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3	Using machine learning models to predict oxygen saturation following
4	ventilator support adjustment in critically ill children: a single center
5	pilot study.
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Abstract 20

21 Clinicians' experts in mechanical ventilation are not continuously at each patient's bedside in 22 an intensive care unit to adjust mechanical ventilation settings and to analyze the impact of ventilator settings adjustments on gas exchange. The development of clinical decision support 23 24 systems analyzing patients' data in real time offers an opportunity to fill this gap. The 25 objective of this study was to determine whether a machine learning predictive model could 26 be trained on a set of clinical data and used to predict hemoglobin oxygen saturation 5 min 27 after a ventilator setting change. Data of mechanically ventilated children admitted between 28 May 2015 and April 2017 were included and extracted from a high-resolution research 29 database. More than 7.10⁵ rows of data were obtained from 610 patients, discretized into 3 30 class labels. Due to data imbalance, four different data balancing process were applied and 31 two machine learning models (artificial neural network and Bootstrap aggregation of complex 32 decision trees) were trained and tested on these four different balanced datasets. The best 33 model predicted SpO₂ with accuracies of 76%, 62% and 96% for the SpO₂ class "< 84%", "85 34 to 91%" and "> 92%", respectively. This pilot study using machine learning predictive model resulted in an algorithm with good accuracy. To obtain a robust algorithm, more data are 35 36 needed, suggesting the need of multicenter pediatric intensive care high resolution databases. 37

39 Introduction

40 In case of respiratory failure, mechanical ventilation supports the oxygen (O₂) diffusion into 41 the lungs and the carbon dioxide (CO_2) body removal. As an expert in mechanical ventilation cannot reasonably be expected to be continuously present at the patient's bedside, specific 42 medical devices aimed to help in ventilator settings adjustments may help to improve the 43 44 quality of care. Such devices are developed using either algorithms based on respiratory 45 physiology/medical knowledge that adapt ventilator settings in real time based on patients' characteristics but are not accurate enough to be used widely in clinical practice, especially in 46 47 children [1, 2]; or physiologic models that simulate cardiorespiratory responses to mechanical 48 ventilation settings modifications but none was validated for this indication [3]. The above-49 mentioned models all share the limitation of not being suited to learn from ever-growing sets 50 of clinical research data, and potentially improve their performances. To overcome this 51 drawback, another avenue is the development of algorithms using artificial Intelligence to 52 provide caregivers with support in their decision-making tasks. In this study, we assessed 53 machine learning methods to predict transcutaneous hemoglobin saturation oxygen (SpO₂) of mechanically ventilated children after a ventilator setting change using a high resolution 54 55 research database.

56

57 Materials and Methods

58 This study was conducted at Sainte-Justine Hospital and included the data collected

59 prospectively between May 2015 and April 2017 of all the children, age under 18 years old,

60 admitted to the Pediatric Intensive Care Unit (PICU) who were mechanically ventilated with

an endotracheal tube. Patients' data were excluded if the patient was hemodynamically

62 unstable defined as 2 or more vasoactive drugs delivered at the same time (ie., epinephrine,

	63	norepinephrine,	dopamine or vas	opressin) or with an u	incorrected cyanotic	heart disease
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64 defined by no $SpO_2 > 97\%$ during all PICU stay. All the respiratory data from included

65 patients were extracted from the PICU research database [4], after study approval by the

- 66 ethical review board of Sainte-Justine hospital (number 2017 1480).
- 67

68 Data extraction

- 69 To determine the data that will be extracted for each child, an item generation was
- 70 conducted by three physicians (PJ, MS, DB). The resulting items are presented in Fig 1 within
- 71 their sources, means of extraction and a schematic of the main components of the study.
- The predictive SpO₂ value was the SpO₂ 5 minutes after a change of a ventilator setting. The
- 73 delay of 5 min corresponded to the shortest period of time to reach a steady state after
- 74 modification of a ventilator setting [5].

75 Fig 1. Schematic description of the analysis process and items involved. EMR: electronic Medical Record, FiO₂: inspired fraction of Oxygen, Vt: tidal volume, PEEP: 76 77 Positive end expiratory pressure, PS above PEEP: pressure support level Above 78 PEEP, PC above PEEP: pressure control level above PEEP, MVe: expiratory 79 minute volume, I:E Ratio: inspiratory time over expiratory time, Measured RR: 80 respiratory rate measured by the ventilator, PIP: positive inspiratory pressure ie 81 maximal pressure measured during inspiration. 5minSpO2: SpO2 observed 5 min 82 after PEEP, FiO₂, tidal volume, PS above PEEP, PC above PEEP change, ML: 83 machine learning, ANN: artificial neural network, BACDT: Bootstrap aggregation 84 complex decision trees. 85

86 Data formatting

87 The data extracted from the research database needed: (1) to remove erroneous da

- 88 disconnection of the patient from the ventilator or the monitor, or due to transient
- 89 interventions such as suctioning; (2) to remove the rows at which no ventilator setting
- 90 variables was modified; (3) to adapt data format for classifier training. The methodology to
- 91 format the data is described in S1 file.
- 92

93 Data categorization

- 94 SpO₂ levels at 5min were classified into three categories (Table 1). The thresholds were
- 95 selected according to clinical value: a $SpO_2 < 92\%$ is a target to increase oxygenation in
- 96 mechanically ventilated children [6]. The critical level of 85% SpO₂ is used as an alarm of
- 97 severe hypoxemia in intensive care [7].
- 98

99 Table 1: Definition of SpO₂ class labels specifications

SpO ₂ classification	SpO ₂ range	Rows number
	(%)	(n)
1	< 84	17,112
2	85 to 91	29,869
3	92 to 100	729,746

100

101 Data balancing

102	The data analysis showed a severe imbalance with most SpO_2 at 5min above 92%. This is
103	logical as caregivers want to maintain SpO_2 in normal range during child PICU stay. In such
104	condition, the classifier learns the majority class label (class 3) (Table 1) but doesn't learn the
105	minority class labels (class 1 and 2) [8]. The data balancing process aims to allow the

106 classifier to learn from all class equally. The data balancing process used in this study

107 included a combination of down-sampling and up-sampling techniques: to balance the three

108 classes of the data involved, a down-sampling of the SpO₂ class 3 using TOMEK algorithm [9]

and an over-sampling of SpO₂ class 1 and 2 using Synthetic Minority Oversampling

110 Technique (SMOTE) [10] were performed.

111 The creation of synthetic data points by SMOTE can be formulated as follows:

112

 $x_{syn} = x_i + (x_{knn} - x_i) \times \delta$ ⁽²⁾

In equation (2), x_{syn} represents the synthetic data point. The variables x_i and x_{knn} are respectively the original instance, and the nearest neighbor data point which is randomly picked among the *k* nearest neighbors.. The random number δ is generated in [0,1] to determine the position of the created synthetic data point along a straight line joining the original data point x_i and its chosen nearest neighbor x_{knn} .

118 To study which data balancing method provided the more accurate algorithm, four datasets

119 were produced via four different balancing procedures, involving different combinations of

120 data balancing techniques (Fig 2).

121 Fig 2. Descriptions of the four balancing procedures.

122

123 Predicted SpO₂ Classification

124 To identify the best machine learning classification method, we tested two classification

125 models: artificial neural network and bagged complex decision trees, on the four balanced

126 datasets.

127 Artificial Neural Network (ANN)

128 Once the data has been pre-processed, a machine learning predictive model was trained on a 129 sub-set of labeled training data. The model is then used to predict the target variable values on

130 a testing subset where the class labels are hidden. We used Artificial Neural Networks 131 (ANN) to make predictions of the SpO_2 variable, based on the values of other variables of 132 interest. Through the function approximation that the ANN performs, it is possible to make 133 predictions of SpO_2 variable, based on the input data.

134

The ANN is learned from training data, using the backpropagation algorithm [11] and is tested on a test set made of the remaining rows of data to validate the generalization of the model. The learning algorithm runs through all the rows of data in the training data set and compares the predicted outputs with the target outputs found in the training data set. The weights are adjusted via supervised learning, in a manner to minimize the error of predicted SpO₂ vs target SpO₂. The process is repeated until the error is minimized.

141

The ANN classifier was implemented through cycles of forward propagation followed by
backward propagation through the network's layers. The backpropagation algorithm is used
for performance optimization.

For a given number of classes K > 2, the cross-entropy error can be formulated as shown in eq. 3, where $(W_i)_i$ is the matrix of weights between the neuron layers, r_i is the target value. y_i is the value generated by the ANN, i.e., its output.

148
$$E'((W_i)_i | x^t, r^t) = -\sum_i r_i^t \log y_i^t$$
(3)

149 The outputs of the ANN are:

150
$$y_i^t = \frac{exp \, w_i^t x^i}{\sum_k exp \, w_k^t x^t} \tag{4}$$

Using stochastic gradient-descent (SGD) for error minimization, the update rule for the ANNweights is:

153
$$\Delta w_{ij}^t = n(r_i^t - y_i^t)x_j^t \tag{5}$$

In equation 5, η is the learning rate, which, when SGD is used, decreases as the error is minimized. During ANN training, each observation, comprised of an input vector and a target output, is denoted (x^t , r^t), with $r^t \in ("1", "2", "3")$. The reason why the cross-entropy (eq. 3) is used instead of the Least Square Error (LSE) is to avoid long periods of training, due to the ANN going through stages of slow error reduction.

159

160 Bootstrap aggregation of complex decision trees

161 Bootstrap aggregating (acronym: bagging) was proposed by L Breiman in 1994 to improve 162 classification by combining classifications of randomly generated training sets [12]. Bagging 163 allows for the creation of an aggregated predictor via the use of multiple training sub-sets 164 taken from the same training set. Let (T^{i}) denote the replicate training sub-sets bootstrapped 165 from the training set T. These replicate sub-sets each contain N observations, drawn at 166 random and with replacement from T. For each of these sub-sets of N observations, a 167 prediction model, or classifier, is created. The computational model we used for bagging was 168 complex decision trees. This means that, for each bootstrapped sub-set of training data, a 169 complex decision tree is trained and thus a classifier is created. If i = 1, ..., n, then n 170 classifiers are created through the bagging process.

171

A decision tree is a flowchart computational model which can be used for both regression, as well as classification problems. Paths from the root of the tree to its various leaf nodes go through decision nodes in which decision rules are applied in a recursive manner, based on values of input variables. Each path represents an observation $(X, y) = (x_1, x_2, x_3, ..., x_n, y)$, where the label assigned to the target *y* is given in the leaf node, at the end of the path, ie., classification [13].

179	In the aim of maximizing the model's generalization capability during the training process,
180	the Bagged Complex Trees' performance is tested via k -fold cross-validation. A value $k = 10$,
181	which is common practice, was used in this study. The training using k -fold cross-validation
182	is carried out as described in Fig 3.
183	Fig 3. <i>k</i> -fold cross-validation
184	
185	The mathworks Matlab R2016b Machine Learning toolbox was used for the creation of the
186	ensemble of Bagged complex trees model.
187 188	Assessment of the performances of the classifiers
189	We evaluated the performances of the classifiers based on the metrics including testing
190	confusion matrix, average accuracy, precision, recall and F score [14] with a $_{5min}SpO_2$
191	prediction expected above 0.9 for each class.
192	
193•	Precision
194	$Precision = \frac{\# True \ positives \ class \ i}{Total \ \# \ classifications \ for \ class \ i} $ (6)
195	The <i>Precision</i> (eq. 6) is the ratio of all correct classifications for class <i>i</i> to all instances labeled
196	as class label i by the model. In a non-normalized confusion matrix, this would mean
197	dividing the number of instances classified in class label <i>i</i> by the total of instances in column
198	<i>i</i> .
199	
200=	Recall
201	$Recall = \frac{\# True \ positives \ class \ i}{Total \ \# \ observations \ class \ i} \tag{7}$

- 202 Recall is the ratio of the number of instances classified in class label *i* to the number of true
- 203 class *i* labels. In a non-normalized matrix, this would require dividing the number of
- 204 instances classified in class label *i* by the total of row *i*
- 205
- 206• F-score
- 207 $F score = \frac{2}{\frac{1}{recall} + \frac{1}{precision}}$ (8)
- 208 The F-score provides a single measure of classification performance of the model used.
- 209
- 210 Results and discussion

211 We developed and assessed the performances of two machine learning classifiers on four 212 different balanced datasets to predict SpO_2 at 5 min after a ventilator setting change (*ie* FiO₂, 213 PEEP, Vt/Pressure), in 610 mechanically ventilated children. In Fig 4 and Table 2, we report 214 the performances of these two classifiers. Using the classification performance metrics, the 215 bagged trees classifier trained on dataset #3 (see Fig 2) has yielded the best classification 216 performance on the test sets (Table 2). The confusion matrix of the whole bagged trees shows that SpO₂ at 5 min could correctly predict in 76% of class "1" data, 62% of class "2", 217 218 and 96% of class "3" (Fig 4). This huge variation in classification performances of the three 219 class labels can be explained by the large variation in the numbers of observations available 220 for each of the class labels in the initial dataset that has limited the machine learning (Table 221 1).

222

Fig 4. Artificial neural network (ANN) and bootstrap aggregation of complex decision trees (BACDT) test confusion matrices. The darker colors represent higher levels of accuracy. A:

balanced dataset 1, B: balanced dataset 2, C: balanced dataset 3, D: balanced dataset 4 (see
Fig 2).

227

Table 2. Performance of artificial neural networks (ANN) and bootstrap aggregation of complex decision trees (BACDT) classifiers for SpO₂ prediction at 5 min following a ventilator setting change. Avg/total: average accuracy of total classification values. In italics is the performance of the best predictive model obtained among the eight tested.

232

Balanced	5minSpO2		ANN		B	ACDT	
datasets	class	Precision	Recall	F-	Precision	Recall	F-
				score			score
	1	0.12	0.70	0.21	0.80	0.76	0.78
	2	0.16	0.43	0.23	0.61	0.56	0.59
Dataset 1	3	0.96	0.67	0.79	0.97	0.98	0.97
	Avg/total	0.88	0.65	0.73	0.94	0.94	0.94
	1	0.09	0.72	0.16	0.77	0.72	0.74
	2	0.09	0.47	0.16	0.57	0.53	0.55
Dataset 2	3	0.98	0.70	0.81	0.98	0.99	0.98
	Avg/total	0.93	0.69	0.78	0.96	0.97	0.97
	1	0.16	0.68	0.25	0.80	0.76	0.78
	2	0.26	0.42	0.33	0.67	0.62	0.65
Dataset 3	3	0.92	0.60	0.72	0.95	0.96	0.96
	Avg/total	0.80	0.58	0.65	0.91	0.91	0.91
	1	0.09	0.69	0.16	0.80	0.74	0.77
	2	0.12	0.47	0.19	0.58	0.54	0.56
Dataset 4	3	0.97	0.68	0.80	0.98	0.98	0.98
	Avg/total	0.92	0.67	0.76	0.96	0.96	0.96

233

234 For the artificial neural network, the variation of the number of hidden layers and number of

235 neurons per hidden layer did not seem to have a significant effect on the model's

236 classification performance (Table 3). As for the Bagged complex trees, the variation of the

237 number of complex trees did not yield significant changes in classification performance

238 (Table 4).

239

Table 3. Absence of impact on performance of the increase of neurons and hidden layers
 for artificial neural network (ANN). Example of the performance assessed by the F score on
 the balanced dataset 3 (see fig 2)

243

244

			A	ANN						
Hidden layers (n) Neurons/hidden layer (n)		1		2		3				
		10	50	100	10	50	100	10	50	100
	_{5min} SpO ₂ class 1	25	25	25	25	25	25	22	22	19
F-score	_{5min} SpO ₂ class 2	33	33	33	33	33	33	33	33	32
	_{5min} SpO ₂ class 3	72	72	72	72	72	72	69	69	69

245

246Table 4. Absence of impact on performance of the number of complex trees for bootstrap247aggregation of complex decision trees (BACDT). Example of the performance assessed by

- 248 the F score on the balanced dataset 3 (see Fig 2)
- 249

		BACDT		
		n = 30	n=50	
	5minSpO2 class 1	78	78	
F-score	5minSpO2 class 2	65	65	
	5minSpO2 class 3	96	96	

250

251 In agreement with previous studies regarding bagging being a better method for medical 252 data classification, tree Bagging fared better than the artificial neural network used in this 253 study [12]. It is noteworthy however that the gaps in performance results between the 254 training and testing confusion matrices are relatively higher in the case of bagged trees 255 model than in that of the artificial neural network (Fig 5). This seems to indicate that, 256 although the bagged trees model was capable of learning very well from the data, there's 257 still room for improvement in the generalization. The SMOTE algorithm is designed in such a 258 way that should theoretically not affect the generalization of the trained model. In cases of 259 extreme data imbalance, however, as is the case in this study, the over-sampling within the 260 data space of a given minority class label, used for increasing the cardinality of the class 261 label's set, is also likely to be extreme. This may render the data space of this class relatively 262 dense with respect to the rest of the data, made up of real data points of the studied patient 263 sub-population. This may potentially explain the classification model's relatively poor

264	generalization for $_{5min}$ SpO ₂ class "1" and "2" with respect to the generalization for $_{5min}$ SpO ₂
265	class "3". Also, since SMOTE generates synthetic data points by interpolating between
266	existing minority class instances, it can obviously increase the risk of over-fitting when
267	classifying minority class labels, since it may duplicate minority class instances. The fact that
268	the training confusion matrix shows extremely high classification performances for the
269	minority $_{5min}$ SpO ₂ class "1" and "2", as opposed to those shown in the testing confusion
270	matrix, suggests that the over-sampling of the minority $_{5min}$ SpO $_2$ class using SMOTE could
271	have caused some overfitting for these classes, but this would have to be further
272	investigated.
273	
274 275 276	Fig 5. Training and testing confusion matrices of artificial neural networks (ANN) and bootstrap aggregation of complex decision trees (BACDT) classifiers for SpO ₂ prediction at 5 min following a ventilator setting change.
277	
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289 developing algorithms domains, such as transport or finance, data are specifically collected 290 for research purposes. This is not the case in healthcare where the primary objective of data 291 collection systems is to document clinical activity, resulting in several issues to address in 292 data collection, data validation and complex data analysis [17]. As detailed in S1 file, a 293 significant amount of effort is needed, when data have been successfully archived and 294 retrieved, to transform the data into a usable format for research. 295 This study has several limitations. The limited row number reduced the SpO₂ classification 296 for machine learning predictive model to three clinically relevant classes. SpO_2 is a 297 continuous variable and the use of three class is probably insufficient, especially when high 298 SpO₂ range is suggested as potentially harmful [18, 19]. Instead of the classification model, 299 the next step could be to test regression models' performance. SpO₂ was predicted at 5min 300 after ventilator setting change, a clinically relevant delay. However, the delay between 301 ventilator setting change and oxygenation steady state is not well defined and vary from 1 to 302 71 minutes according to the parameter set (FiO₂, PEEP or other parameters that change 303 mean airway pressure) and clinical conditions studied [15, 20, 21]. This needs further 304 research and probably more sophisticated clinical decision support systems using machine 305 learning predictive models should consider these factors. Finally, we excluded hemodynamic 306 unstable patients using a treatment criteria (≥ 2 vasoactive drugs infused) because this 307 condition decreases pulse oximeter reliability [22, 23]. The validation and electronic 308 availability of reliable markers of hemodynamic instability in children such as 309 plethysmographic variability indices could be helpful [24]. 310

311 Conclusion

312	This pilot study using machine learning predictive model resulted in an algorithm with good
313	accuracy. To obtain a robust algorithm with such a method, more data rows are needed,
314	suggesting the need of multicenter pediatric intensive care high resolution databases.
315	
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322	
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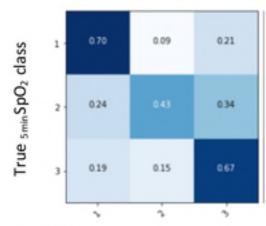
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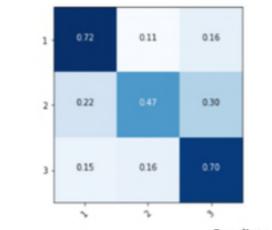
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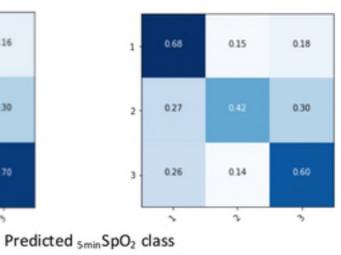
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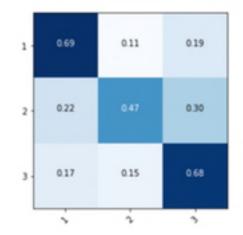
- 388 Supporting information
- 389
- **390 S1 File: Data formatting process**

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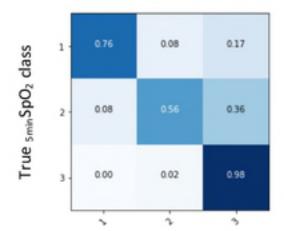




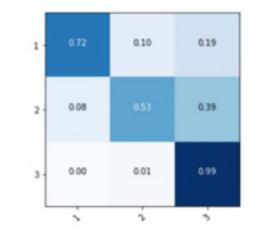




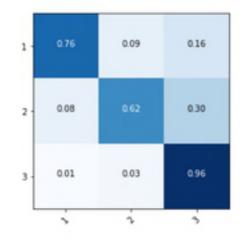
BACDT

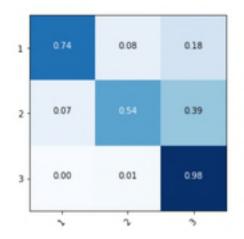


А



В







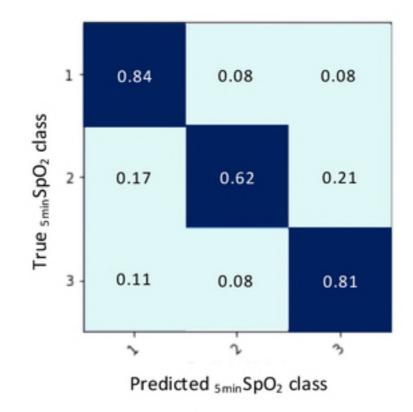




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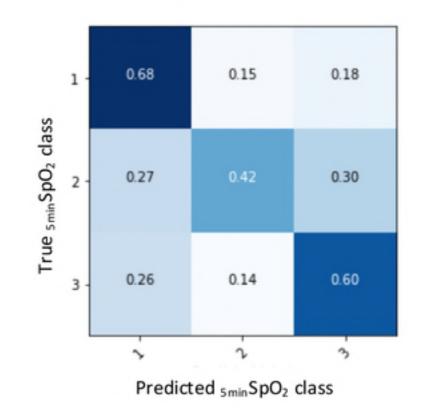
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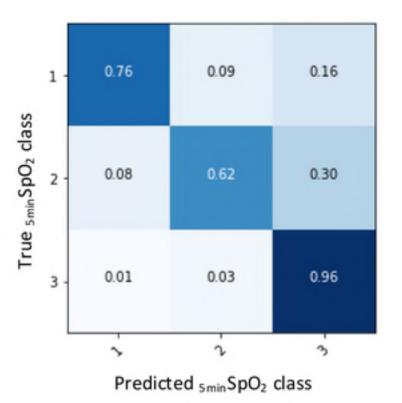
Training confusion matrix Test confusion matrix



>0.99 1 <0.01 <0.01 True _{5min}SpO₂ class 0.99 0.01 2 0.01 0.01 3 -<0.01 0.99 3 2 \sim

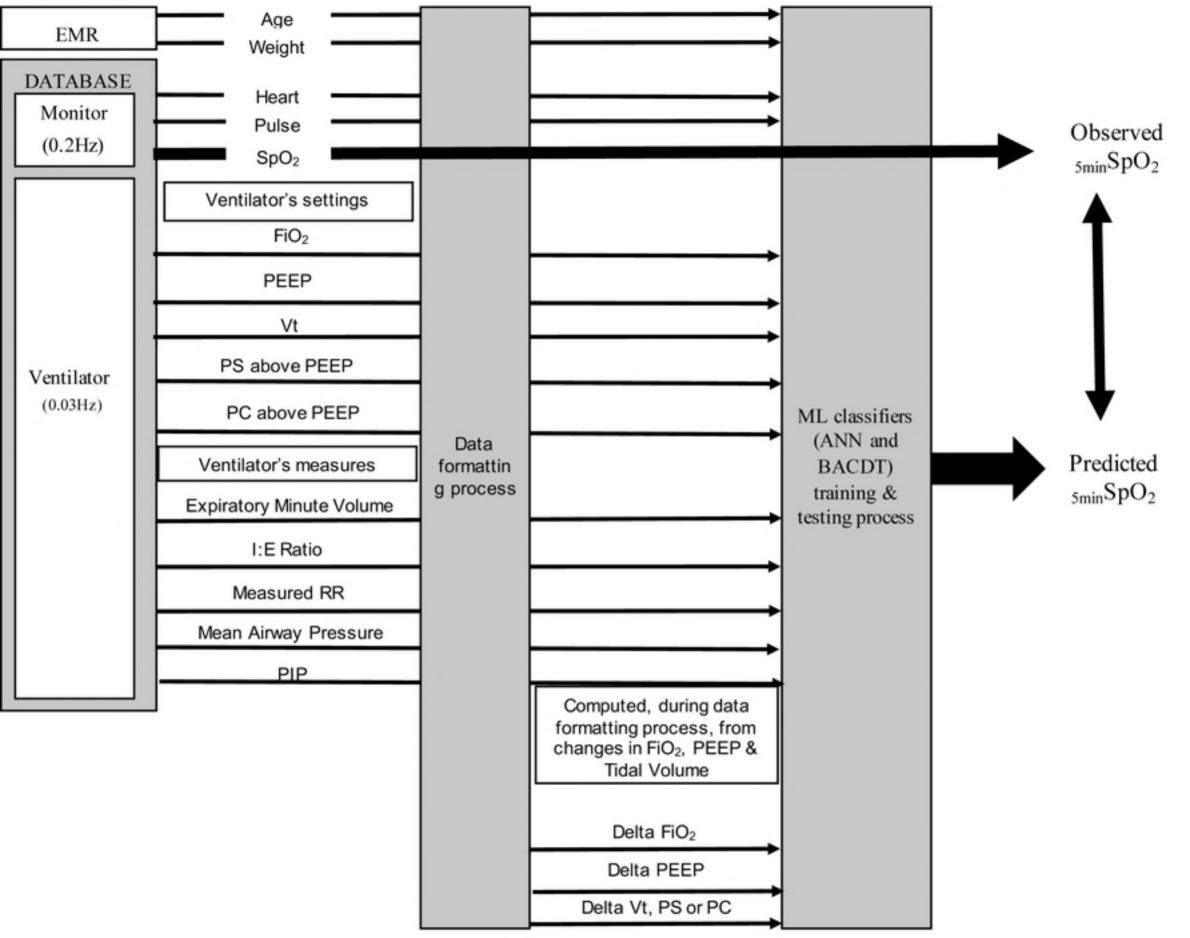
Predicted 5minSpO2 class





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Training set: 975,036 samples

Test set: 193,528 samples Class Balancing: TOMEK applied to dataset (before dataset has been split into training & test set) to remove tomek links, random undersampling applied to class 3 once dataset is split into training and testing subsets, then SMOTE applied to classes 1 and 2 to make their cardinalities equal to that of class 3 (n=325,012).

Training set: 2,293,119 samples

Test set: 201,926 samples Class Balancing: SMOTE applied to classes 1 & 2 to make their cardinalities equal to that of class 3 (n=764,373).

Training set: 487,464 samples Test set: 106,028 samples Class Balancing: TOMEK applied to dataset (before dataset has been split into training & test set) to remove tomek links, random undersampling applied to class 3 once dataset is split into training and testing sub-sets, then SMOTE applied to classes 1 and 2 to make their cardinalities equal to that of class 3 (n=162,488).

Training set: 1,462,503 samples Test set: 281,028 samples Class Balancing TOMEK applied to dataset (before dataset has been split into training & test set) to remove tomek links, random undersampling applied to class 3 once dataset is split into training and testing sub-sets, then SMOTE applied to classes 1 and 2 to make their cardinalities equal to that of class 3 (n=487,501).

- The data-set is first divided into two parts; the training-set and the testset.
- The training of the "Bagged" Complex Trees includes a k-fold crossvalidation, which is performed as follows:
 - Randomly partition the data-set into k equal-sized subsets (folds).
 - ➢ For each of the k equal-sized subsets:
 - ✓ Train/fit the model on the elements contained in the other (k-1) subsets.
 - \checkmark Test the model's accuracy on the given subset.
 - Iterate over the k subsets, until each one has been used once for testing the model's performance during its training.
 - The training validation score consists of the average score obtained by validating the model on all k subsets.