replicate (Table 1). The lag phase for replicate 1 was quite different
157 from the other samples (Fig. 1f).

158 Table 1: Average Bray-Curtis distance between the samples based on their growth phase or their replicate. A.U.=
159 arbitrary units.

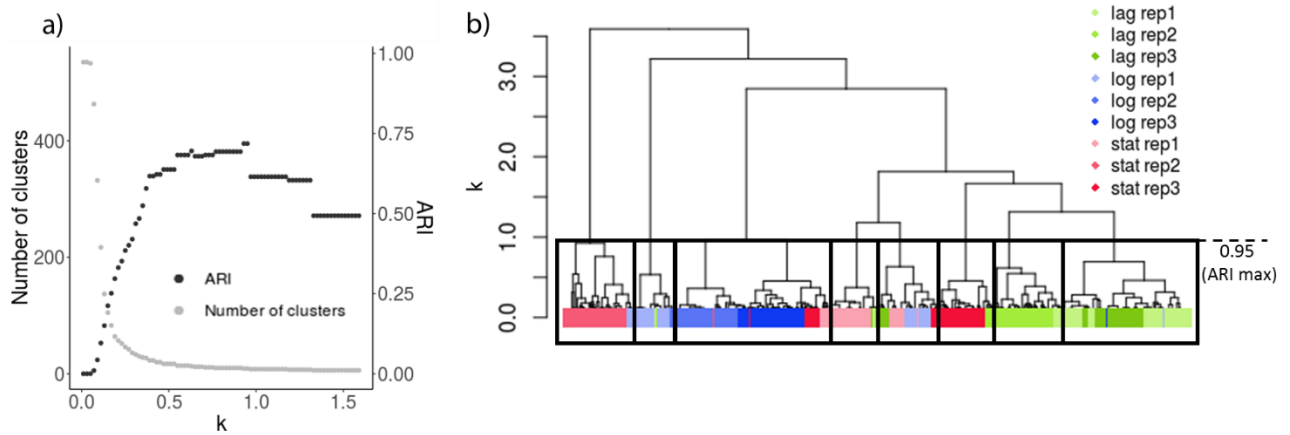
	Average distance between samples (A.U., n=3)	Standard deviation (n=3)
Lag phase	0.33	0.08
Log phase	0.33	0.06
Stationary phase	0.21	0.06
Replicate 1	0.41	0.18
Replicate 2	0.35	0.04
Replicate 3	0.35	0.07

160

161 Raman spectroscopy – clustering results

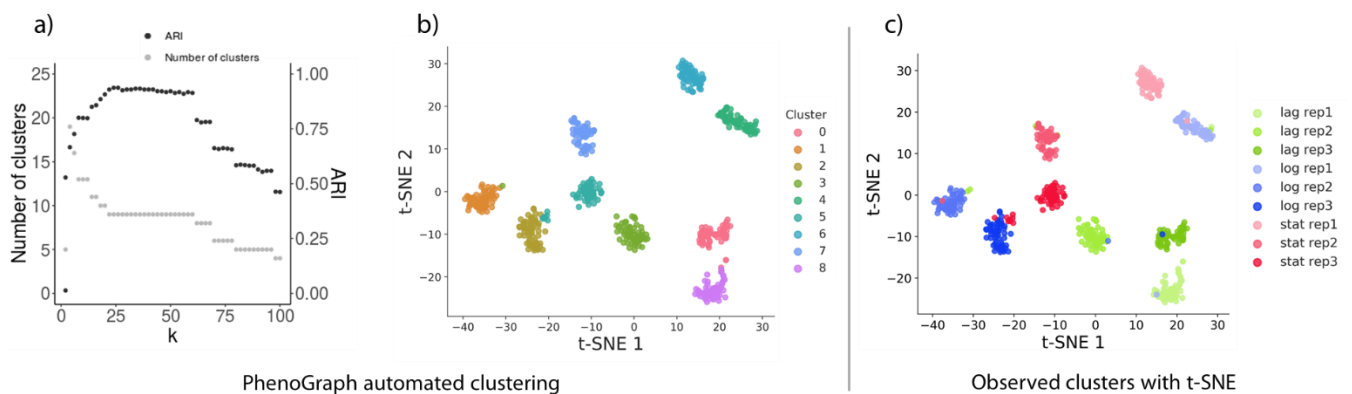
162 The samples used for flow cytometric analysis were fixed and analysed using label-free Raman
163 spectroscopy following the protocol from (García-Timmermans et al. 2018). To identify
164 phenotypic populations, two clustering methods were used. First, using an agglomerative
165 hierarchical clustering approach and secondly, using the PhenoGraph algorithm - a tool
166 developed for the analysis of high-dimensional cytometry data. To determine the hierarchical
167 clustering, the spectral contrast angle between samples was calculated (a measure of the
168 spectra similarity). Then, phenotypic populations can be delineated by setting a threshold upon
169 inspection of the resulting dendrogram after hierarchical clustering (Fig. 2). On the other hand,
170 PhenoGraph makes use of k -nearest-neighbours clustering, in order to determine groups of
171 similar cells, and as such, phenotypic populations. In other words, k expresses the amount of
172 local information that is included when cells are grouped according to similar spectra. k will

173 therefore, in a similar way as the threshold used in hierarchical clustering, impact the number
174 of phenotypic populations that are defined (Fig. 3).



175

176 Fig. 2: Hierarchical clustering of Raman spectra derived from the *E. coli* culture. Cells were measured in the log,
177 lag and stationary phase using Raman spectroscopy. (a) Left axis, grey: Visualization of the number of clusters we
178 can obtain by cutting the cluster at different heights (k). Right axis, black: ARI, which quantifies how many cells are
179 identified as the expected phenotypic population when clusters are made at different levels. (b) Dendrogram
180 representing the distance (calculated as the spectral contrast angle) amongst the Raman spectra. The black boxes
181 divided the phenotypic populations when the dendrogram is cut at $k=0.9$. This is the maximum adjusted Rand index
182 (ARI), as calculated in Fig. 2a.



183

184 Fig. 3: PhenoGraph clustering of Raman spectra derived from the *E. coli* culture. a) Influence of hyperparameter k
185 on the automated identification of phenotypic populations. Left axis, grey: Visualization of the number of clusters in
186 function of k . Right axis, black: Adjusted Rand index (ARI), which quantifies how many cells are identified as the
187 expected phenotypic population when clusters are made at different levels (k). b) t-SNE visualization, colored

188 according to PhenoGraph clustering with optimal ARI ($k=22$). c) t-SNE results colored according to growth phases
189 and replicates.

190 The adjusted Rand index (ARI) was used to quantify similarity between the clusters that were
191 determined by hierarchical clustering and Phenograph and the known phenotypic populations
192 (i.e. growth phase and replicate). An ARI of 1 indicates perfect grouping of the data. The
193 PhenoGraph algorithm resulted in a higher ARI as opposed to hierarchical clustering based on
194 the spectral contrast angle (Fig. 2a vs. Fig. 3a). Inspecting the PhenoGraph results, there is a
195 stable region for k that retrieves clustering according to both growth phase and replicate (i.e.,
196 nine clusters were found for $k = 20, \dots, 60$). A value of $k = 24$ or 26 gave rise to an optimal
197 clustering (Fig. 3a). Smaller k allowed to inspect phenotypic populations at smaller scales and
198 investigate the heterogeneity accordingly. See for example the clustering results for $k = 15$,
199 which resulted in eleven different groups of cells (Fig. S5). Additional clusters that emerged
200 were the result of splitting two clusters into two smaller ones. Likewise, larger k will result in
201 larger clusters. For example, for $k = 100$, data is grouped in five clusters (Fig. S5). Structure in
202 the data is retained, as clusters are merged either according to growth phase (clusters 0, 2
203 and 3) or replicate (cluster 1).

204 Often a single-cell was classified as the expected replicate, but in another growth phase (Fig.
205 3c). The samples in the lag phase seem to have a single-cell that is already in the log phase,
206 and in the cultures in the log phase, we find a cell in the stationary phase (in replicate 3) and
207 one cell in the lag and in the stationary phase (in replicates 1 and 2). It is also worth noting
208 that some cells from replicate three seem to be between the log and the stationary phase.

209 Raman spectroscopy – tentative region assignment

210 The Boruta algorithm, a variable selection algorithm based on Random Forests, was used to
211 associate the most distinctive regions in the Raman spectrum with cluster assignments
212 according to the hierarchical clustering and PhenoGraph algorithm. The cluster labels that
213 resulted in an optimal ARI were used. Regions were linked with different molecules based on

214 a recent summary from Wang et al., 2016. In this way, metabolic associations could be inferred
 215 that contained predictive power as a function of different phenotypic populations (Table 2).

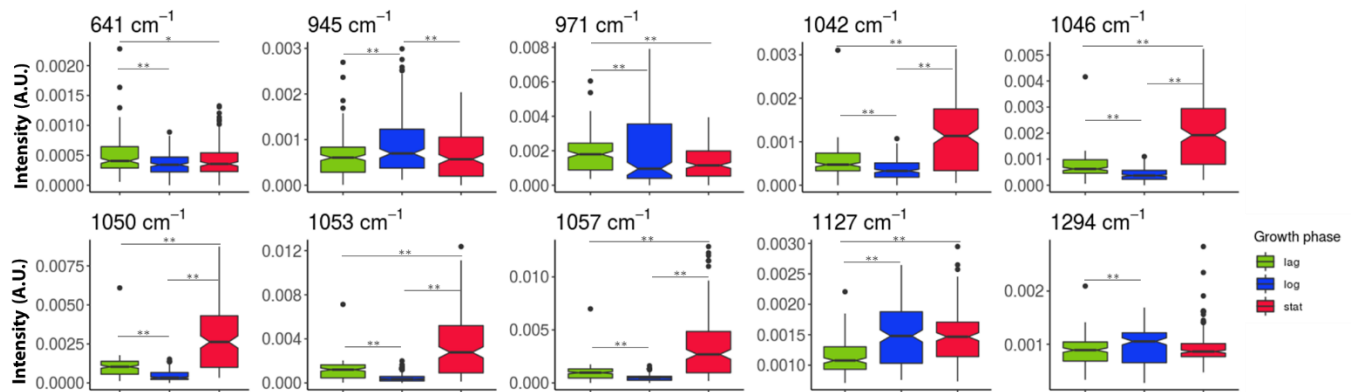
216 Table 2: Tentative assignment of Raman spectra using the Boruta algorithm based on phenotypic identification
 217 using hierarchical clustering and PhenoGraph. The 10 highest ranked areas are shown. When there is no known
 218 compound in the spectral region, either the closest compound or a blank is shown. A.U.=arbitrary units.

219

Wavelength (cm ⁻¹)	Features importance		Tentative assignment
	PhenoGraph (k=22, 9 clusters) (A.U.)	hclust (h=1, 8 clusters) (A.U.)	
1042	9.8	9.8	Carbohydrates, Proline (1043)
971	9.5	9.7	v(C-C) wagging (971) // Phosphate monoester groups of phosphorylated proteins and cellular nucleic acids (970)
945	9	8.9	vs (CH ₃) of proteins (α-helix) (951)
1057	8.9	8.8	Lipids (1057) // Carbohydrates (1030-1130)
1294	8.5	8.5	CH ₂ deformation (1295)
1050	8.5	8.6	Nucleic acids, CO stretching; protein, C-N stretching, PHB (1054) // Carbohydrates (1030-1130)
1053	8.4	8.4	Nucleic acid (1054) // Carbohydrates (1030-1130)
1127	8.3	8.4	v(C-N), protein (1127) // Carbohydrates (1030-1130)
1046	8.1	8.2	v ₃ PO ₄ ³⁻ (symmetric stretching vibration of v ₃ PO ₄ ³⁻ of HA) (1044)
641	8	7.9	C-C twisting of tyrosine (642)

220

221 To understand how the molecules in Table 1 vary from one group to another, the distribution
 222 of intensities of these Raman regions was plotted for every growth phase (Fig. 4). A Wilcoxon
 223 rank sum test with a Benjamini–Hochberg correction was performed for the ten highest ranked
 224 variabls according to the Boruta algorithm (Fig. 4).

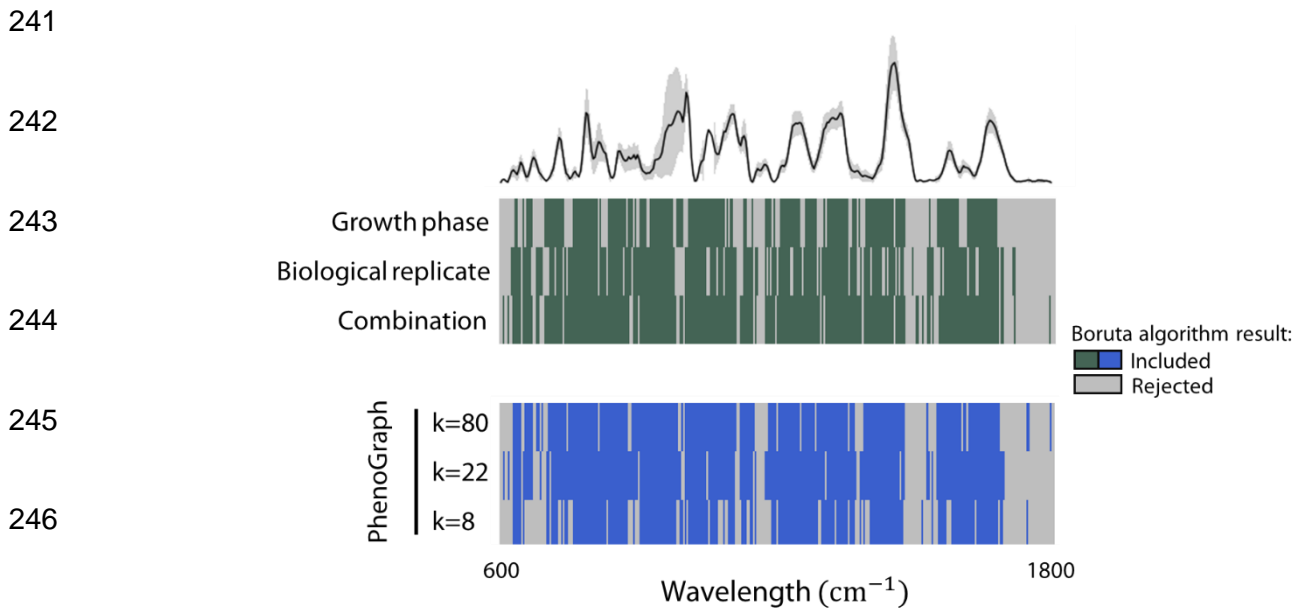


225

226 Fig. 4: Distribution of intensities of the most relevant regions associated with phenotypic populations according to
227 the Boruta algorithm. Boxplots represent the growth phases (replicates were pooled together). Groups were made
228 according to the growth phase: lag (green), logarithmic (blue) or stationary (red). For every spectral region, a
229 Wilcoxon rank sum test was made, with a Benjamini-Hochberg correction (upon rejection of the null hypothesis).
230 Groups with significantly different peaks are signalled with (*) ($p < 0.05$) or (**) ($p < 0.01$).

231 To better understand what regions of the Raman spectra (and therefore, what biomolecules)
232 were making these phenotypic populations different, we defined phenotypic populations at
233 different levels (changing the k parameter in the PhenoGraph algorithm) and then used the
234 Boruta algorithm to identify the most relevant regions.

235 When more phenotypic populations were distinguished (i.e. setting the value of k lower) more
236 regions in the Raman spectrum were associated with differences in phenotypic populations.
237 As shown in Figure 5, to find the phenotypic populations with different growth phases, 59% of
238 the regions are included (green); to find the biological replicates, it is 67%; and to find both
239 categories, 77%. Although this result was expected, a large number of Raman regions (48%)
240 were relevant for all levels of classification.

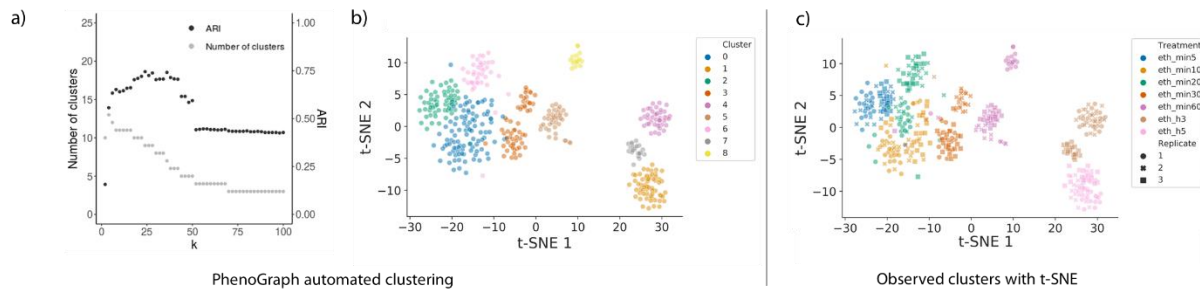


248 Fig. 5: Spectral regions relevant for phenotypic classification at different levels, according to the Boruta algorithm.
249 The top heatmap shows the results for the growth phase and replicates. At the bottom, the results for PhenoGraph
250 with the clustering hyperparameter k as 80, 22 or 8 are shown. In green and blue, spectral regions confirmed by
251 the Boruta algorithm as relevant, in grey the rejected. The average of all spectra is also plotted; the grey areas in
252 the average spectrum correspond to the standard deviation.

253 Validation of single-cell analysis of Raman spectra

254 To validate our workflow to analyse microbial single-cell Raman data, the dataset from Teng
255 et al., 2016 was used. In this work, *E. coli* was exposed to different chemicals (ethanol,
256 antibiotics, n-butanol or heavy metals) and the spectra of the bacteria were measured at
257 several time points after the treatment (5, 10, 20, 30 and 60 min, 3h and 5h). Three replicates
258 of the cell culture were made for each treatment. Here we show the results for cells treated
259 with ethanol (Fig. 6), representative for what is observed in the other groups (Fig. S6). t-SNE
260 was able to visualize groups of bacteria that received different treatments at different points in
261 time. Furthermore, two subpopulations are seen in every group. They correspond to the
262 replicates, where two replicate samples are separated, and the third replicate is either assigned
263 to one of the two or divided amongst the two subpopulations. The optimal ARI is lower than
264 the one reported for our own work, but still considerably higher than zero. This means that

265 although the clusters assigned according to PhenoGraph have a better match with the
266 treatments induced in our own dataset compared to this one, the clustering is still meaningful.



267

268 Fig. 6: External dataset clustered using t-SNE. *E.coli* treated with ethanol and measured at time points 5, 10, 20,
269 30 and 60 min, 3h and 5h. (a) Influence of hyperparameter k on the automated identification of clusters. Left axis,
270 grey: Visualization of the number of clusters in function of k . Right axis, black: Adjusted Rand index (ARI), which
271 quantifies how many cells are identified as the expected phenotype when clusters are made at different levels (k).
272 (b) Using the maximum ARI, samples were automatically clustered using PhenoGraph. (c) t-SNE was performed
273 on the data set and samples were labelled according to their treatment. The shapes represent the sample replicate.

274

275

276 Discussion

277 Flow cytometry quantifies population shifts

278 When using single-cell data from flow cytometry, the different phenotypic populations
279 overlapped and did not form separate clusters, as shown by both the t-distributed stochastic
280 neighbourhood embedding (t-SNE) and the principal component analysis (PCA) (Fig. 1a, SI
281 Fig. 2). However, in the t-SNE plot, a consistent shift in the cells distribution could be observed
282 in response to the different growth phases (Fig. 1a-d). In other words, gradual shifts in the
283 structure of the phenotypic population, i.e. the phenotypic heterogeneity, could still be
284 detected, although individual cells could not be separated according to growth phase or
285 replicate. As flow cytometry is capable of rapidly measuring a large amount of cells, the
286 differences in phenotypic heterogeneity at the population level could be described by
287 constructing cytometric fingerprints (Koch et al. 2014; Props et al. 2016). The Bray-Curtis
288 dissimilarity was used to quantify these differences at a sample level. The average Bray-Curtis
289 dissimilarity showed that the effect of the replicates exceeded the effect of the growth phase
290 (except for the lag phase). This implies that the differences of *E. coli* cells in different growth
291 stages are comparable or smaller to those the differences amongst replicates. The results from
292 (Teng et al. 2016) analysed in Figure 6 leads us to hypothesize that when the community is
293 steered with a stressor, the effect in the fingerprint is bigger, making the replicate effect smaller.

294 Flow cytometry is a high-throughput technique, able to rapidly measure hundreds to thousands
295 of individual cells. By applying fingerprinting approaches to cytometry data, differences
296 between microbial populations at the population level can be assessed and quantified. In this
297 work, gradual shifts could be detected in the flow cytometric data at the level of individual cells,
298 while at the sample-level (i.e. the population distribution level), differences between
299 communities could be quantified (e.g., using the Bray-Curtis dissimilarity) and separated
300 accordingly. In other words, while current resolution at the single-cell level appears to be limited
301 for microbial flow cytometry, due to its high-throughput nature, its power lies in the possibility
302 to characterize and phenotypic heterogeneity at the population level and quantify shifts in

303 phenotypic heterogeneity. In this work, gradual shifts could be detected in the flow cytometric
304 data at the level of individual cells, while at the sample-level (i.e. the population distribution
305 level), differences between communities could be quantified (e.g., using the Bray-Curtis
306 dissimilarity) and separated accordingly.

307 It is worth noting that in this work the effect of using additional or more specific labels for
308 cytometric analysis has not been explored, which might improve the resolution. It is possible
309 to add stains to target specific substrates (see the review of Léonard et al. (2016) on the use
310 of individual and double stains, and an example of a three-color analysis by (Barbesti et al.
311 2000)), but the number of markers describing microbial cells using flow cytometry will never
312 be of the same order as that of Raman spectroscopy. In eukaryotic flow cytometry, where the
313 tagging of specific antibodies is much more feasible, 19-parameter flow cytometry is routinely
314 used (17 fluorescence and two scatters) (Perfetto, Chattopadhyay, and Roederer 2004) and
315 30-parameter flow cytometry has just recently been published (Mair and Prlic 2018). However,
316 the dimensionality of cytometry data in these settings is still much lower than the number of
317 variables derived from Raman spectroscopy. Even in the best-case scenario, the
318 dimensionality of flow cytometry data cannot get close to the number of parameters that
319 Raman spectroscopy exhibits. On the other hand, depending on the research question, a high-
320 dimensional tool might not be needed. For example, biomolecules that are associated with a
321 phenotypic population might be known, and there could be a dye available to highlight these
322 molecules. In this case, flow cytometry could be more relevant for phenotyping than Raman
323 spectroscopy, provided the proper parameters are chosen to differentiate among treatments.
324 In this work, we compared phenotypic populations that are not differentiated by (a) specific,
325 known molecule(s) but used a general marker to characterize the DNA content. This explains
326 why flow cytometry did not have enough resolution to differentiate the phenotypic populations.

327 **Raman spectroscopy detects phenotypic populations at the single-cell level**

328 Raman spectroscopy is lower throughput for single-cell analysis when compared to flow
329 cytometry, but it is able to retrieve much more information per cell. Its resolution is enough to

330 conduct research at the single-cell level. The study of bacterial phenotypes using Raman
331 spectroscopy has been done by other groups: to identify different growth stages in *L.casei*
332 (Ren et al., 2017), stress-induced phenotypic populations (Teng et al. 2016), bacterial
333 phenotypes with different antibiotic responses (REFAtha 2014) or with different antibiotic
334 susceptibility (Novelli-Rousseau et al. 2018). It has also been used to discriminate between
335 different *Acinetobacter* (Maquelin et al. 2006) or different *E. coli* strains (Jarvis and Goodacre
336 2004) amongst other examples. However, in these studies the expected phenotypes were
337 known in advance. How to define what a phenotype is in a less-known system or a natural
338 environment? In this work, we propose and validate the use of PhenoGraph –a tool derived
339 from t-SNE and developed for the analysis of flow cytometry data- to do an automated
340 identification of bacterial phenotypes.

341 The PhenoGraph algorithm was originally developed for mass cytometry data (Levine et al.
342 2015), a variation of flow cytometry which makes use of heavy metal ion tags instead of
343 fluorochromes, resulting in more observed variables but at a lower acquisition speed (Spitzer
344 and Nolan 2016). PhenoGraph was demonstrated to be highly effective for clustering purposes
345 of single-cell Raman data, and returned a higher clustering performance compared to a more
346 traditional hierarchical clustering approach. However, hierarchical clustering allows to inspect
347 which cells are most similar to each other, a characteristic which is lost when using
348 PhenoGraph. Therefore we want to reiterate that, as proposed by (Andrews and Hemberg
349 2018) for the analysis of single-cell RNA sequencing data, "[I]ikewise, no computational
350 methods for dimensionality reduction, feature selection and unsupervised clustering will be
351 optimal in all situations". The algorithm of choice depends on the needs of the user. If a
352 researcher wants to visualize subpopulations, we recommend the use of t-SNE. If identification
353 of phenotypic populations is needed in an automated way, PhenoGraph is more appropriate.
354 To assess which individual cells are phenotypically closest, hierarchical clustering can be
355 used. Further investigation of the analysis of Raman data is needed, but investigating

356 additional algorithms specifically developed for high-dimensional single-cell data might further
357 support the impact of the use of Raman spectroscopy.

358 To improve the analysis speed of Raman spectroscopy, metallic substrates can enhance the
359 signal (SERS), but also microfluidic chips (McIlvenna et al. 2016) or optical tweezers can be
360 used (Xie, Chen, and Li 2005). An advantage of Raman spectroscopy is that it can be applied
361 without the use of labels. This allows to analyse the biochemistry of samples even without
362 knowing their nature. Raman spectroscopy also presents disadvantages. For instance, the
363 Raman signals of certain compounds can be quite weak, making them difficult to detect or
364 undetectable. The Raman signal of certain compounds can be composed of several peaks, or
365 be unknown. Also, the background of samples can interfere with the Raman signal of bacteria.
366 The equipment can be quite costly, depending on the type of Raman spectroscope.

367 Raman spectroscopy offers more parameters per cell compared to flow cytometry (hundreds
368 versus typically three or four for microbial experiments). Thus, individual bacteria are described
369 in a much larger multivariate space and can therefore be clustered into separate phenotypic
370 populations. This explains why bacterial subpopulations can be visualized at the single-cell
371 level using t-SNE (Fig. 3). The t-SNE results were confirmed with a PCA (Fig. S3).

372 The main downside of the use of label-free Raman spectroscopy is that the time of
373 measurement is long: in this experiment, for single-cell label-free measurements, we used an
374 acquisition time of 40 seconds per cell. Even when the acquisition time is lower –for instance,
375 (Liu et al. 2016) reported a 1-3 seconds acquisition time to detect antibiotic susceptibility using
376 surface-enhanced Raman spectroscopic biomarkers- the speed of Raman spectroscopy
377 cannot match the high-throughput nature of flow cytometry for single-cell analysis.

378 Raman spectroscopy allows to detect differences in biomolecules from one
379 sample to another

380 Raman spectroscopy allows to detect biomolecules present in different phenotypic
381 populations. Therefore, after automated identification of phenotypic populations, one can use

382 the phenotypic groups to perform a variable selection strategy to select important regions in a
383 data-driven way. We illustrated this approach using the Boruta algorithm, which was recently
384 evaluated as one of the state-of-the-art variable selection methods using Random Forests for
385 omics datasets (Degenhardt, Seifert, and Szymczak 2017). We found that a majority of
386 selected spectral regions were the same according to treatment and automated phenotypic
387 population identification using PhenoGraph (Fig. 3). This information can be used to infer how
388 phenotypic populations are different at the level of their metabolism. To do so, we have based
389 ourselves on a recent literature survey summarizing associations between Raman regions and
390 certain biological compounds (Wang et al. 2016). The ten most important regions in function
391 of phenotypic identification are listed in Table 2, along with the distribution of their intensities
392 (Fig. 4). These regions correspond to carbohydrates and nucleic acids, as well as some
393 unknown regions. An increase in the carbohydrate band (peaks 1042, 1046, 1050, 1057 cm-
394 1) was observed for the stationary phase. The band at 1053 cm-1 could also be a nucleic acid
395 peak, expected at 1054 cm-1. Nevertheless, these assignments for the Raman bands are
396 tentative and based solely on a literature research, and thus proper validation of these results
397 would have to be made in future experiments.

398 How to define a phenotypic population?

399 In this work, we have steered microbial communities towards a certain growth stage, expecting
400 that they would express a certain phenotype that could be retrieved using flow cytometry and
401 Raman spectroscopy. However, in each one of these isogenic populations there might be
402 subpopulations, as can be seen in Figure 2b. We acknowledge the difficulty in defining what a
403 phenotypic population is, and setting a threshold to determine when one phenotypic population
404 ends and another begins.

405 A similar problem exists in the area of bacterial taxonomy, where the similarity of 16S
406 sequences is compared. In this case, an arbitrary threshold is set (e.g., 95% similarity at the
407 genus level, 98.56% at the species level) (Stackebrandt and Goebel 1994; Kim et al. 2014).
408 As explained by Beye et al. (2018), this cut-off was meant to standardize the use of 16S rRNA

409 gene amplicon sequencing, but it had to evolve; i.e., the first threshold for the species level
410 has changed from 97%, to 98.7%, to the current 98.65%. Even now, it is argued that these
411 thresholds are not applicable to multiple genera (Mysara et al. 2017). In the case of phenotypic
412 populations, we propose a definition based on their similarity (after setting a similarity
413 threshold) and their ecology (their relationship with one another and with their environment).
414 Quantifying their similarity can be done in a data-driven way, by means of for example
415 clustering, at the resolution that is required for the specific research. This operational definition
416 allows to define phenotypic populations depending on the research question, as long as
417 researchers motivate and validate their choice. However, using this operational definition
418 means that results cannot be compared across experiments or labs. This is why we highlight
419 the need to find a more standard way to define 'basic phenotypic units', that would allow to
420 measure phenotypic traits and determine if bacteria belong to the same phenotypic population.

421 We propose to use algorithms -such as hierarchical clustering, t-SNE or PhenoGraph, applied
422 throughout this paper- to define, visualize and characterize phenotypic populations. t-SNE is a
423 well-known technique to visualize high-dimensional single-cell data, being commonly applied
424 to visualize for example cytometry and single-cell RNA sequencing data (Amir et al. 2013;
425 Andrews and Hemberg 2018). Our results confirm that it can be used as an 'off-the-shelf'
426 visualization method to detect phenotypic populations in Raman data when applied to
427 microorganisms.

428 Bacteria were grown in 9 different conditions (three replicate cultures of three growth stage
429 conditions) to steer the same *E. coli* population to a different morphological and/or metabolic
430 state –to steer them into 9 phenotypic populations. While hierarchichal clustering was able to
431 find eight of these phenotypic populations, PhenoGraph was able to retrieve all nine of them,
432 resulting in a higher ARI as well.

433 t-SNE and PhenoGraph were also applied to an external dataset from Teng et al., 2016,
434 consisting of *E. coli* that had been treated with different agents, and measured at several time

435 points. We showed that PhenoGraph was capable of differentiating the time points per
436 treatment. Interestingly, two subpopulations were identified per treatment, although samples
437 were measured in triplicate. These corresponded to two replicates, where the third was either
438 assigned to one subpopulation or divided between both (Fig. 6, Fig. S6). Our group has
439 previously shown how small technical variations can create subpopulations that have no
440 biological meaning (García-Timmermans et al. 2018), which might explain these findings.

441 Each algorithm has its own advantages and disadvantages. t-SNE is a highly effective
442 technique to visualize high-dimensional single-cell data, which we confirmed for the Raman
443 analysis of microorganisms. However, automated clustering of the data is not possible using
444 t-SNE without additional algorithms, such as PhenoGraph.

445 Conclusions

446 The results of this research suggest that:

- 447 - Flow cytometry is a more high-throughput technology than label-free Raman
448 spectroscopy, but Raman describes bacterial cells in many more variables, without the
449 need for staining.
- 450 - Flow cytometry can be applied to quantify differences in phenotypic heterogeneity at
451 the population level, whereas Raman spectroscopy has sufficient resolving power to
452 identify separated phenotypic populations at the single-cell level.
- 453 - Raman spectroscopy provides the possibility to infer which metabolic properties define
454 different phenotypic populations, and potentially exploit this information for bioprocess
455 monitoring.
- 456 - We propose a workflow to automatically identify bacterial phenotypes, based on
457 Raman spectral data. We also recommend t-SNE to visualize Raman data.

458 - From a broader perspective, one can motivate that phenotypic populations depend on
459 a similarity threshold, which can be set in clustering algorithms, and on their ecological
460 niche. We therefore suggest that researchers try to include validation controls in their
461 experimental setup, in order to motivate the threshold of choice in the algorithm.

462

463 Materials & Methods

464 Cell culture

465 To determine the growth stages of the cell culture (lag, log and stationary phase), *Escherichia*
466 *coli* DSM 2092 was grown in nutrient broth (NB, Oxoid, United Kingdom) at 28°C, 120 rpm
467 shaking in three replicates. Cultures had an initial concentration of 10⁶ cells/ml, measured with
468 a BD Accuri C6 flow cytometer (BD Biosciences), following the protocol from Van Nevel 2013.
469 The samples were incubated in the dark for 30 h at 28°C, during which optical density (OD, λ
470 = 620 nm) measurements were automatically collected each hour using a microtiter plate
471 reader (Tecan Infinite M200 Pro; Tecan UK, Reading, United Kingdom). The growth phases
472 were assigned after fitting the results with the function *SummarizeGrowth()* from the
473 'Growthcurver v0.30' R package (Sprouffske and Wagner 2016). Cells were harvested 1h,
474 7h30 and 24h after inoculation, corresponding accordingly to the lag, log and stationary phases
475 of *E.coli* (see Fig. S1). Nutrient broth was included as a negative control.

476 Sample preparation

477 Samples were measured immediately in the flow cytometer after sampling. For Raman
478 spectroscopy, samples were harvested and fixed in formaldehyde 4% (Sigma-Aldrich)
479 dissolved in PBS (protocol from Bio-Techno Ltd., Belgium) following the protocol from (García-
480 Timermans et al. 2018). First, 1mL of the cell suspension was centrifuged for 5 min at room
481 temperature and 1,957 x *g*. For the samples in the lag phase, up to 10 mL were suspended
482 until a pellet could be seen. The supernatant was discarded and cells were suspended in
483 filtered and cold PBS (4°C). The samples were again centrifuged at 1,957 x *g* for 5 min at room
484 temperature. The supernatant was discarded and the pellet was re-suspended in filtered
485 formaldehyde 4%. The cells were allowed to fix for 1h at room temperature (21°C). Then, the
486 samples were centrifuged at 1,957 x *g* for 5 min at room temperature and washed twice with
487 cold PBS (4°C). Cells were stored at 4°C and analysed in the Raman spectroscopy within the
488 week.

489 Flow cytometry

490 Fresh samples taken at the lag, log and stationary phase were diluted in filtered PBS and
491 stained with SYBR Green I 1% (Thermo Fisher) during 13 min at 37°C. They were measured
492 with the flow cytometer BD Accuri C6 (BD Biosciences). This resulted in a multivariate
493 description of each cell by four fluorescence detectors (FL1: 533/30 nm, FL2: 585/40 nm, FL3:
494 > 670 nm long pass, FL4: 675/25 nm), of which the FL1 detector was targeted by SYBR Green
495 I, and two scatter detectors (forward scatter, FSC and side scatter, SSC). The channels FSC-
496 H, SSC-H, FL1-H and FL3-H were used for data analysis.

497 Single-cell analysis

498 *t-distributed stochastic neighborhood embedding (t-SNE)*

499 t-SNE is a dimensionality reduction technique developed for the visualization of high-
500 dimensional data (Van Der Maaten and Hinton 2008). The *TSNE()* function from the scikit-
501 learn machine learning library was used (Pedregosa et al. 2011, v0.19.1). Principal component
502 analysis was set as initialization method. TSNE was run with default settings unless reported
503 otherwise. Data were first transformed by the function $f(x) = \text{asinh}(x)$, and next normalized so
504 that each channel has a mean of zero and standard deviation of one.

505 *Principal component analysis (PCA)*

506 Flow cytometric single-cell data were analysed with the *PCA()* function from the scikit-learn
507 machine learning library after normalization. Data were first transformed by the function $f(x) =$
508 $\text{asinh}(x)$, and next normalized so that each channel has a mean of zero and standard deviation
509 of one.

510 Community analysis

511 The PhenoFlow R package (Props et al., 2016) was used for the analysis. Four channels (FL1-
512 H, FL3-H, FSC-H and SSC-H) were selected to derive a phenotypic fingerprint for each
513 sample. Bacteria were gated to differentiate from background noise as shown in Fig. S2. As
514 quality control, the stability of the FL1 signal over time was checked. A 128 x 128 binning grid

515 was constructed for each pairwise combination of these channels (resulting in 6 in total). Next,
516 a bin a kernel density estimation was performed to determine the density per bin (with a
517 Gaussian kernel density bandwidth of 0.01). Then, all bins are concatenated to a one-
518 dimensional vector, representing the cytometric fingerprint. Data were normalizedtransformed
519 usingby the function $f(x) = \text{asinh}(x)$ transformation. At least 10.000 cells were measured per
520 sample.

521
522 *Principal component analysis (PCA) and principal component analysis (PCoA)*

523 The pulled information for every group was analysed with the function *fviz_pca_ind()* from the
524 R package 'factoextra' (Kassambara and Mundt 2017).

525 Principal coordinate analysis (PCoA, also known as multidimensional scaling) was calculated
526 based on the Bray-Curtis dissimilarities between all fingerprints. The function *beta_div_fcm()*
527 from the R package 'PhenoFlow' was used (Props et al. 2016).

528 Raman spectroscopy

529 Fixed samples were centrifuged at 1,957 x g for 5 min at room temperature and re-suspended
530 in cold Milli-Q water (Merck-Millipore) (4°C). Then, a 5µL drop was allowed to dry until
531 evaporation on a CaF₂ slide (grade 13 mm diameter by 0.5 mm polished disc, Crystran Ltd).
532 As control for the instrument performance, a silica gel was measured with a grating of 600 –
533 mm/g, with a 1 second time exposure and 10 accumulations. Laser power was also monitored
534 to detect possible variations. Bacteria were measured with a grating of 300 –mm/g, with a 40
535 second exposure time and 1 accumulation. More information on the Raman spectroscope and
536 data collection is included in the Raman aid (see Table 3). The metadata were collected
537 following the guidelines from (García-Timmermans et al. 2018) and can be found in the
538 Supplementary Information.

539 Raman spectra pre-processing

540 The Raman spectra were analysed in the 600-1800 cm^{-1} region, and baseline correction using
541 the SNIP algorithm (ten iterations) and normalization were performed. The area under the
542 curve (AUC) normalization was calculated with the MALDIquant package (v1.16.2) (Gibb and
543 Strimmer 2012).

544 Single-cell analysis

545 *t-distributed stochastic neighborhood embedding (t-SNE)*

546 Raman single-cell data was analyze dusing t-SNE. The *TSNE()* function from the scikit-learn
547 machine learning library was used. Principal component analysis was set as initialization
548 method. TSNE was run with default settings unless reported otherwise. Each region in the
549 spectra was normalized to have zero mean and standard deviation of one.

550 *Principal component analysis (PCA)*

551 Single-cell Raman spectra were analysed with the function *fviz_pca_ind()* from the R package
552 'factoextra' (Kassambara and Mundt 2017) or with the *PCA()* function from the scikit-learn
553 machine learning library after normalization of the spectra, so that each region has a mean of
554 zero and standard deviation of one.

555 *Hierarchical clustering*

556 To measure how dissimilar the samples were, we calculated the spectral contrast angle (Wan,
557 Vidavsky, and Gross 2002) between individual cells based on Raman spectra. Then, clusters
558 were determined in an agglomerative way, through Ward's method (*ward.D2*) from the
559 *fastcluster* R package (Müllner 2018). Hierarchical clustering was implemented using the
560 *hclust()* function from the stats package (R Core Team 2018).

561 *PhenoGraph*

562 PhenoGraph is a clustering algorithm specifically designed for the analysis of high-dimensional
563 flow- or mass-cytometry data (Levine et al. 2015). It employs a two-step approach, in which for
564 every cell its *k*-nearest cells of similar phenotypic populations are grouped together. This

565 means that, if N denotes the number of cells, N neighbourhoods are created. Next, a weighted
566 graph is created on these sets of cells. The weight between nodes scales with the number of
567 neighbours that are shared. The Louvain community detection method is implemented to
568 cluster the graph by maximizing the modularity of different groupings of the nodes (Blondel et
569 al. 2008). The PhenoGraph algorithm was run with default settings, in which k was evaluated
570 for different values between five and 100 (github.com/jacoblevine/PhenoGraph). PhenoGraph
571 was run after normalization of the spectra, to have zero mean and standard deviation of one.

572 *Adjusted Rand Index*

573 Clustering results from both hierarchical clustering and PhenoGraph were quantified by the
574 Adjusted Rand Index (ARI) (Hubert and Arabie 1985). The ARI was calculated with the
575 `adjusted_rand_score()` function from the scikit-learn machine learning library (v0.19.1)
576 (Pedregosa et al. 2011). The Rand index is defined as the number of pairs of instances that
577 are in the same group or in different groups based on two partitions, which is divided by the
578 total number of pairs of instances. This index is then corrected for the expected index, which
579 is based on random clustering in which the elements per cluster are shuffled between clusters.
580 A value of 1 resembles the perfect match between cluster assignments and ground truth labels,
581 a value of 0 resembles random clustering and a negative value (up to -1) resembles arbitrarily
582 worse clustering.

583 *Boruta variable selection*

584 The Boruta variable selection extends on traditional variable selection using Random Forest
585 based variable importance measures. The method includes shadow variables, which are
586 copies of original variables that have been permuted. By performing a Random Forest
587 analysis multiple times, one can decide by means of multiple hypothesis testing which
588 variables are relevant with a certain significance level compared to the most relevant shadow
589 variable (Kursa and Rudnicki 2010). It has been recently proposed as one of the most accurate
590 and stable variable selection methods based on Random Forest based (Degenhardt, Seifert,

591 and Szymczak 2017). The Boruta algorithm from the *Boruta* R package was run, using the
592 default settings (v6.0.0) (Kursa and Rudnicki 2010).

593 *Statistical test on Boruta outcome*

594 The ten most relevant regions for classification according to the Boruta algorithm were
595 selected. The intensity of these peaks amongst the growth phases were compared with the
596 Wilcoxon rank sum test with a Benjamini-Hochberg correction (upon rejection of the null
597 hypothesis). The functions `pairwise.wilcox.test()` and `p.adjust()` from the R package `stats` v3.5.1
598 (R Core Team 2018) were used.

599 *Data availability*

600 Data and code to reproduce analysis is available on the following repository:
601 <https://github.com/CMET-Ugent/FCMvsRaman>.

602 Data analysis was conducted using the program R (R Core Team 2018), RStudio (RStudio
603 team and RStudio 2016) and Python.

604

605 *External dataset*

606 We included the dataset from (Teng et al. 2016) in order to validate the generalizability of the
607 PhenoGraph and t-SNE algorithms for the analysis of label-free bacterial Raman data. As
608 described in their article, they tested the stress response of *E. coli* to six chemical stressors at
609 different time intervals with label-free Raman spectroscopy: ethanol, antibiotics ampicillin and
610 kanamycin, n-butanol or heavy metals Cu^{2+} (CuSO_4) and Cr^{6+} (K_2CrO_4). Teng et al. showed
611 that each of these treatments resulted in a different phenotype. In other words, each treatment
612 resulted in a unique Raman characterization of cells, which should group together upon
613 analysis. These treatments were therefore used as label according to which PhenoGraph or t-
614 SNE should group the cells. Three biological replicates of the cell culture were made, and 20
615 cells were tested per replicate. Bacteria were sampled at different stages of the cell growth.
616 The Raman spectra of the stressed cells were collected after the treatment (5, 10, 20, 30 and
617 60 min, 3h and 5h).

618 *Data availability*

619 Our code and data to reproduce the analysis is available at [https://github.com/CMET-](https://github.com/CMET-Ugent/FCMvsRaman)
620 [Ugent/FCMvsRaman](https://github.com/CMET-Ugent/FCMvsRaman).

621 **Conflicts of interest**

622 The authors declare that the research was conducted in the absence of any commercial or
623 financial relationships that could be construed as a potential conflict of interest.

624 **Author contributions**

625 CGT and PR co-wrote the paper with contributions from JH, FMK, RP, AS, WW, and NB. CGT
626 collected the data. PR, CGT and RP performed the data analysis. CGT, PR, JH, FMK, RP,
627 WW and NB designed the study. All authors read and approved the final version of the
628 manuscript.

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640

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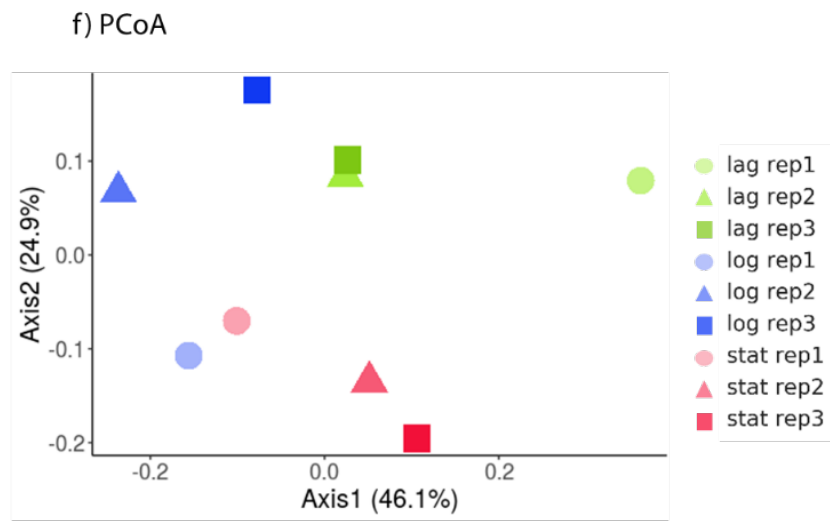
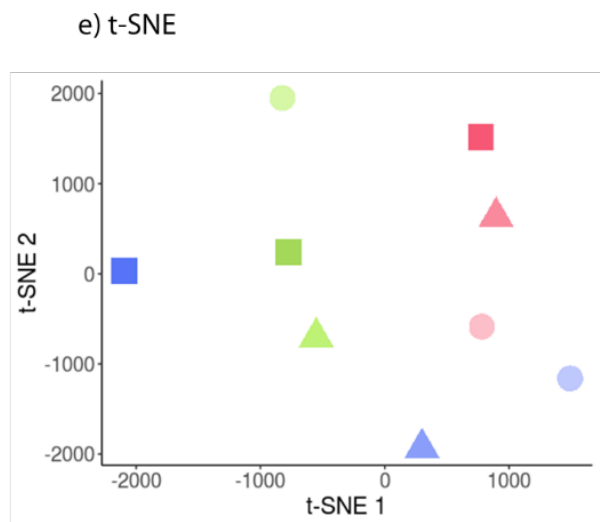
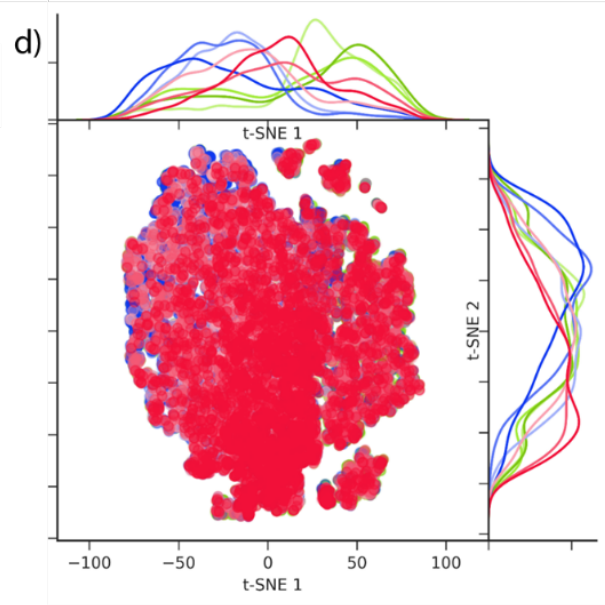
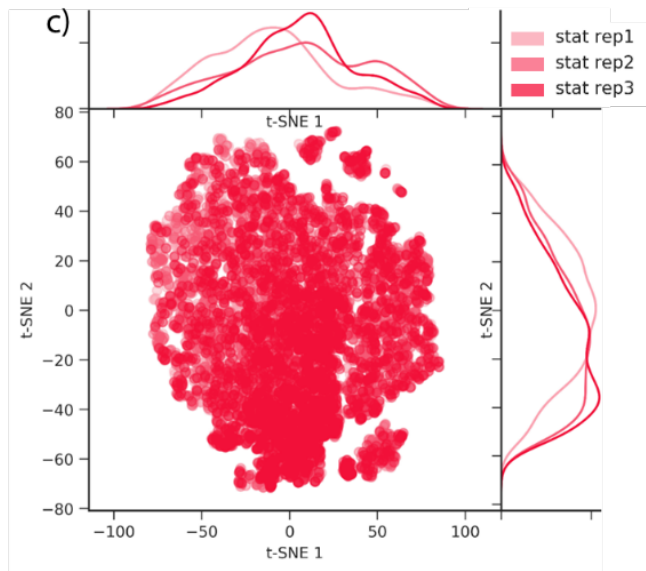
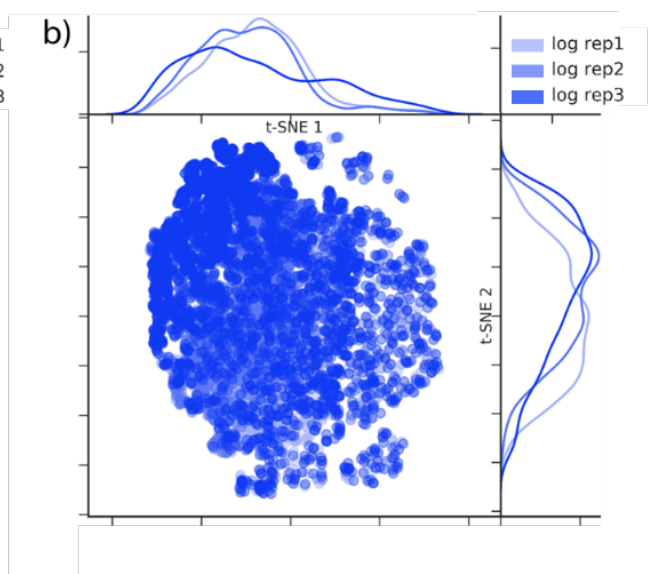
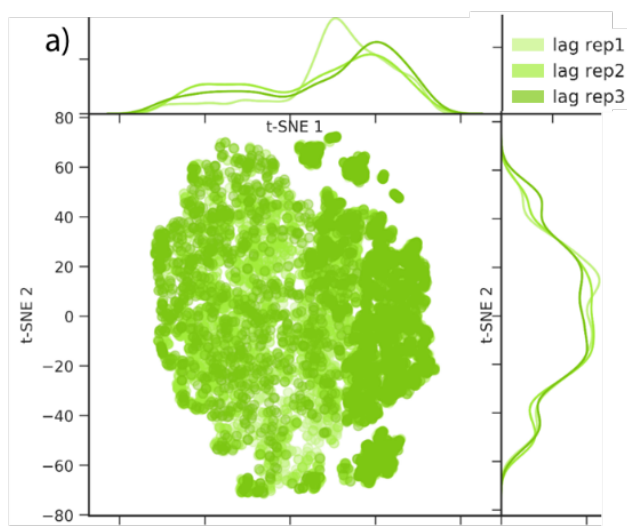
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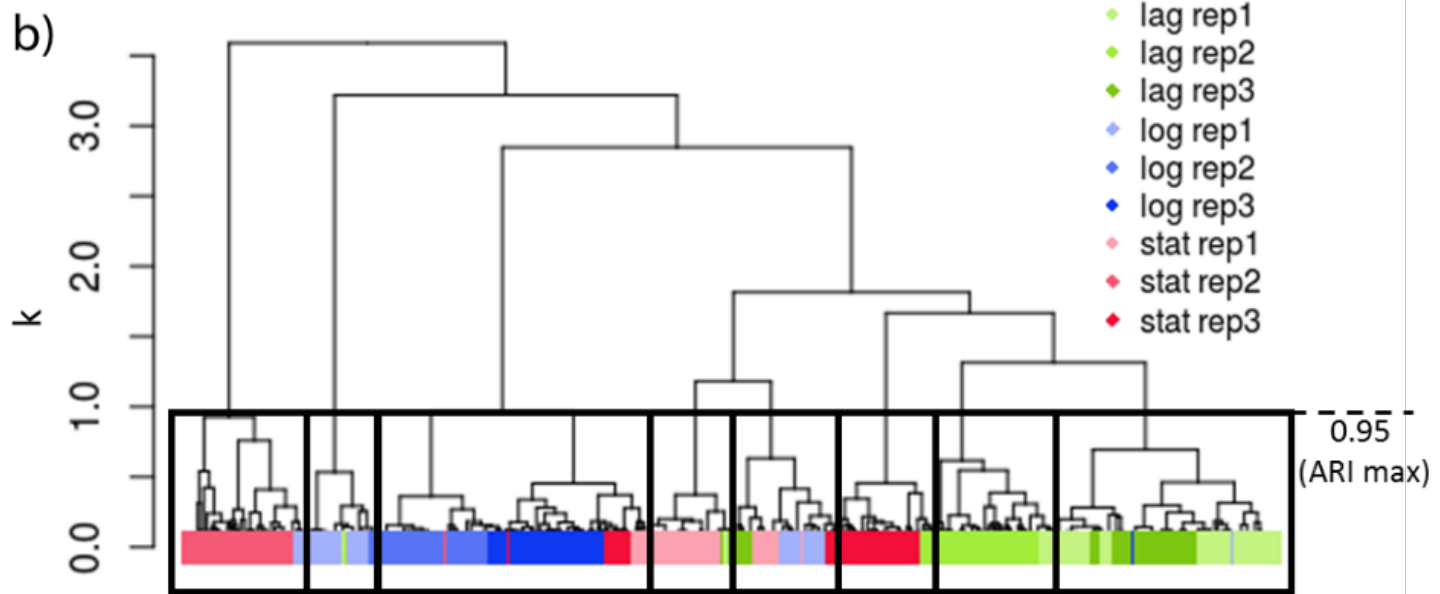
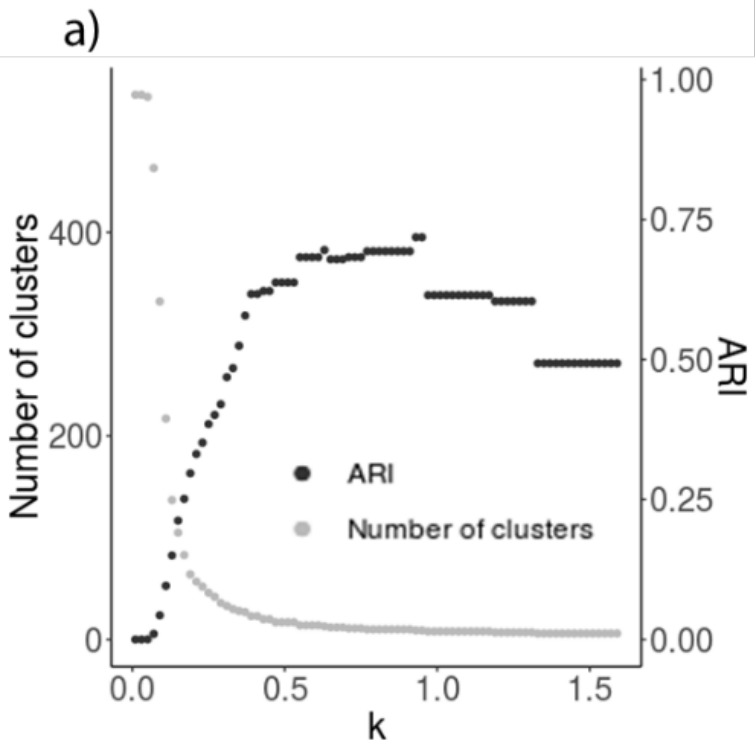
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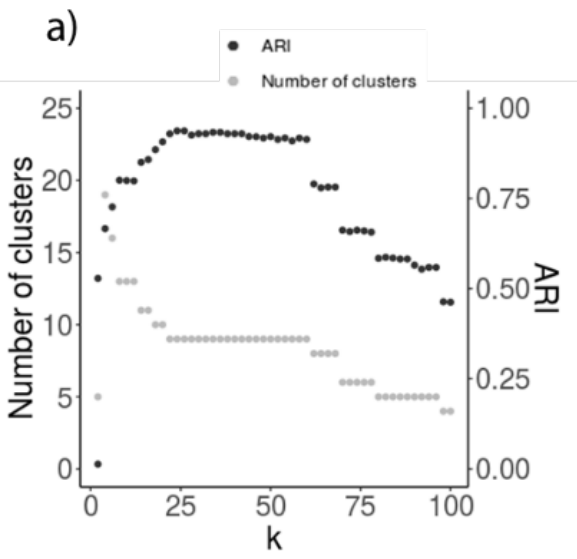
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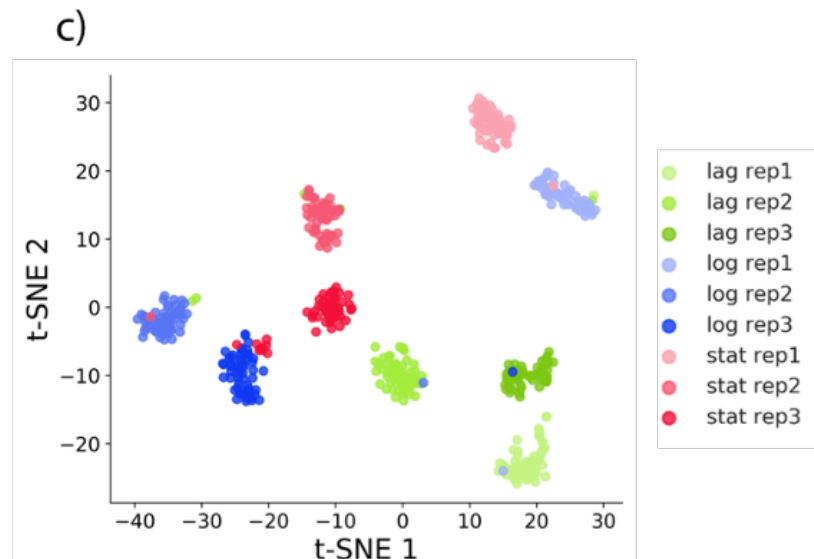
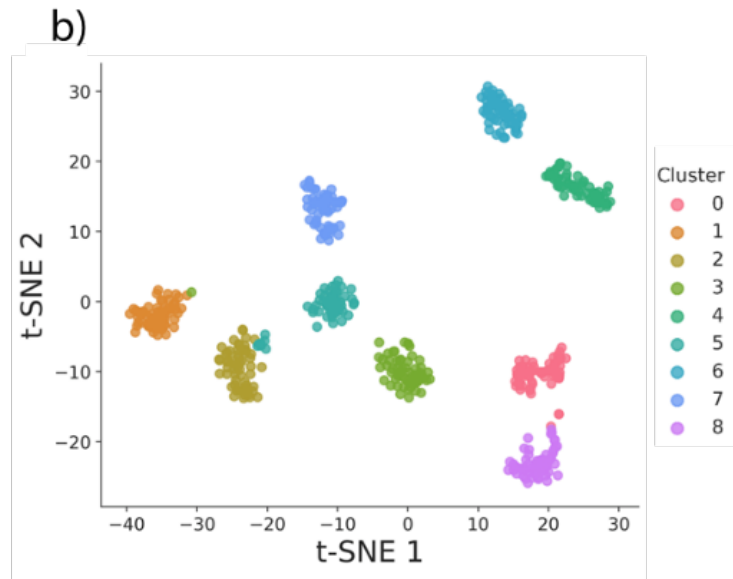
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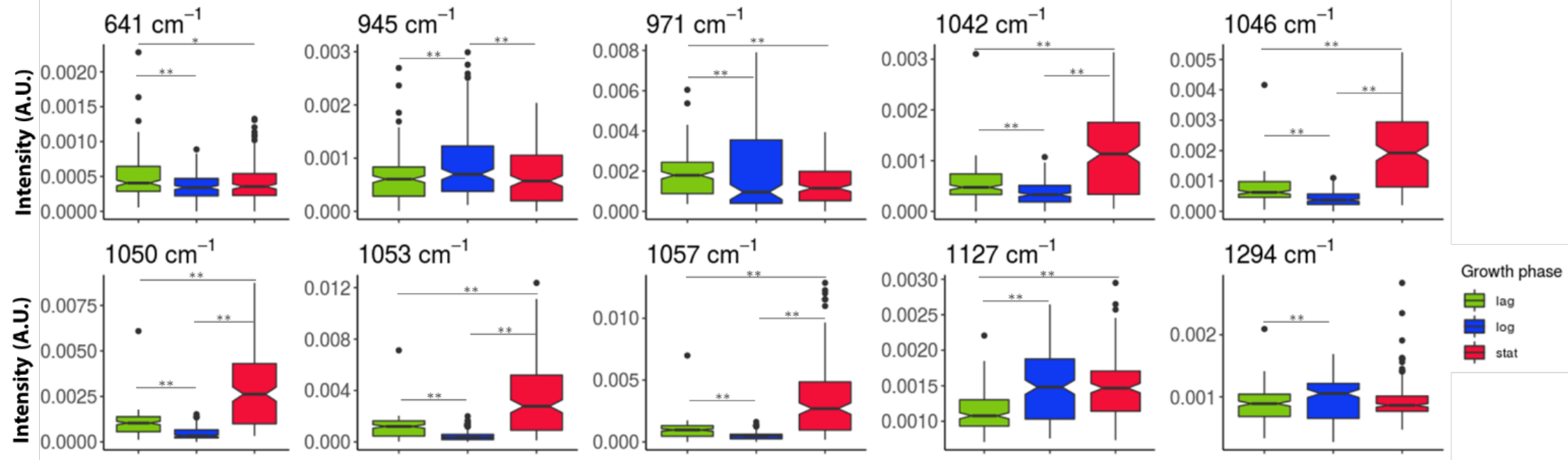


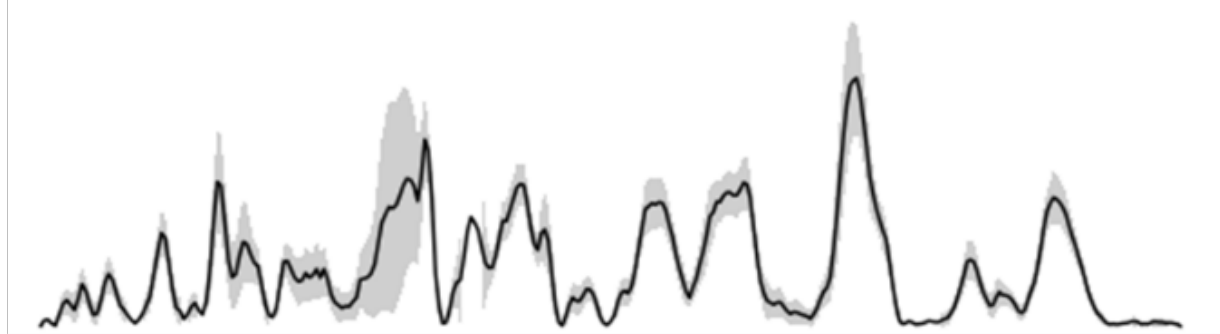


PhenoGraph automated clustering

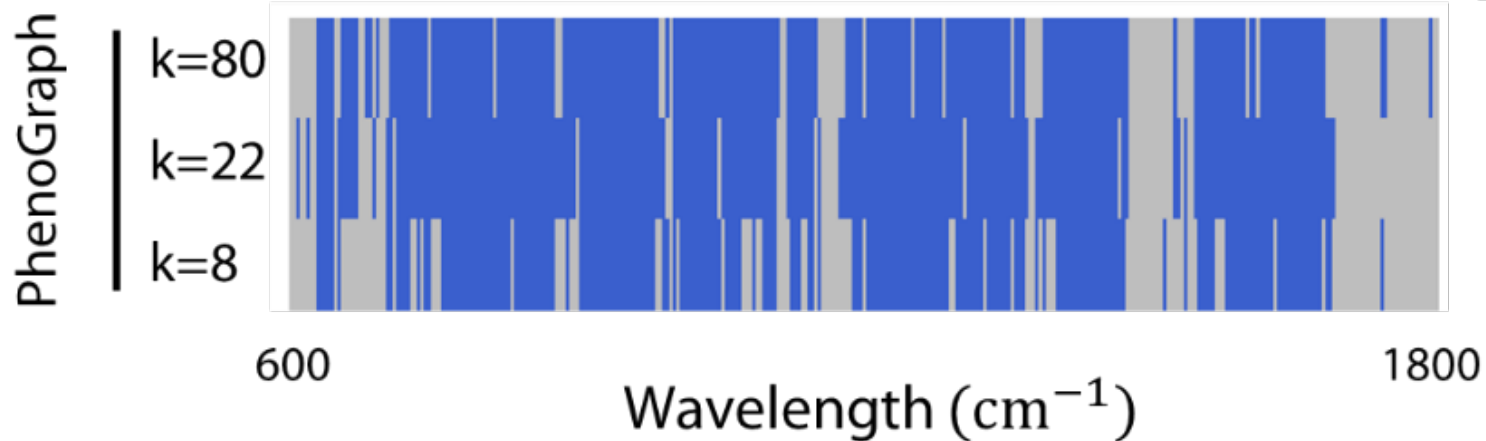


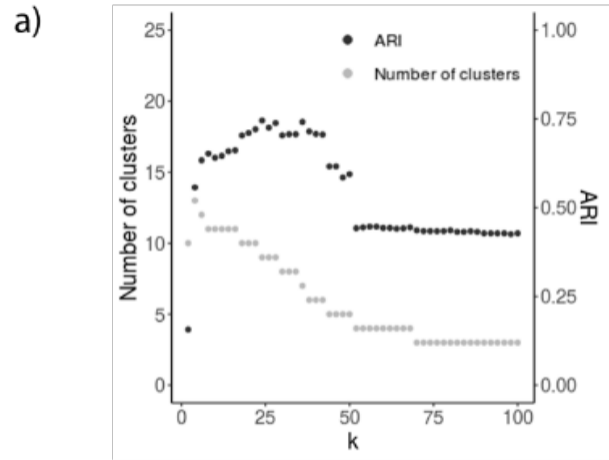
Observed clusters with t-SNE



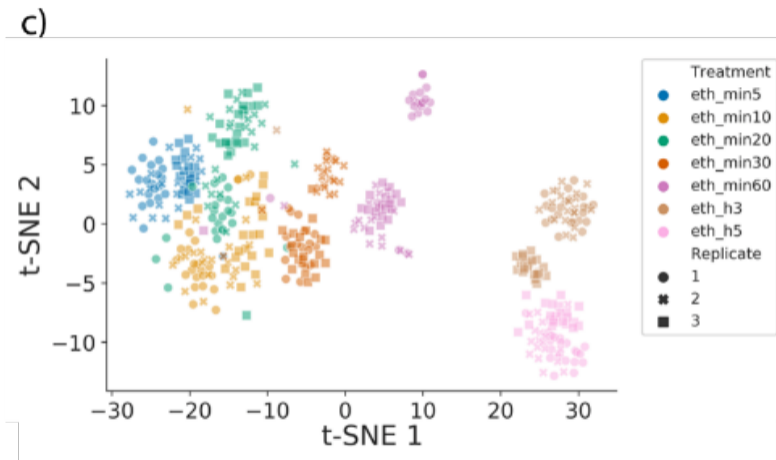
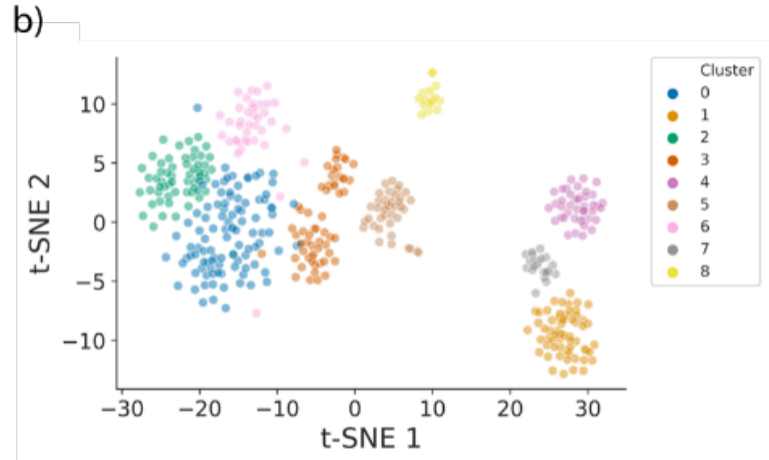


Boruta algorithm result:
■ Included
■ Rejected

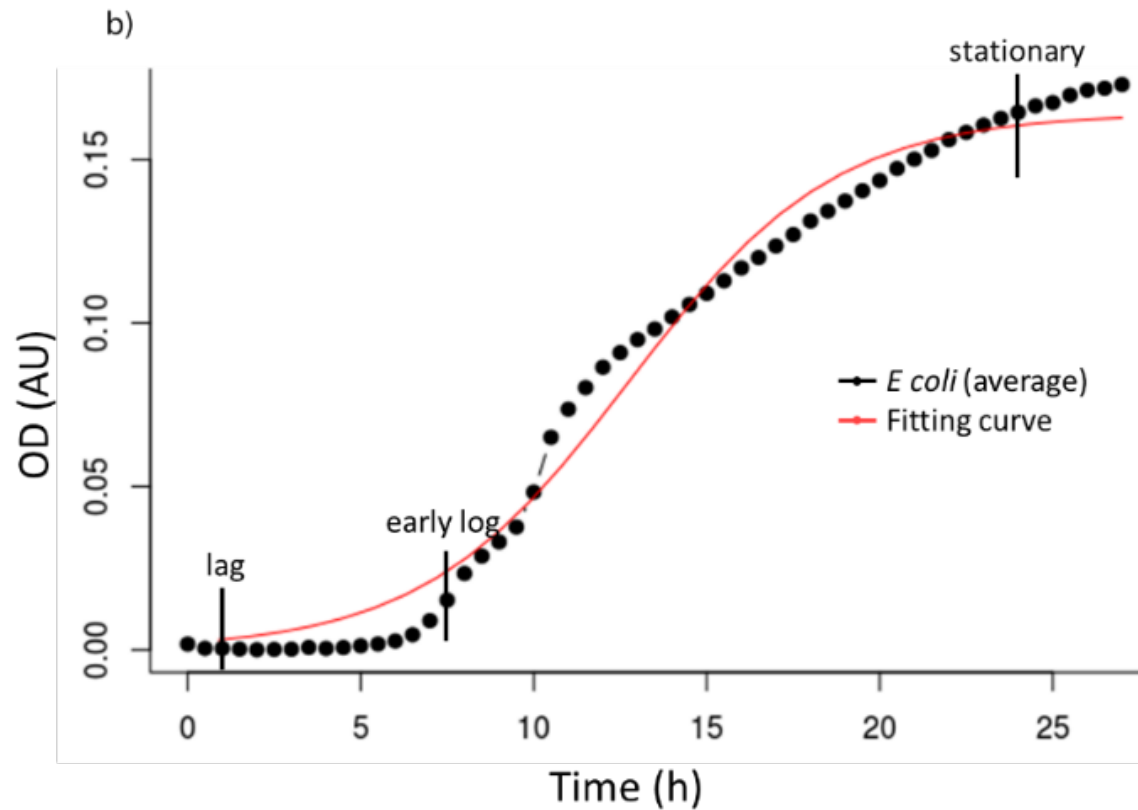
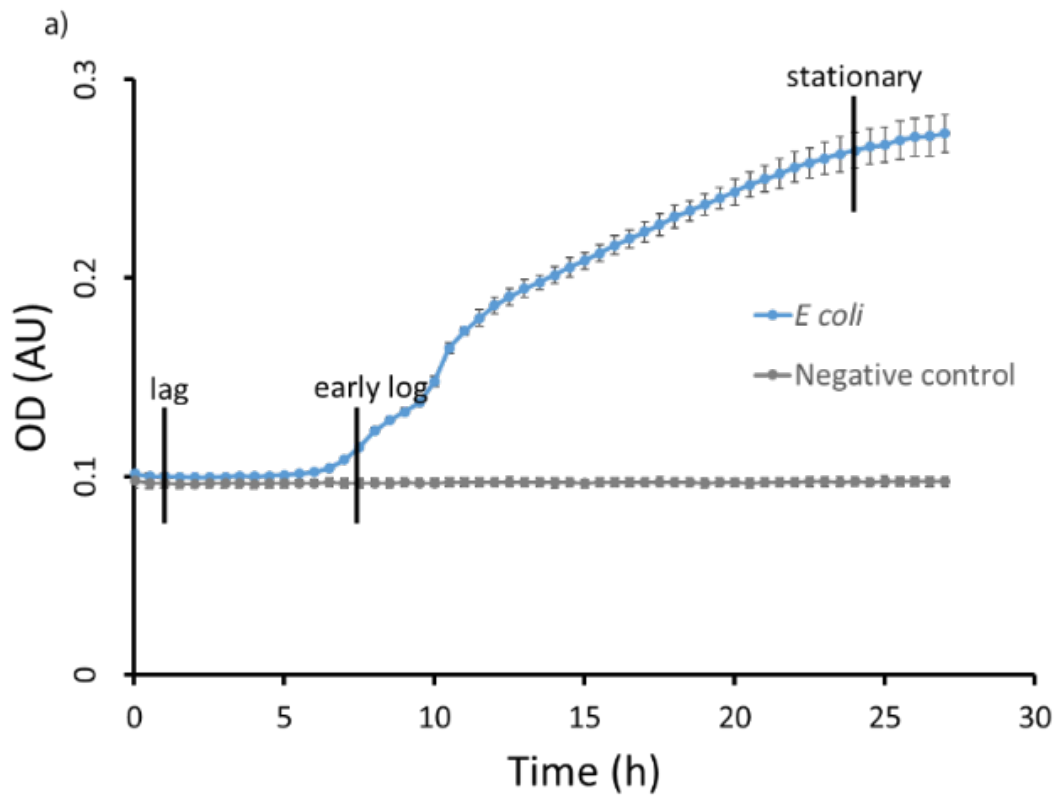




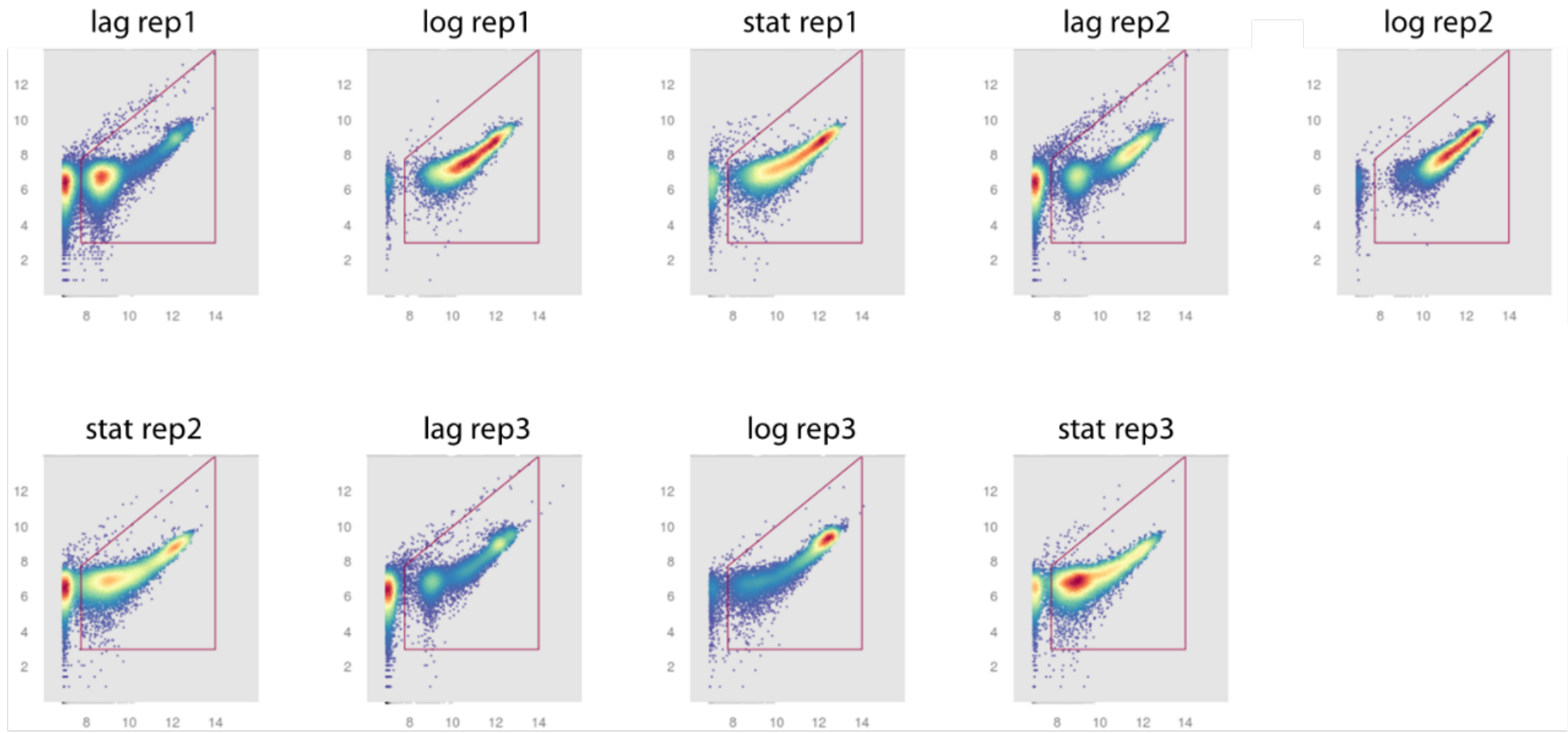
PhenoGraph automated clustering



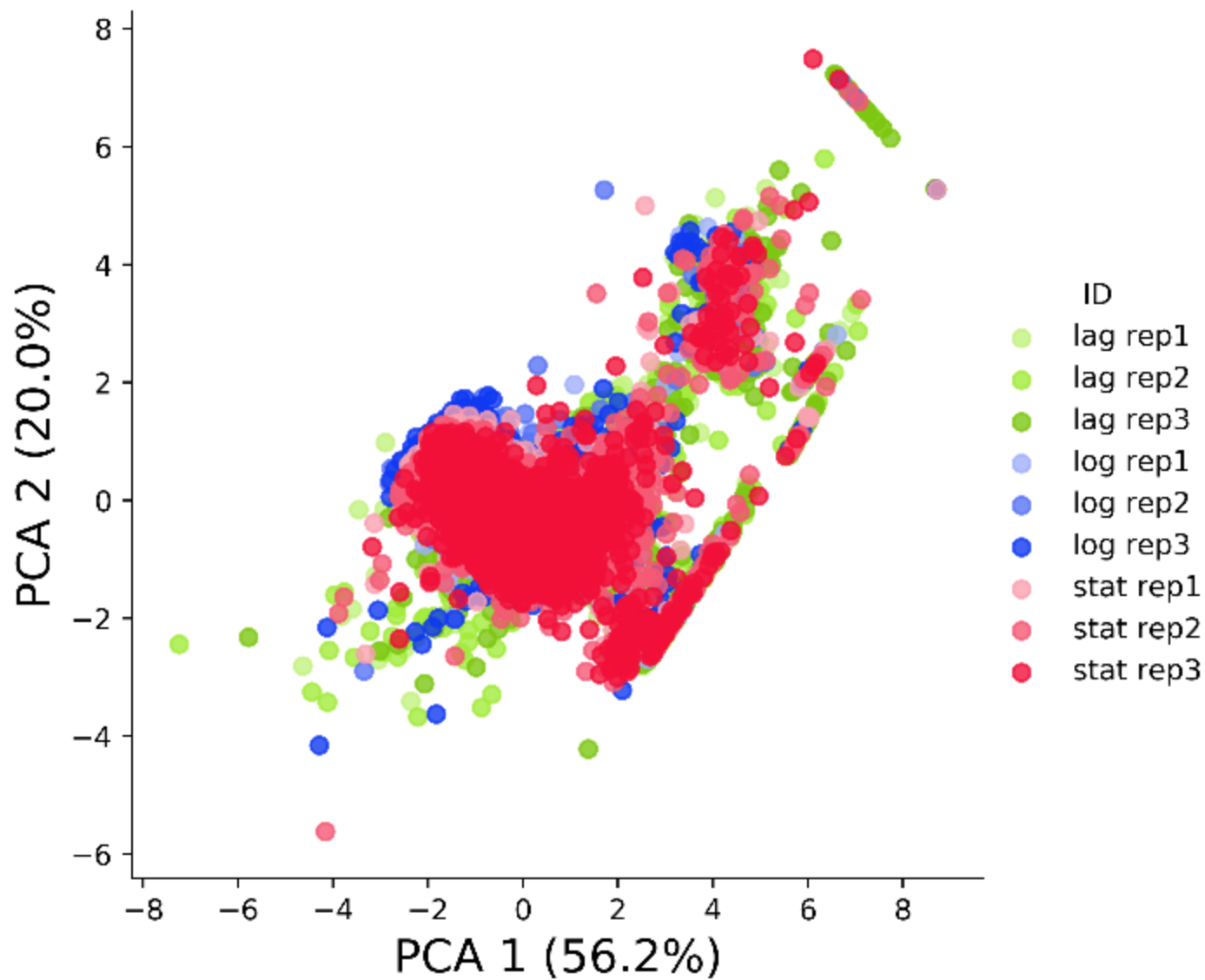
Observed clusters with t-SNE



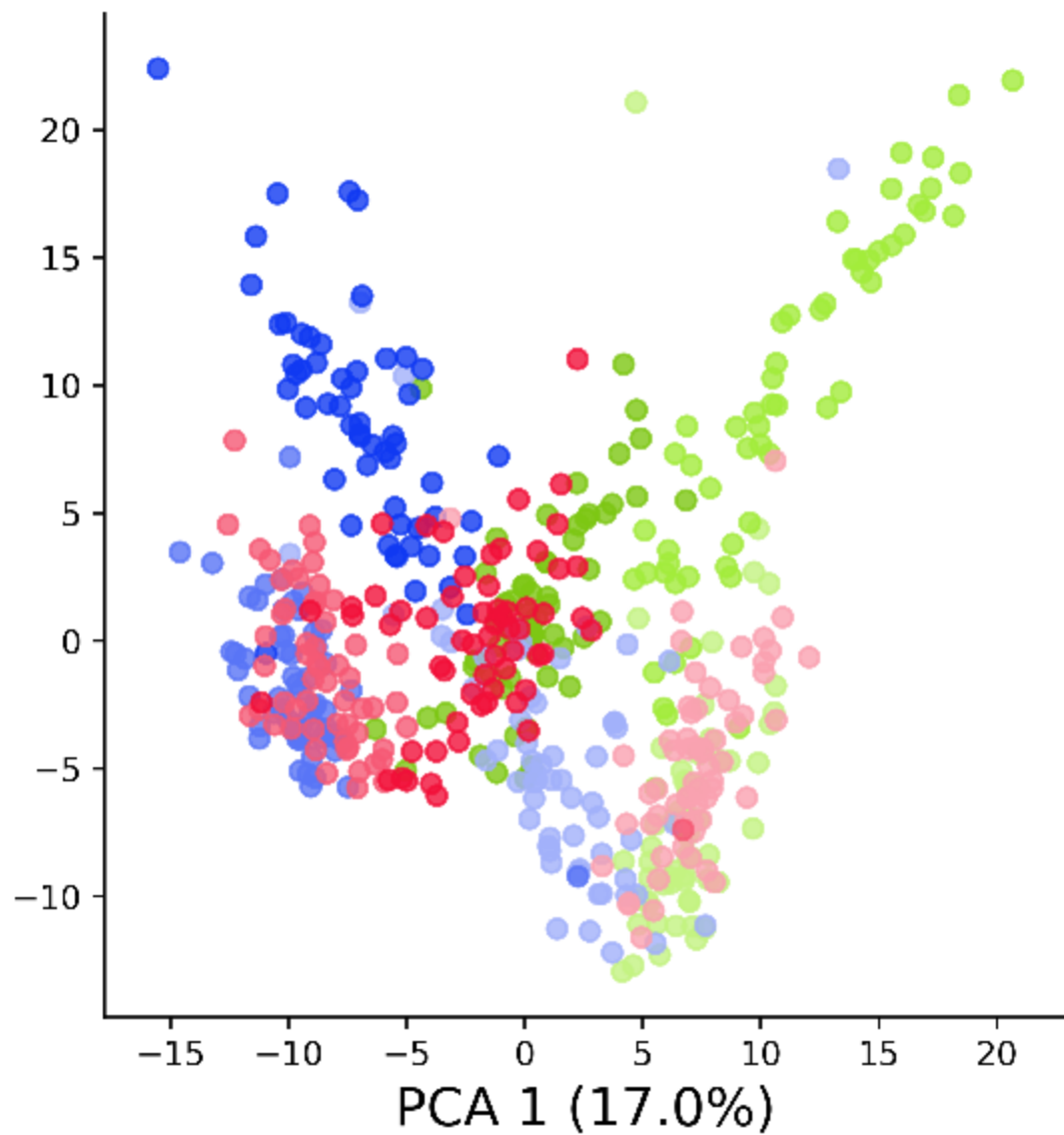
FL3-H



FL1-H



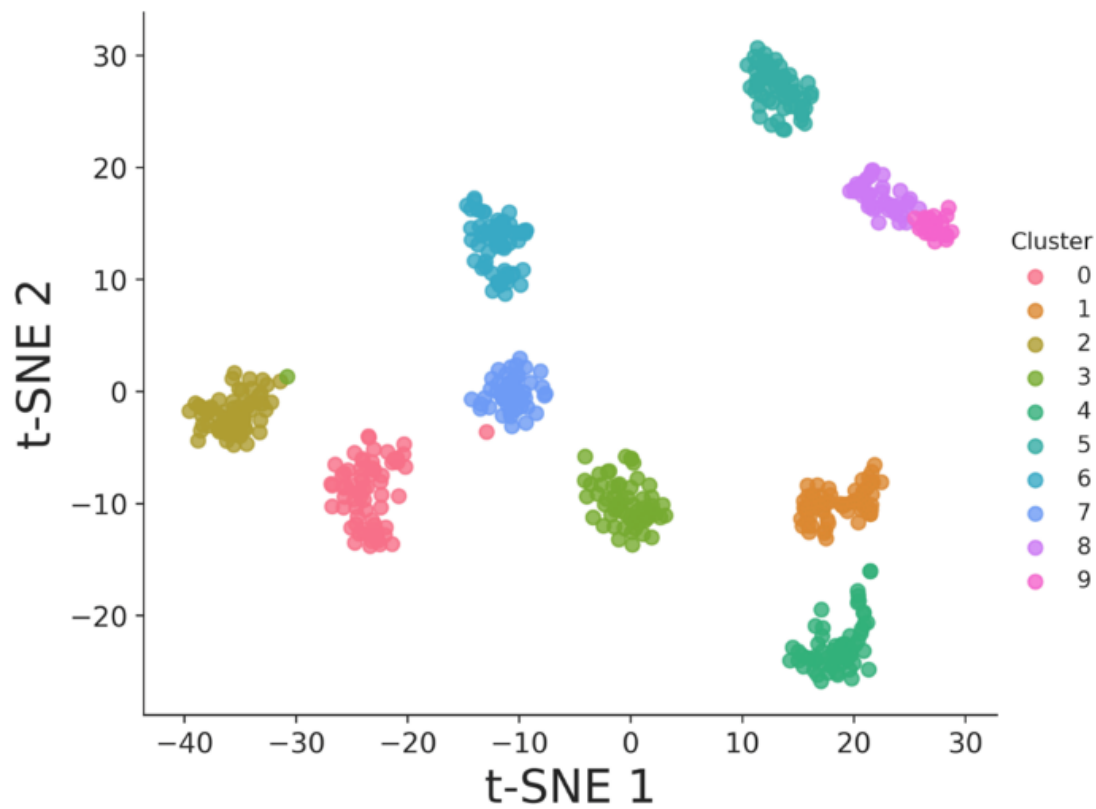
PCA 2 (14.2%)



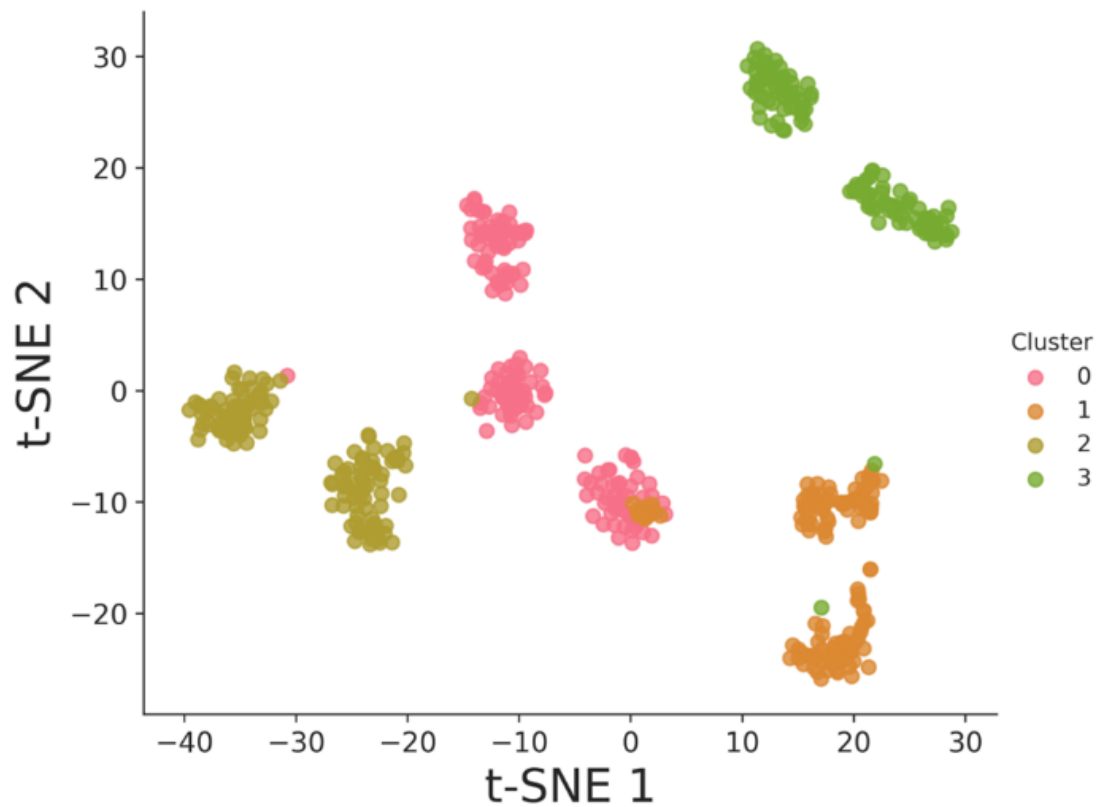
PCA 1 (17.0%)

- ID
- lag rep1
 - log rep1
 - stat rep1
 - lag rep2
 - log rep2
 - stat rep2
 - lag rep3
 - log rep3
 - stat rep3

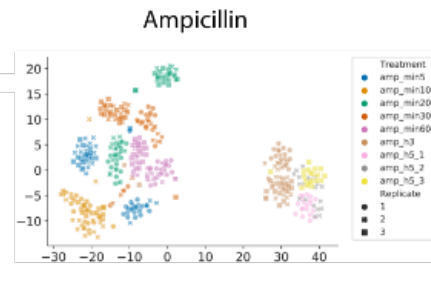
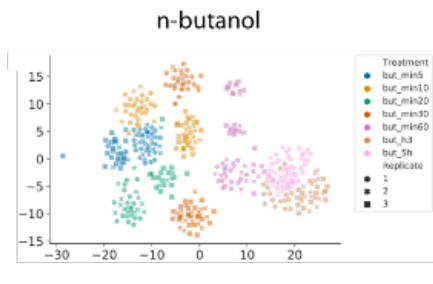
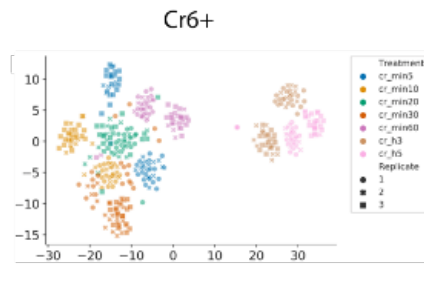
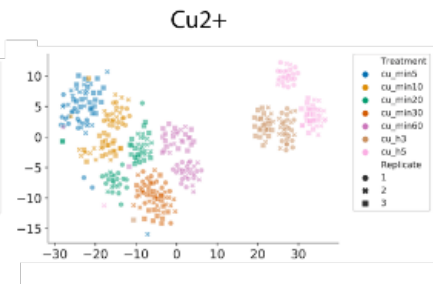
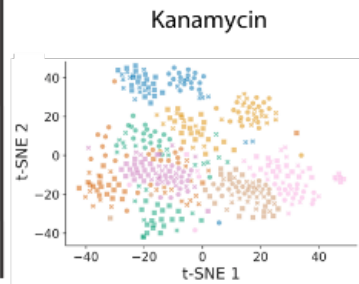
a) k=15



b) k=100



t-SNE observed groups



PhenoGraph optimal k

