- 1 A systematic examination of learning in the invasive ant
- 2 Linepithema humile reveals very rapid development of short and
- 3 long-term memories
- 4
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9 Abstract

10 The Argentine ant (*Linepithema humile*) is one of the most damaging and widespread invasive 11 ant species worldwide. However, control attempts often fail due to insufficient bait uptake, or bait abandonment. Increasing preference for, and consumption of, is thus an important 12 13 requirement for successful control. Associative learning and within-nest information transfer 14 might be a potential tool for achieving this goal. Here, we conducted a detailed and systematic 15 investigation of olfactory learning and side learning in Argentine ants. The ants showed very 16 strong and rapid side learning, choosing the correct arm in a Y-maze 65% of time after just one 17 visit, and 84% correct after two. Odour learning was even more rapid, with just one visit to a 18 flavoured food source, reached by a scented runway, leading to 85% choices for the 19 corresponding scent on a Y-maze. Further experiments demonstrated that having two cues 20 (runway odour and food flavour) does not improve learning significantly over just one cue. 21 This rapid learning is long-lasting, with one exposure to a runway odour associated with a 22 reward resulting in a strong preference (73%) for this odour even after 48 hours. Food flavour 23 information is transferred efficiently between nestmates in the nest, driving preference: naïve 24 ants housed with ants fed on flavoured food show a strong preference (77%) for that odour 25 after 24 hours. Our results demonstrate the impressive learning abilities of Linepithema humile, which coupled with efficient intranidal information transfer and strong use of 26 27 pheromonal recruitment may help explain their ability to discover and then dominate resources. However, these strengths could potentially be used against them, by exploiting 28 29 learning and information transfer to increase toxic bait uptake during control efforts. Steering 30 ant preference by leveraging learning might be an underappreciated tool in invasive alien species control. 31

32 Keywords: Associative learning, memory, Argentine ants, invasive species, odour

33 Introduction

34 With increasing trade, and the concomitant breakdown of biogeographic barriers, invasive 35 species are spreading globally (Mack and Lonsdale 2001; Mooney and Cleland 2001; Perrings 36 et al. 2005). Invasive species are often economically damaging and ecologically devastating 37 (Marbuah et al. 2014; Escobar et al. 2018), with invertebrates being amongst the most 38 damaging invasive groups (Ricciardi 2015). Ants are especially effective at invading habitats 39 outside their native range (Tsutsui and Suarez 2003), where they displace native species 40 through competition and predation (Ness and Bronstein 2004; Abbott 2006; Matsui et al. 41 2009).

The Argentine ant (*Linepithema humile* (Mayr, 1868)) is one of the most damaging ant species worldwide, and the most widespread invasive ant in Europe (Human and Gordon 1999; Trigos-Peral et al. 2021). The presence of *L. humile* in invaded areas causes a massive decrease in invertebrate diversity and even affects vertebrates (Wetterer et al. 2001; Suarez et al. 2005; Alvarez-Blanco et al. 2021). In addition, *L. humile* can act as an important agriculture pest by enhancing Hemipteran populations, which then increase the likelihood of fungal and viral infections (Wetterer et al. 2009).

49 The economic damage through invasive species costs the EU an estimated €12.5 billion 50 a year (European Commission, 2011). Especially combatting invasive ants has become a top 51 priority for conservation programs (Hoffmann et al. 2016). Unfortunatly, in addition to being 52 ecologically and economically damaging, invasive ants are also difficult to control. Two-thirds 53 of L. humile eradication attempts fail (Hoffmann et al. 2016). Insect control methods usually 54 rely on the use of insecticide spraying, which is known to be ineffective against ants. The 55 reason behind this ineffectiveness is primarily the strongly sheltered reproductive part of a 56 colony, the queens (Williams et al. 2001). The queens and the brood are not only physically 57 protected, but may also be protected by tuned interaction networks within the colony, which 58 regulate the exposure of vulnerable individuals, at least to pathogens (Stroeymeyt et al. 2018). 59 The current gold standard approach for eradication of ants is the use of baits with a slow-60 acting poison, which allows workers to bring the food-poison mixture back to the nest to 61 distribute it to the brood and the queen (Hoffmann et al. 2016). Even so, the success rate of 62 such eradication attempts is still low (Souza et al. 2008; Hoffmann 2011). A big issue is the 63 availability of high-quality natural food, which is often preferred by ants and acts as a 64 competitor for the poisoned bait, leading to low bait consumption rates (Rust et al. 2003;

65 Silverman and Brightwell 2008). Driving bait preference and increasing consumption is thus a66 critical step towards successful ant control.

67 One approach to increasing bait attractiveness, beyond a change in bait formulation, 68 is to steer ant behaviour. Studies in leaf-cutting ants showed that alarm pheromones can be 69 used to increase bait consumption and foraging activity (Hughes et al. 2001, 2002). A study in 70 Argentine ants showed that synthetic (Z)-9-hexadecenal, the main component of the trail 71 pheromones in this species, increased bait (liquid sucrose) consumption (Greenberg and Klotz 72 2000). Pheromones can not only be used to lure ants to a bait, but also to disrupt their trail-73 following behaviour (Tatsuki et al. 2005; Tanaka et al. 2009). An open field experiment 74 demonstrated that the combination of a highly-concentrated synthetic pheromone and 75 insecticidal baits may provide effective control of Argentine ant populations (Sunamura et al. 76 2011).

77 However, preference and consumption can also be manipulated by exposing 78 individuals to tailored information. Insights from behavioural economics and cognition 79 research are regularly used to drive preference and consumption behaviour in humans. A 80 widespread example is the exploitation of the endowment effect, where the perceived value of a good is increased by the subject already owning it. For example, someone who would be 81 82 willing to pay €5 for a mug may, if given the mug for free, demand €8 to sell it (Kahneman et al. 1991). Companies and advertisers exploit this by providing a service at a discount for a 83 84 limited period, to cause endowment, before raising the price. This demonstrates that insights 85 from behavioural economics and cognition research can be used to effectively drive 86 preferences and consumption behaviour. Driving preference using such behavioural economic 87 effects has been shown also in animals. Primates and birds are known to be sensitive to 88 irrational behaviours like the endowment effect (Shafir et al. 2002; Bateson 2002; 89 Lakshminaryanan et al. 2008). A related concept to an endowment effect was shown in Lasius 90 niger ants, where foragers were trained to expect one food flavour, and then provided another 91 food source of equal value but with a different flavour. These ants undervalued the novel 92 flavoured food, as demonstrated by reduced food and recruitment (Oberhauser and Czaczkes 93 2018). However, we are still far from a sophisticated understanding of insect value perception.

Possibly the easiest way of changing the perceived value of a cue is via associative learning. Associative learning is perhaps the most fundamental form of learning, and strongly impacts perceived value. Classical association experiments involve the pairing of an 97 unconditioned stimulus (e.g. food), which innately produces a response, with a neutral 98 stimulus (e.g. odour), which usually triggers no response. After training, exposure to the 99 conditioned stimulus can trigger the unconditional response which the unconditional stimulus 100 usually elicits, or allows the subject to predict that the unconditional stimulus is imminent 101 (Fanselow 1998; Clark 2004).

102 Ants have been shown to be good associative learners. Ants can form impressive route 103 memories which allow them to associate a direction, panorama, or a route with a food reward, 104 nest (Aron et al. 1988; Harrison et al. 1989; Graham and Collett 2006; Grüter et al. 2011; 105 Knaden and Graham 2016) or even with a negative outcome (i.e. getting trapped) (Wystrach 106 et al. 2020). Many ant species have been shown to associate an odour with a food reward 107 (Roces 1990; Helmy and Jander 2003; Dupuy et al. 2006; Czaczkes et al. 2014; Oberhauser et 108 al. 2019; Czaczkes and Kumar 2020). Food-odour associations can be rapidly formed and may 109 last for days (Josens et al. 2009; Arenas and Roces 2018; Piqueret et al. 2019).

110 However, very little is known about the associative learning ability of invasive ants. In 111 one study it was shown that Argentine ants (L. humile) can use visual and spatial cues to find 112 a food source, but the experimental setting was a binary choice test between visual cues and 113 a pheromone trail (Aron et al. 1988, 1993). A recent study in *L. humile* showed that they are 114 also able to associate an odour spot in a circular arena with a sucrose solution (Rossi et al. 115 2020). Preexposure to trail pheromone increased food acceptance rates, but had no effect on 116 associative learning. Rossi et al. (2020) is a very important paper for us, as it is the only 117 currently available investigation of associative learning in free-running Argentine ants. In that 118 study, ants were allowed to visit the sucrose reward three times. It is thus unclear how many 119 exposures to the reward would be required in order for the individual to form a short-term 120 association. Furthermore, no long-term memory tests were conducted, nor has information 121 transfer of food-associated odours between nestmates been investigated, as previously 122 shown in bees, wasps, and other ants (Farina et al. 2005; Provecho and Josens 2009; Schueller 123 et al. 2010).

Here, we conduct a comprehensive in-depth investigation of learning in the ecologically important ant *L. humile*. We study how rapidly *L. humile* form short- and longterm memories, which types of cues best support this, and whether food-related cues are transferred between nestmates intranidally. Such information is critical if we hope to develop cognition-based control strategies.

129 Materials and Methods

130

131 <u>Colony maintenance</u>

132 Linepithema humile ants were collected in 2021 from Girona, Spain and Proença-a-Nova, 133 Portugal, and were all part of the same European supercolony. Colony fragments (henceforth 134 colonies), consisting of one or more queens and 300-1000 workers, were kept in plastic 135 foraging boxes (32.5 x 22.2 x 11.4 cm) with a plaster of Paris on the bottom. The walls were 136 coated in fluon to prevent escape. Each box contained several 15mL red plastic tubes partly 137 filled with water, plugged with cotton, for use asas nests. The ants were maintained on a 12:12 138 light:dark cycle at room temperature (21-25 °C) and provided with water ad libitum. Colonies 139 were fed for three days with ad libitum 0.5M sucrose solution and Drosophila melanogaster, 140 and deprived of food for four days prior to testing. For all experiments using odours and/or flavours, donor and recipient colony pairs were used. Such colonies were collected in the same 141 142 location at the same time, however the donor colonies had never experienced any of the 143 chemicals used, whilst the recipient colonies received individuals that had experienced these.

144

145 Solutions and odours

146 1M sucrose solutions, (Südzucker AG, Mannheim, Germany), were used as a reward during 147 training for all experiments. Where a negative reinforcement was also presented, 0.6mM 148 quinine (Merck KGaA, Darmstadt, Germany) solutions were used. Paper overlays, used during 149 odour experiments, were stored for at least 1 week prior to the experiments in airtight plastic 150 boxes (19.4 x 13.8 x 6.6 cm) containing a glass plate with 500µl of either strawberry or apple 151 food flavouring (Seeger, Springe, Germany). For experiments were flavoured food was used, 152 1µL of the respective flavouring was added per mL of 1M sucrose solution. Pilot studies 153 showed L. humile workers having a slight preference for strawberry over apple flavour (58% 154 of the ants prefered strawberry, N = 158, see supplement 3).

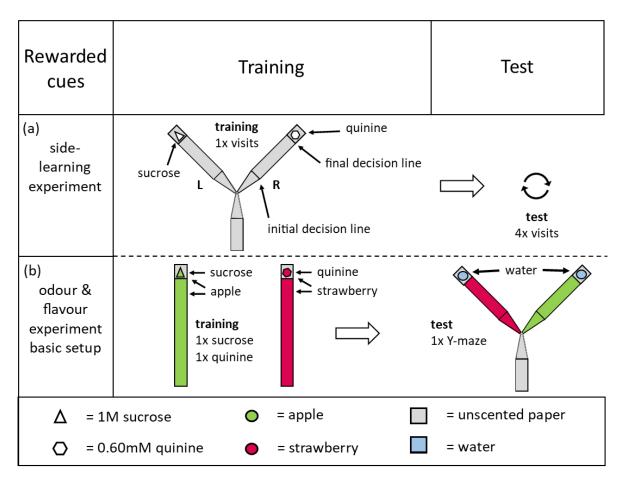
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156 Experiment 1 – Short-term spatial memory

157 Can *L. humile* ants learn to associate a location, one arm of a Y-maze, with the presence of a
158 reward? Here we investigate this by offering a reward, sucrose, on one of the Y-maze arms
159 and a punishment, quinine, on the opposing arm. 6-8 ants per day were tested, testing in total
160 46 ants from 7 colonies

Y-maze setup and training methods follow Czaczkes (2018). A colony was connected via a drawbridge to a Y-maze (arms 10cm long, 1cm wide, tapering to 2mm at the bifurcation, see fig. 1a) covered in unscented disposable paper overlays. A c. 20µl drop of sucrose solution was placed at the end of one arm of the maze, and a drop of quinine solution on the other.

165 The first 1-3 ants to initially chose the arm leading to the punishment was marked with acrylic 166 paint after it subsequently found the sucrose reward. This protocol ensures that the focal ants 167 do not have an innate preference for the rewarded side. From this point on, only one by one 168 of the marked ants were selectively allowed to move onto the setup. Upon satiation, ants ran 169 back over the bridge to the nest and unloaded their collected food to their nestmates. While 170 unloading, the Y-maze paper overlays were replaced with fresh overlays, to remove any 171 pheromone trails or cuticular hydrocarbons left by the ant. After unloading, the ants were 172 allowed back onto the Y-maze via the bridge. We recorded the ant's initial decision (defined 173 as the antennae crossing a line 2cm from the bifurcation) and final decision (crossing a line 174 8cm from the bifurcation, 2cm from the arm end). We then allowed the ant to carry out 3 175 more such visits (5 visits to the sucrose, 4 trained decisions in total). Half the ants were 176 rewarded on the left, the other half rewarded on the right.



177

178 Figure 1: Basic setup used for all experiments: a) Ants were trained to associate a side of the Y-maze with a 1M sucrose reward, while the other side contained 0.60mM quinine or water 179 180 (exp 1). In all other experiments (b), ants were trained to associate an odour (apple or 181 strawberry) or/and a flavour (apple or strawberry) with a 1M sucrose reward on a linear 182 runway and were then tested on a Y-maze. In experiments where quinine was used as 183 negative reinforcer (2,4,6,8) the flavour and odour of the quinine was the converse of that of 184 the reward. In the experiments (3,5,8,9) the quinine punishment training was removed. In 185 the test trials the arms of the Y-maze contained a water drop. The ants' decision was noted 186 when they crossed the initial decision line (2cm after arm start) and a final decision line (8cm 187 after arm start, 2 cm before end).

Experiment	Runway odour	Food flavour	Punishment visit (quinine)	N	Set	Short or long-term memory	% correct choices
2) Scented & flavoured reward vs. punishment	Х	x	X	72	1	short	84%
3) scented & flavoured reward vs. neutral stimulus	Х	Х		48	1	Short	85%
4) scented & unflavoured reward vs. punishment	Х	-	X	72	1	Short	72%
5) unscented & flavoured reward vs. neutral stimulus		х		48	1	Short	65.5%
6) unscented & flavoured reward vs. punishment		X	x	44	2	Short	86%
7) scented & unflavoured reward vs. punishment	Х	-	Х	48	2	short	78.5%
8) scented & flavoured reward vs. neutral stimulus	X	X		70	1	Long (8, 24, 48 hours)	8h = 85% 24h = 81% 48h = 80% Nestmates: 24h = 77% , 48h = 67%
9) scented & unflavoured reward vs. neutral stimulus vs. neutral stimulus	x	-	X	56	1	Long (8, 24, 48 hours)	48h = 67% , 24h = 78% 48h = 73% Nestmates: 24h = 40% 48h = 30%
1) Side learning: Training on a Y-maze, reward on one arm, punishment on the other			X		1	short	Visit # 2 = 65%, 3 = 84% 4 = 84% 5 = 88%

Table 1) Experimental overview. Experiments 2-9 involved training on a linear runway and testing on
 a Y-maze with scented arms. Experiment 1 involved training over multiple visits on a Y-maze. Runway
 odour: was the runway scented during training? Food flavour: was the food (and punishment where

odour: was the runway scented during training? Food flavour: was the food (and punishment wherepresent) flavoured during training? Experiments in set 1 were carried out between April and August.

present) flavoured during training? Experiments in set 1 were carried out between April and August.
 Experiments in set 2 were carried out between November and December. In short-term learning

experiments training occurred immediately after testing, c. 1-5 minutes. In long-term memory

194 experiments testing occurred the stated number of hours after training. % correct choices are

195 printed in **bold** if significantly different from random choice. In experiments 8 and 9 untrained

196 nestmates, housed with the trained nestmates, were also tested.

197 Experiment 2 – Short-term memory: scented and flavoured reward versus punishment

198 (experimental set 1)

199 Experiments conducted in summer are considered as experimental set 1.

200 The aim of this experiment was to examine if ants can associate two environmental cues 201 (odour and a flavour) with a sucrose reward. An ant was allowed access to a 10cm-long straight 202 runway covered by a scented paper overlay, which had a drop of flavoured sucrose solution 203 at the end (apple or strawberry). After the ant offloaded the collected food in a recipient sub-204 colony nest, created to prevent them from sharing odour or flavour information with future 205 tested ants, it was allowed to visit the runway again. The reward odours and flavours used 206 were alternated between different ants, where if an ant experienced strawberry as a reward 207 then it would experience apple as a punishment and vice-versa. The training phase was 208 concluded once the ant experienced both the reward and punishment in a straight runway 209 and was allowed back into the recipient colony. The ant was then allowed onto a Y-maze (see 210 above), in which one arm was covered in a reward-associated scented overlay and the other 211 in the punishment-scented overlay, and the ant's preference was tested as in experiment 1 212 (see "test" in fig. 1b & table 1). 72 ants from three donor colonies were tested, ensuring an equal number of individuals was tested for each odour/flavour and Y-maze side combination 213 214 daily.

215

216 Experiment 3 – Short-term memory: scented and flavoured reward versus neutral stimulus 217 (experimental set 1)

The aim of this experiment was to test whether ants need a positive and a negative stimulus for successful learning, or if only a positive stimulus is sufficient. Ants were trained as in experiment 2 (runway odour and flavoured food), but no second visit to a punished runway was performed. The test was carried out as in experiment 2 (see also fig. 1 & table. 1). 48 ants from two donor colonies were tested, and again both odours/flavours and Y-maze sides were alternated in every combination possible to remove any potential bias.

224

225 <u>Experiment 4 – Short-term memory: scented and unflavoured reward versus punishment</u>
 226 <u>(experimental set 1)</u>

The aim of this experiment was to determine whether ants can associate runway odour cues alone with a reward or punishment. Ants were trained as in Experiment 2 (see fig. 1 & table

1), except this time, the food reward and the quinine were not flavoured. 72 ants from 6

colonies were tested and both odours and Y-maze sides were alternated daily.

231

232 <u>Experiment 5 – Short-term memory: unscented and flavoured reward versus neutral stimulus</u>
 233 (experimental set 1)

The aim of this experiment was to test whether flavoured food, without runway odour or negative reinforcement, is sufficient to form an association between flavoured food and an runway odour presented on a Y-maze arm. This is especially important for potential future applications in pest control. Ants were trained as in Experiment 3, except that the runway overlay was unscented (see fig. 1 & table.1). In the test, ants had the choice between a scented arm and an unscented one. 48 ants from two colonies were tested.

240

241 <u>Experiment 6 – Short-term memory: unscented and flavoured reward versus punishment</u>
 242 (experimental set 2)

243 We had the oppertunity to collect additional data in winter, which we considered as 244 experimental set 2.

The aim of this experiment was to test whether flavoured food, without runway odour, is sufficient to form an association between flavoured food and an runway odour presented on a Y-maze arm when we add a quinine visit as punishment (contrary to experiment 5). Ants were trained as in experiment 5 except that a quinine visit was added. The test was carried out as in experiment 2 (see fig. 1 & table 1). 44 ants from three colonies were tested.

250

251 <u>Experiment 7 – Short-term memory: scented and unflavoured reward versus punishment</u>

252 (experimental set 2)

253 The results of Experiment 6 were unexpected, considering the ones from Experiment 3.

254 Therefore Experiment 4 was repeated to ensure these surprising results were not caused by

255 seasonal effects or some other systematic change between experimental sets (see fig. 1 &

table 1). 48 ants from three colonies were tested.

257 <u>Experiment 8 – Long-term memory: scented and flavoured reward versus neutral stimulus</u>
 258 (experimental set 1)

259 In this experiment, ants were trained as in experiment 3 (see fig. 1 & table 1) with the

260 exception that every colony was only conditioned to one reward odour (strawberry or

261 apple). Two colonies were conditioned to strawberry and two to apple. 50 ants were trained 262 and, after training, housed in a small sub-colony with 60 naïve ants from their nest. Trained 263 ants were tested in a Y-maze, as in experiment 3, after 6 hours, 24 hours and 48 hours (4 264 colonies, 14 ants per period). Each individual ant was only tested once and was then removed. After the trained ants were tested we also tested the untrained nestmates (4 265 266 colonies, 20 ants per period, 24h and 48h), to test whether contact with the trained ants, 267 which had fed on flavoured food, allowed them to learn the food flavour and thus follow this 268 odour cue. The colony test order was alternately between a colony conditioned to apple or 269 strawberry. In total, we tested 70 trained and 80 untrained ants per time period (trained = 270 6h, 24h and 48; untrained = 24h and 48h).

271

Experiment 9 – Long-term memory: scented and unflavoured reward versus neutral stimulus 272 273 The aim of this experiment was to exclude the possibility that the ants in experiment 8 were 274 not remembering their association for the whole time period, but rather were refreshing their memory by repeatedly sampling the flavoured food from other nestmates. To this end, 275 276 this experiment was identical to experiment 8 but with an unflavoured reward - only a 277 scented runway was used (see fig. 1 & table 1). From the previous experiments, we expected 278 that the trained ants would form a strong association even without food flavour, but that the 279 untrained ants would not be able to gain any relevant odour information from their sisters. 280 In total, we tested 56 trained and 80 untrained ants from 4 colonies per time period.

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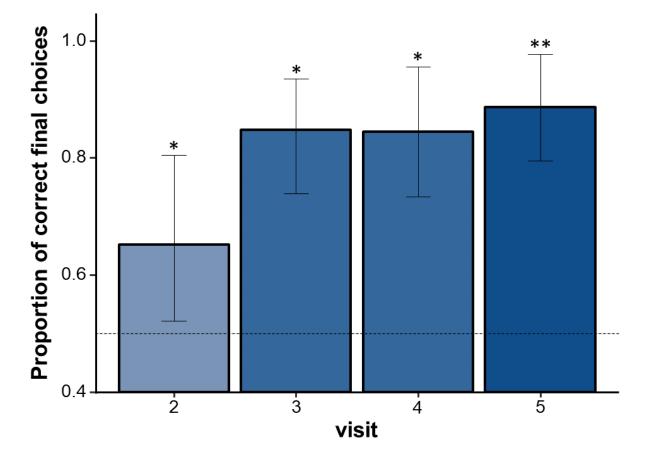
282 Statistical analysis

283 Only 3.6% – 10.9% of initial and final choices differed, depending on experiment, so we 284 focused our analysis on the final choices. Data were analysed using generalized linear mixed-285 effect models (GLMM) (Bolker et al. 2009) in R version 4.1.0 (R Core Team 2021). GLMMs 286 were fitted using the lme4 package (Bates et al. 2015). As the data were binomial (correct / 287 incorrect), a binomial error distribution was used. Since multiple ants were tested per 288 colony, we included colony as random factor. Each model was validated using the DHARMa 289 package (Hartig 2018). Results were plotted using the gglot2 package (Wickham 2016). The 290 complete code and analysis output is provided in supplement 1.

291 **Results**

- 292 The complete dataset is provided in supplement 2.
- 293 Experiment 1 Side-learning
- 294 This experiment tested whether Argentine ants can associate a side of the Y-maze with the
- reward (food), and how this memory develops over subsequent visits.
- 296 Over all visits, significantly more choices were made for the arm leading to the food (GLMM,
- 297 n = 46, z-ratio = 2.513 p = 0.045, see fig. 2). In visit 2, after only one visit to the food, 65%
- (30/46) of ants chose the arm leading to the food (n =46, z-ratio = 2.581, p = 0.042). This rose
- 299 to 84% (39/46) in visit 3 (n = 46, z-ratio = 1.860, p = 0.026), 84% in visit 4 (38/45) (n = 45, z-
- 300 ratio = 1.469, p = 0.032) and 88% (39/44) in visit 5 (n = 44, z-ratio = 2.245, p = 0.009). For a
- 301 pairwise comparison between visits, see online supplement 3

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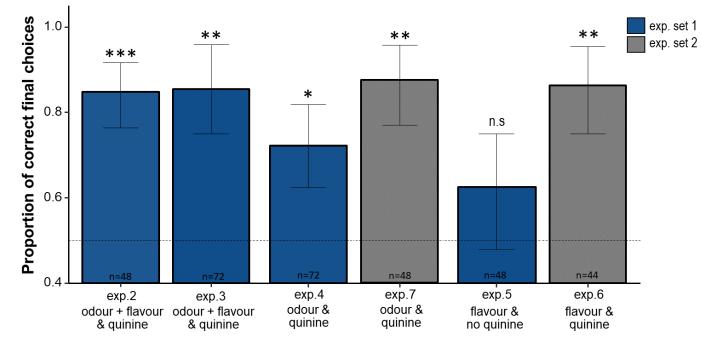


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Figure 2: Side-learning: Proportion of ants choosing the side associated with reward (food) per visit. Ants chose the side associated with reward significantly more often than chance after all visits. Bars depict mean, whiskers 95% confidence intervals derived from the fitted GLMM. The dotted horizontal line displays chance level of 50%. *p < 0.05; **p < 0.01; ***p <0.001.

309 Odour association: Short-term memory

- 310 The aim of experiments 2 7 was to understand if and how well Argentine ants can
- 311 associate odours and food flavours with food rewards, and whether punishment improves
- learning (as has been shown in honeybees, Avargues-Weber et al. 2010).



313

314 Figure 3: Short-term odour associative learning: Proportion of ants reaching the end of a Y 315 maze arm scented with an odour associated with a sucrose reward. Ants were able to form a 316 strong association to both training runway odour and food flavour. Punishment of the 317 contrasting odour using quinine did not improve learning. Ants learned better in 318 experimental set 2 (conducted in the winter) – this is especially noteable when ants were 319 trained to flavoured food without a scented runway. Offering both odour and flavour cues 320 did not increase learning compared to offering only one cue. Bars depict means, whiskers 321 95% confidence intervals derived from the fitted GLMM. The dotted horizontal line displays chance level of 50%. **p* < 0.05; ***p* < 0.01; ****p* < 0.001. 322

- 323
- 324 Experiment 2 Runway odour and flavoured reward (experimental set 1)
- 325 This experiment tested if ants learn to associate the sucrose reward with both
- 326 environmental cues, a food flavour and the corresponding runway odour (apple or
- 327 strawberry). 84% (61/72) of the ants chose the food-associated odour arm (GLMM, z-ratio =
- 328 3.375, p < 0.001, see fig. 3). The specific odour rewarded did not significantly affect choice
- 329 accuracy (apple 80% and strawberry 88%, z-ratio = -0.972, p = 0.3312).

330 Experiment 3 – Runway odour and flavoured reward, no quinine visit

331 (experimental set 1)

332 This experiment tested whether a reward alone, and no punishment (quinine), results in an

equally high proportion of choices for the food-associated odour. 85% (41/48) of the ants

chose food-associated odour arm (GLMM, z-ratio = 2.938, p = 0.003, see fig. 3). Again, the

335 specific odour rewarded did not significantly affect choice accuracy (apple 83% and

336 strawberry 87%, z-ratio = -0.408, p = 0.683).

337

338 Experiment 4 - Runway odour, unflavoured reward (experimental set 1)

339 This experiment tested if Argentine ants can associate a runway odour (apple or strawberry)

340 with an unflavoured reward. 72% (52/72) of the ants chose the side of the Y-maze with a

341 scent associated with a reward (GLMM, z-ratio = 2.568, p = 0.010). Ants performed

identically on both rewarded odours (72% correct decisions for both odours, z-ratio = 0.00, p

343 = 1.0000, see fig. 3).

344

345 Experiment 5 - Flavoured reward, no runway odour, no quinine (experimental set 1)

346 This experiment was run to test the ant's learning ability without negative reinforcement

and using only one cue, the flavoured food. 62.5% (30/48) of ants chose the food-associated

348 odour arm, which does not differ significantly from random choice (GLMM, z-ratio = 1.212, p

349 = 0.226, see fig. 3). Again, there was no significant difference between performance with the

350 two odours (62.5% correct decisions for both odours, z-ratio = 0.000, p = 1.000).

351

352 Experiment 6 - Flavoured reward, no runway odour (experimental set 2)

353 This experiment was similar as the 5th experiment except that a quinine visit was added and

with only one cue (flavour). Again, the purpose of this study was to test for the need of a

355 punishment visit. Unlike in summer (experimental set 1), the winter experiment

356 (experimental set 2) showed that ants were able to learn to associate just one cue (flavour)

with a sucrose reward. 86% (38/44) of the ants chose the side of the Y-maze with a scent

associated with reward (GLMM, z-ratio = 2.721, p = 0.0065, see fig. 3. There was no

359 significant difference between the two odours (apple 81% and strawberry 90%, z-ratio = -

360 0.863, p = 0.388)

361

362 Experiment 7 - Runway odour, unflavoured reward (experimental set 2)

This experiment, conducted in winter, was the same as the 4th experiment. The purpose was to test if ants show a systematic difference in learning between the two experimental sets. The ants again formed a strong association between just one cue (odour) and the sucrose reward. 87.5% (42/48) of the ants chose the side of the Y-maze with a scent associated with reward a reward (GLMM, , z-ratio = 2.656, p = 0.007, see fig. 3). Again, the specific odour rewarded did not significantly affect choice accuracy (apple 79% and strawberry 95%, z-ratio = -1.582, p = 0.1138).

370

371 The roles of runway odour and food flavour in learning

372 In order to characterise the relative roles of runway odour and food flavour in driving

learning, we compared the behaviour of ants in experiments 2 (runway odour and food

374 flavour during training) with the results from experiment 4 (only runway odour) and

experiment 5 (only food flavour). Note, however, that experiment 5 did not include a

negative reinforcement, while experiments 2 and 4 did. We consider this appropriate, since
negative reinforcement did not improve learning (compare experiments 2 & 3).

Combined runway odour and flavoured food led to a significantly higher proportion of correct choices than only having flavoured food (z-ratio = -2.714, p = 0.018). However, runway odour alone was not significantly weaker than the combined cues (z-ratio = -1.118, p = 0.502). Runway odour alone did not result in significantly more correct choices than food flavour alone (z-ratio = 1.803, p = 0.168).

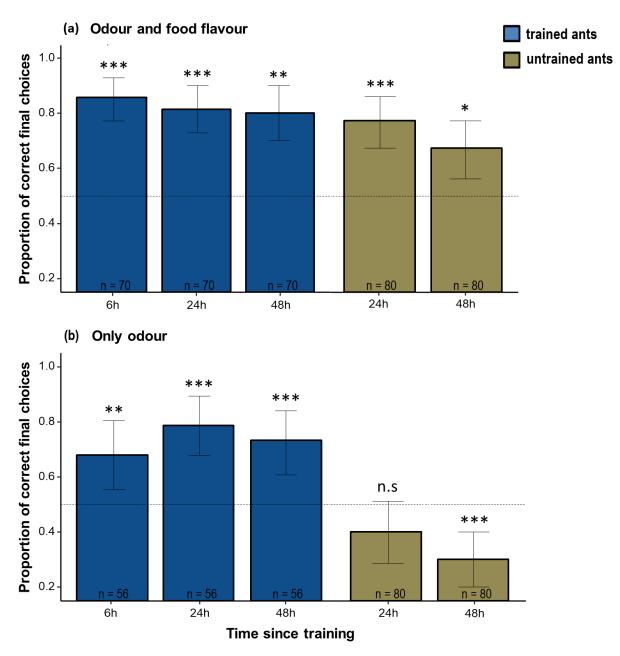
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384 Long-term odour and flavour association

385 The aim of experiments 8 and 9 was to examine if Argentine ants also form a long-term (6h,

24h, 48h) association between runway odours and food rewards (experiment 9) and with

387 flavoured food rewards (experiment 8).



388

Figure 4: Long-term odour associative learning: Proportion of ants choosing the odour 389 390 associated with a sucrose reward. Trained ants were tested after 6h, 24h, and 48h. 4a: 391 Untrained nestmates also showed a preference for the rewarded odour when food was 392 flavoured, which was not significantly weaker than that of trained ants. 4b: Trained ants were able to associate a runway odour alone with an unflavoured sucrose reward after 6h, 393 394 24h and 48h. By contrast, untrained nestmates did not show any odour preference after 24 395 hours, and showed an aversion for the food odour after 48 hour. Bars depict means, 396 whiskers 95% confidence intervals derived from the fitted GLMM. The dotted horizontal line displays chance level of 50%. **p* < 0.05; ***p* < 0.01; ****p* < 0.001.

397 398

399 Experiment 8 - Long-term memory, runway odour and flavoured food

- 400 Trained ants and their ability to build a long-term association
- 401 Ants trained on combined runway odour and food flavour significantly preferred the odour-
- 402 associated Y-maze arm after 6 hours, 24 hours and 48 hours (GLMM, z-ratio = 4.204, p <

403	0.0001, see fig. 4a), with 85% (60/70), 81% (57/70), and 80% (56/70) correct choices after 6,
404	24, and 48 hours respectively (6 hours: GLMM, z-ratio = 5.246, p < 0.0001, 24 hours: GLMM,
405	z-ratio = 4.809, p < 0.0001 , 48 hours: GLMM, z-ratio = 8.515, p < 0.0001).
406	
407	Odour preference in untrained ants housed with flavoured-food fed nestmates (trained)
408	Untrained ants housed with ants trained with flavoured food showed a strong preference for
409	that food flavour after 24 and 48 hours (z-ratio = 3.830, p < 0.0001, see fig. 4a). 77% (62/80)
410	and 67% (54/80) of ants chose food-associated odour after 24 and 48 hours respectively (24
411	hours: GLMM, z-ratio = 4.619, p < 0.0001, 48 hours: GLMM, n = 80, z-ratio = 2.511, p =
412	0.012).
413	
414	Experiment 9 - Long-term memory, only runway odour, unflavoured reward
415	This experiment was run to quantify long term learning without access to informative
416	flavoured food, since this could refresh the ants' memories.
417	
418	Trained ants and their ability to build a long-term association with unflavoured food
419	Ants trained with runway odour and unflavoured food nonetheless significantly preferred
420	the odour-associated Y-maze arm after 6, 24 and 48 hours (GLMM, z-ratio = 3.990, p <
421	0.0001, see fig. 4b), with 67% (38/56), 78% (44/56), 73% (41/56) correct choices after 6, 24,
422	and 48 hours respectively (6 hours: GLMM, z-ratio = 2.611 , p = 0.009, 24 hours: GLMM, z-
423	ratio = 3.990, p < 0.0001 , 48 hours: GLMM, z-ratio = 3.332, p < 0.0001.
424	
425	Odour preference in <u>untrained</u> ants housed with <u>unflavoured-food</u> fed nestmates (trained)
426	Unlike naïve ants housed with nestmates trained on flavoured food, naïve ants housed with
427	nestmates trained on unflavoured food showed no preference for the food-associated odour
428	(z-ratio = -1.777, p = 0.075, see fig. 4b). 40% (32/80) and 30% (24/80) of ants chose the food-
429	odour covered Y-maze arm after 24 and 48 hours, respectively. Indeed, while the choice of
430	naïve ants after 24 hours did not differ from chance (GLMM, z-ratio = -1.381, p = 0.268),
431	after 48 hours ants significantly avoided the scented arm (z-ratio = -3.473, p < 0.0001).

432 The effect of food flavour presence on the long-term memory of trained ants

- 433 Here we compared how well the Argentine ants performed on the long-term memory test
- 434 (6h, 24h, 48h) when they had a flavoured reward vs. an unflavoured reward. Do they form a
- 435 significantly better memories when they had a flavoured reward?
- 436 There was no significant difference between trained ants who had an unflavoured reward
- 437 treatment (Experiment 9) and those trained on flavoured food (experiment 8) after 6 hours,
- 438 24 hours and 48 hours (6 hours: GLMM, n =56[exp.8] and n=70[exp.9], z-ratio = 2.344, p =
- 439 0.176 ,24 hours: GLMM, n =56[exp.8] and n=70[exp.9] , z-ratio = 0.399 , p = 0.998, 48 hours:
- 440 GLMM, n =56[exp.8] and n=70[exp.9], z-ratio = 0.897, p = 0.947).
- 441 However, untrained ants who were treated with an unflavoured reward (9. Experiment)
- 442 performed significantly worse than ants with a flavoured reward treatment (8. Experiment)
- 443 after 24 hours and 48 hours (24 hours: GLMM, n =80[exp.8] and n=80[exp.9], z-ratio = 4.709,
- 444 p < 0.001, 48 hours: GLMM, n =80[exp.8] and n=80[exp.9], z-ratio = 4.631, p < 0.001).

445 **Discussion**

446

447 Linepithema humile are adept learners: The side-learning results show that Argentine 448 ants are capable of learning to associate a direction or an arm of a Y-maze with a food reward 449 after just one visit, and accuracy improves with further visits (see fig. 2). Such rapid and reliable 450 learning is surprising, given the fact that L. humile relies strongly on social information 451 (pheromone trails), while other recruiting social insects which learn equally fast, such as the 452 ants Lasius niger and Paraponera clavata ants, and the honeybee Apis melifera, prioritize 453 memories over recruitment signals when the two conflict (Harrison et al. 1989; Aron et al. 454 1993; Grüter et al. 2008, 2011; Czaczkes et al. 2013; von Thienen et al. 2016). *L. humile's* strong 455 individual memory may allow them to reliably recruit even to distant resources, while their 456 strong reliance on social information, and ability to recruit from active trails (Flanagan et al. 457 2013), may allow them to rapidly dominate these resources once found. Indeed, the rapid 458 discovery of new resources and massive, rapid recruitment might be an important 459 contribution to making Argentine ants competitive against native ants (Holway 1999), but see 460 (Cordonnier et al. 2020). Route learning and navigation is hindered by higher complexity, at 461 least in La. niger ants, but when trail pheromones are present, error rates decrease (Czaczkes 462 et al. 2013). The combination of social information and a strong individual side-learning 463 memory could hence be extremely beneficial and explain why Argentine ants developed such 464 a strong individual route learning ability in parallel to their pheromone recruitment system. 465 However, a systematic exploration of learning in (social) insects has not been carried out, so 466 it is also possible that many or most ants are equally good learners.

467 Alongside their impressive route learning, Argentine ants also show even more rapid 468 learning of olfactory cues. Ants were able to form a strong association after only one rewarded 469 visit (see fig. 3 & table 1). These findings are again comparable to results from Lasius niger 470 (Czaczkes et al. 2014; Czaczkes and Kumar 2020). Somewhat surprisingly, results from both 471 the short-term and long-term learning experiments showed that punishing the alternative 472 odour with quinine does not improve response accuracy. While some studies report ants 473 (Camponotus fellah) failing to form a negative association to a scent (Josens et al. 2009), 474 studies on Las. niger ants and honeybees do (Avarguès-Weber et al. 2010; Wenig et al. 2021). 475 Also remarkable is that *L. humile* is able to form an association with a food source given only 476 one cue: a food flavour or a runway odour. Although the difference between choice accuracy when trained on only one cue or both was not significantly, the gain of 10-16 (see fig. 3 & table
percentage points when both are available, and the fact that both single cues were
sufficient to form an association, suggests to us that cue effects could have an additive or subadditive effect on learning.

481 To our knowledge, the learning ability of *Linepithema humile* has never before been 482 described in such detail, and their very rapid learning of olfactory cues never fully appreciated. 483 Rossi et al. (2020) previously demonstrated that L. humile could associate an odour with a 484 food reward. Our results support their findings using a different experimental approach, and 485 with a higher resolution: the Rossi study allowed 3 visits to a circular open foraging arena, so 486 did not explore the limits of ant learning. Our study controlled the experiences of the 487 individual ants more tightly, by reducing the number of rewarded visits to one, and separating 488 rewarded and unrewarded learning events. While other studies have also demonstrated that 489 ants can associate an odour alone with a reward, in combination with a quinine negative trial, 490 these studies required extensive training, with 6-24 visits to the reward, and the odour was 491 blown by an air stream instead of using scented paper overlays (Dupuy et al. 2006; Guerrieri 492 and d'Ettorre 2010). To our knowledge, our study is also the first study to demonstrated that 493 *Linepithema humile* can learn to associate the flavour of the food alone with the food reward.

494 Alongside the strong short-term olfactory memory, our study demonstrates that 495 Argentine ants also possess a strong long-term memory, which lasts for at least 48 hours (see 496 fig. 4 & table 1). As in our short-term memory tests, an runway odour alone, without food 497 flavour, was sufficient to drive strong and stable learning. This is in line with studies on other 498 species (Formica fusca and Camponotus fellah), which show stable memory for at least 72 499 hours, and a decay in learning after a week (Josens et al. 2009; Piqueret et al. 2019). However, 500 the study on Camponotus fellah again used very extensive training (16 training visits). We 501 found that one exposure alone, without a punishment visit, was all that was required to elicit 502 strong and stable learning. This again suggests that L. humile are an extraordinarily good 503 olfactory learners, as well as strong route learners, although differences in experimental 504 protocol may also have contributed to the impressive *L. humile* results.

505 It is also important to note that, in the long-term memory experiments, tested ants 506 were housed in a small sub-nest where they fed their nestmates after their training. As a 507 result, flavoured food was likely distributed amongst the workers via trophallaxis. This could 508 have acted to 'refresh' the memory of the tested ants for some time. However, learning remained strong even if ants were trained only with runway odours, and without food odours. These impressive learning skills are not limited to trained ants. Tellingly, inclusion of food flavour resulted in the untrained nestmates also developing a preference for that odour, demonstrating a very effective distribution of food-related information within the nest. Such intranidal information spread affecting future foraging decision has been reported in both other ants (Roces 1990; Provecho and Josens 2009; Arenas and Roces 2018), bees (Farina et al. 2005) and wasps (Jeanne and Taylor 2009).

516 Finally, our results indicate that there might be seasonal variation in learning, although 517 this was not tested systematically. While our summer experiments showed that flavour alone 518 is not sufficient for ants to form a strong association with the food reward, repeating the 519 experiment in the winter resulted in very strong learning. Furthermore, our only runway odour 520 experiment conducted in winter revealed an even stronger learning than in summer (see. fig. 521 3 & table 1). However, it has to be mentioned that the flavour experiment in winter had a 522 quinine visit, which summer experiments did not. Nevertheless, as mentioned above, quinine 523 does not seem to improve learning within a season, which makes a seasonal effect more likely. The apparent improvement in learning in the winter may be ecologically relevant, but may 524 525 also be a (to us) inexplicable laboratory artefact. We note that the opposite pattern was found 526 in Lasius niger in a route-learning paradigm (Oberhauser et al. 2018). Season and temperature 527 effects on foraging and recruitment behaviour are commonly reported in social insects (Porter 528 and Tschinkel 1987; Stuble et al. 2013; Stroeymeyt et al. 2014; Park and Nieh 2017)

529 Linepithema humile are adept learners and rapidly disseminate food-related 530 information in the nest – abilities which might help them to adapt to new environments and 531 dominate resources, and could be one reason for their success as invaders. However, their 532 strength could potentially become a weakness, if their memory can be used against them. One 533 possibility would be to use associative learning and intranidal information transfer to steer 534 foraging preference towards poisoned baits, much as honeybee preference can be steered for 535 pollination purposes (Farina et al. 2020). Similarly, foraging preference of leaf-cutter ant 536 colonies can be steered to a specific food target by exploiting their preference for foraging on 537 resources which smell or taste like those already being collected (Arenas and Roces 2018). 538 While leveraging learning to control animal behaviour is commonly used in behavioural 539 conservation of vertebrates, it is mostly used to reduce crop damage or to minimize negative 540 interactions with humans (Matsuzawa et al. 1983; Webb et al. 2015; Valenta et al. 2021).

541 Leveraging learning to improve the control of invasive animals may be an underappreciated

- 542 tool in the conservation toolbox.
- 543
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- 550

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