

1 A waveform-independent measure of recurrent neural activity

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8

9 Abstract

10 Rhythmic neural activity, so called oscillations, play a key role for neural information transmission,
11 processing and storage. Neural oscillations in distinct frequency bands are central to physiological
12 brain function and alterations thereof have been associated with several neurological and psychiatric
13 disorders. The most common methods to analyse neural oscillations, e.g. short-term Fourier transform
14 or wavelet analysis, assume that measured neural activity is composed of a series of symmetric
15 prototypical waveforms, e.g. sinusoids. However, usually the models generating the signal, including
16 waveform shapes of experimentally measured neural activity are unknown. Decomposing asymmetric
17 waveforms of nonlinear origin using these classic methods may result in spurious harmonics visible in
18 the estimated frequency spectra. Here, we introduce a new method for capturing rhythmic brain
19 activity based on recurrences of similar states in phase-space. This method allows for a time-resolved
20 estimation of amplitude fluctuations of recurrent activity irrespective of or specific to waveform-
21 shapes. The algorithm is derived from the well-established field of recurrence analysis, which has rarely
22 been adopted in neuroscience. In this paper, we show its advantages and limitations in comparison to
23 short-time Fourier transform and wavelet convolution using periodic signals of different waveform
24 shapes. Further, we demonstrate its application using experimental data, i.e. intracranial
25 electrophysiological recordings from the human motor cortex of one epilepsy patient.

26

27 **Keywords:** oscillations, waveform, recurrence analysis, nonlinear time series analysis, wavelet,
28 rhythmic neural activity

29 Introduction

30

31 During the last two decades, neural oscillations have gained increasing attention as a fundamental

32 mechanism of neural communication (Buehlmann and Deco 2010; Agostina Palmigiano et al. 2017).

33 Neural oscillations are defined as temporally recurring patterns of neuronal activity, also referred to

34 as periodic and rhythmic activity. Oscillations mainly represent synchronized input to neural ensembles

35 consisting of thousands of cells (Buzsáki and Draguhn 2004). The spatial specificity of recorded activity

36 mainly depends on the measurement device used, with e.g. surface electrocorticography covering a

37 much broader scale than e.g. invasive local field potential recordings (LFPs). Classically, oscillatory

38 activity in the human brain is subdivided into five frequency bands: delta (<4 Hz), theta (4-8 Hz), alpha

39 (8-13 Hz), beta (13-30 Hz) and gamma (>30 Hz) (Buzsáki and Draguhn 2004). A wide range of

40 physiological processes in the animal and human brain is associated with fluctuations of oscillations in

41 distinct frequency bands, e.g. such as deep sleep (delta oscillations, Amzica and Steriade 1998), long-

42 term memory and inhibitory top-down control (theta oscillations, Oehrn 2018), attention and local

43 inhibition (alpha oscillations, Bollimunta et al. 2011) and motor control (beta oscillations, Engel and

44 Fries 2010). Further, alterations in distinct frequency bands occur in neurological and psychiatric

45 diseases, e.g. changes in beta band activity during Parkinson's disease (Hemptinne et al. 2013; Kühn et

46 al. 2006; Little and Brown 2014) and theta activity during essential tremor (Pedrosa et al. 2012;

47 Schnitzler et al. 2009). Nowadays, neuroscientists commonly use wavelet analysis for the

48 quantification of oscillatory activity (Hramov et al. 2015; van Vugt et al. 2007) and Fourier-based

49 analysis tools, such as multitapering or short time Fourier transformation (van Drongelen 2018). While

50 being computational efficient, these methods have certain limitations that one needs to consider

51 during interpretation. Classical Fourier and wavelet analysis usually implicitly assume that the

52 analysed signal is a superposition, i.e. summation of stationary sinusoidal or wavelet shaped

53 components. However, Fourier transformation of a non-periodic or non-sinusoidal signal may be

54 difficult to interpret. While it is theoretically possible to deconstruct any non-periodic signal into a

55 series of infinite sinusoidals using the Fourier transform, one has to be careful not to over interpret

56 frequency components which arise due to the decomposition of a non-periodic non-sinusoidal signal
57 into periodic sinusoidals (Lozano-Soldevilla et al. 2016; Gebber et al. 1999). Thus, the question arises
58 which frequency components do indeed carry meaningful information, and which are redundant or
59 even artificial.

60 The rationale behind using Fourier-based methods is the basic assumption, that most
61 electrophysiologically recorded data, e.g. from electroencephalography (EEG) or LFPs, represent the
62 summed activity of large neuronal populations (Franaszczuk and Blinowska 1985; Buzsáki and Draguhn
63 2004). However, despite few attempts at data-driven modelling of specific waveforms (Sherman et al.
64 2016; Lewis et al. 2012) most often the signal generating mechanisms and models and the prototypical
65 waveform shapes of neuronal activity are unknown (Cole and Voytek 2017). In recent years, waveform
66 shapes have gained increasing interest in the neuroscientific community (for reviews see Jones 2016
67 and Cole and Voytek 2017). Several studies revealed stereotypical variants of classic frequency bands
68 which deviated from the sinusoidal waveform shape, e.g. the sensorimotor “mu rhythm” which is a
69 variation of an alpha wave (Arroyo et al. 1993; Debnath et al. 2019; Muthukumaraswamy et al. 2004;
70 Tiihonen et al. 1989) or motor cortical beta activity with a saw tooth shape (Cole et al. 2017). This non-
71 sinusoidal rhythmic activity is functionally relevant. In Parkinson’s disease, asymmetric beta waves
72 have been associated with the pathological state and shown to become more symmetric with
73 successful treatment i.e. deep brain stimulation (Cole et al. 2017). While waveform shape is
74 increasingly recognized to carry meaningful physiological information, there is still a lack of tools which
75 specifically quantify non-sinusoidal activity. While recently, algorithms to characterize waveform
76 shapes have been proposed, methods to incorporate non-sinusoidal activity into frequency analysis
77 are still lacking (Cole et al. 2017; Pullon et al. 2019; Escobar Sanabria et al. 2017). Using classic
78 approaches like Fourier analysis on asymmetric signals leads to the generation of harmonics in the
79 respective spectra, which can be falsely interpreted as meaningful physiological or pathological
80 activity. This is particularly true for measures of coupling, e.g. phase-amplitude coupling where non-
81 sinusoidal signals may lead to spurious results (Lozano-Soldevilla et al. 2016; Yeh et al. 2016).

82 Here, we introduce a parsimonious way to analyse rhythmic activity that is not based on assumptions
83 regarding waveform shapes. In this approach, we quantify recurrences of similar dynamic states ,based
84 on the established framework of recurrence analysis (Webber and Marwan 2015). We derive a new
85 algorithm for the estimation of a time-resolved recurrence amplitude spectrum and demonstrate its
86 advantages and limitations in comparison to classic approaches, in particular in regard to non-
87 sinusoidal signals. For this purpose, we use artificial data with known ground truth, as well as real
88 intracranial brain recordings from the human motor cortex of one epilepsy patient.

89

90 Methods

91

92 1. Basic definitions

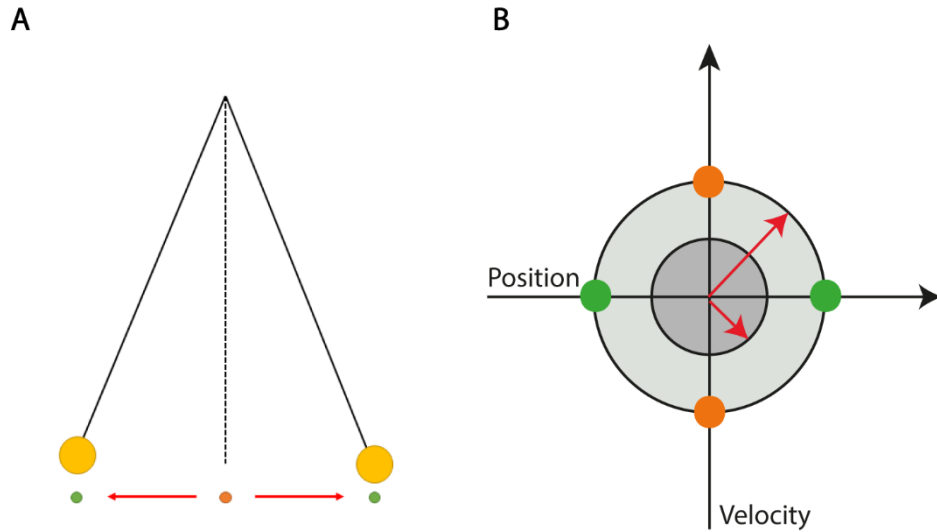
93 For the remainder of this paper, let x_t be the realizations of stochastic variables X_t at time t generating
94 a stochastic process X . Normal case letters indicate scalar valued observations, while bold letters
95 indicate d -dimensional vector valued states. A state is defined as a collection of past mostly
96 independent or temporally uncorrelated variables $X_{t-\Delta t}$, which are sufficient to predict the present
97 observation X_t . States can be reconstructed using Taken's delay embedding theorem (Takens 1981) by
98 time shifting the scalar time series X ($d-1$) times by a factor $\tau=\Delta t$.

$$\mathbf{x}_t^{d_x} = [X_{t-(d_x-1)\tau}, X_{t-(d_x-2)\tau}, \dots, X_{t-\tau}, X_t]^T, \quad (1)$$

99 with T indicating the transpose of the vector. The dimension d represents the minimum number of
100 degrees of freedom necessary to sufficiently describe the process X .

101 The collection of all realized states \mathbf{x}_t is defined as the state-space of process X . For example, a
102 perturbed frictionless pendulum creates a closed trajectory in a two-dimensional phase-space spanned
103 by the variables position and velocity (Figure 1). The coloured dots in Figure 1B correspond to the
104 pendulum positions shown in Figure 1A.

105



106

107 **Fig. 1: Example of a periodic phase-space representation.** A: A frictionless pendulum perturbed from its resting
 108 position (orange) to a new position with small amplitude (green). B: Phase-space representation of the pendulum
 109 with two different amplitudes (grey-shaded circles). The state of the pendulum is uniquely determined by its
 110 momentary position and velocity. Colored circles in b correspond to the positions shown in a. Lengths of the red
 111 arrows indicate the absolute amplitudes for both phase-space representations.

112

113 Assuming the process X to be Markovian, i.e. stochastic with finite memory, the dimension d and the
 114 delay τ can be reconstructed from univariate time series using Ragwitz criterion (Ragwitz and Kantz
 115 2002) or a combination of the false nearest neighbour algorithm (Hegger and Kantz 1999) and the
 116 auto-mutual information (Fraser and Swinney 1986) (for details see Supplement).

117 2. Quantification of recurrent states

118

119 2.1 Frequency estimation: the recurrence period

120 A state $\mathbf{x}_{t+\Delta t}$ is defined to be recurrent after Δt time steps, if it is within a neighbourhood U_ε of X_t with
 121 radius ε (Eckmann et al. 1987):

$$\mathbf{x}_{t+\Delta t}^{d_x} \in U_\varepsilon(\mathbf{x}_t^{d_x}) \quad (2)$$

122 For infinitely small neighbourhoods, i.e. $\varepsilon \rightarrow 0$, $\mathbf{x}_{t+\Delta t}$ is periodic with period Δt (Little et al. 2007). All
123 recurrences of an arbitrarily high dimensional phase-space may be represented by calculating a two-
124 dimensional binary recurrence matrix (Eckmann et al. 1987):

$$M_{t,t+\Delta t} = \Theta(\varepsilon - \|\mathbf{x}_t - \mathbf{x}_{t+\Delta t}\|) \quad (3)$$

125 Θ is the Heaviside step function and $\|\cdot\|$ is the Euclidean distance norm:

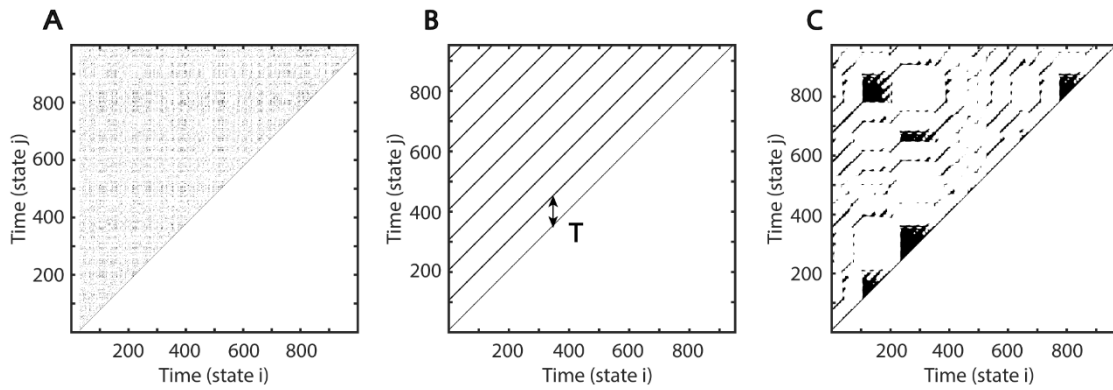
$$\|\mathbf{x}_t - \mathbf{x}_{t+\Delta t}\| = \sqrt{\sum_{i=1}^{d_x} (x_{i,t} - x_{i,t+\Delta t})^2}, \quad (4)$$

126 where i are the components of phase-space vectors. If $(\varepsilon - \|\mathbf{x}_t - \mathbf{x}_{t+\Delta t}\|)$ is negative Θ is 0 else 1. This
127 recurrence matrix M can be graphically represented by a recurrence plot, where each black dot
128 represents one recurrence of time i at time j (Figure 2).

129 Depending on the system's local dynamics, the recurrence plot depicts different motifs. Parallel
130 diagonal lines indicate periodicity and determinism while vertical lines appear due to laminar, i.e.
131 unchanging behavior. White corners arise because of slow drifts or non-stationarity and isolated dots
132 most often indicate stochastic behavior (Eckmann et al. 1987). The recurrence period T of any closest
133 temporal neighbor $\mathbf{x}_{t+\Delta t}$ of \mathbf{x}_t within a spatial neighbourhood U_ε may be estimated as the difference
134 (Little et al. 2007):

$$T = (t + \Delta t - \rho) - (t + \gamma), \quad (5)$$

135 where γ is the difference in samples between \mathbf{x}_t and \mathbf{x}_t first leaving U_ε and ρ is the sample difference
136 between \mathbf{x}_t reentering U_ε and $\mathbf{x}_{t+\Delta t}$ (Figure 3A). In the recurrence matrix, T is equal to the number of
137 states between vertical line segments starting from the main diagonal in M (see Figure 2B).



138

139 **Fig. 2: Examples of Recurrence Plots.** At each time i each black dot indicates a spatial recurrence at time j . Parallel
 140 lines indicate periodic activity. Recurrence plots show characteristic patterns depending on the system's
 141 qualitative dynamics: A: Random white noise. B: Sinusoid with period of 100 samples. C: Recurrence plot of a
 142 classic deterministic nonlinear system, i.e. the Lorenz system (Lorenz 1963).

143

144 2.2. Amplitude estimation

145 As can be seen in Figures 1B and 3A, recurrent systems form closed or nearly closed trajectories in
 146 phase-space. Here, the energy is contained in the phase-space volume of each recurrent state. In
 147 reference to our example, the phase-space portrait would increase in size, if the pendulum would be
 148 moved with a greater amplitude. Thus, a reasonable approximation of the amplitude of each period
 149 would be to estimate its maximum diameter in phase-space (see red arrows in Figure 1B).

$$\bar{a}_{diam}(T) = \sum_{k=1}^q \max \left\| \mathbf{x}_i - \mathbf{x}_j \right\| * q^{-1}, \forall i, j \in n \quad (6)$$

150 With q being the number of recurrences per T , i.e. how often a recurrence of duration T has occurred
 151 and n being the number of samples per recurrence (see Figure 3A).

152 This may be repeated for each recurrent trajectory per recurrence period T and subsequently averaged
 153 (Figure 3B).

154 2.3. Recurrence probability

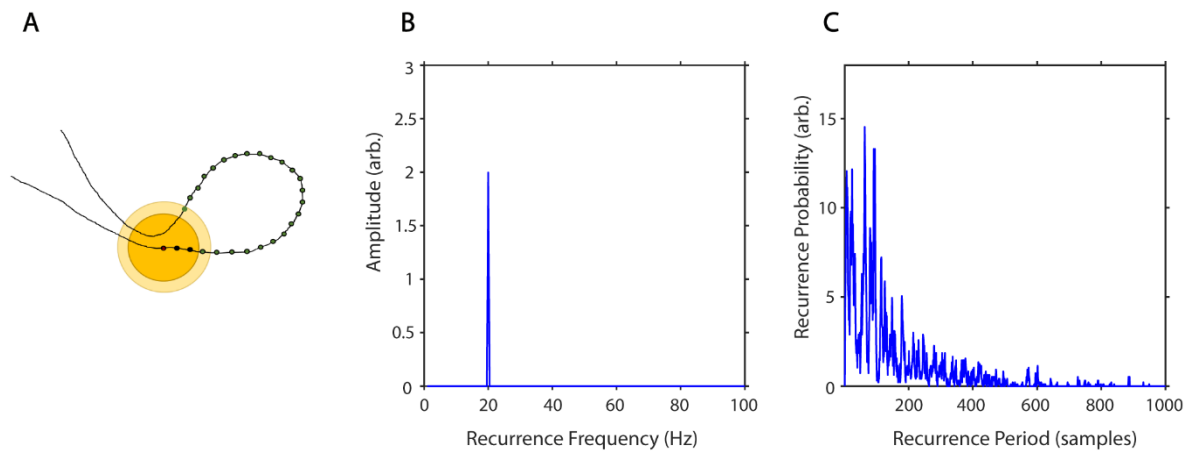
155 By estimating the recurrence period T for all phase-space vectors, it is possible to calculate a histogram
 156 $R(T)$, where the bin number is equal to the longest recurrence period T_{max} . The recurrence probability

157 may thus be estimated by normalizing $R(T)$ by the total number of recurrences (Figure 3C, Little et al.
158 2007). As noisy experimental data may lead to a high number of short period recurrences it is useful
159 to calculate $P(T)$ for a predefined range of T ($T_{min} - T_{max}$):

160

$$P(T) = \frac{R(T)}{\sum_{i=T_{min}}^{T_{max}} R(i)}, T = T_{min} \dots T_{max} \quad (7)$$

161



162

163 **Fig. 3: Estimation of recurrence periods.** A: A closed local trajectory in phase-space. A reference point (red) is
164 tracked in time until it reenters its spatial neighbourhood (examples of two neighbourhoods with different sizes
165 in yellow). In this example the recurrence period is equal to 23, as it takes 23 samples (green) until the trajectory
166 reenters the inner neighbourhood (dark yellow). B: Example estimation of recurrence amplitudes using the
167 maximum norm. Recurrence amplitude of 5 s of a 20 Hz periodic signal with an amplitude of two. C: Example
168 estimation of recurrence probabilities for a nonperiodic but highly recurrent deterministic system, i.e. the classic
169 Lorenz system (Lorenz 1963). The plot shows the recurrence probabilities of each period T .

170

171 Finally, we weight each estimated mean amplitude by its recurrence probability to get an average for
172 each recurrence frequency bin. This is equivalent to estimating the expected value of the amplitude
173 for every recurrence frequency:

$$A(T) = R(T) * \bar{a}(T) \quad (8)$$

174

175 Influence of neighbourhood ϵ on recurrence estimation

176 The recurrence probability is an estimate of the probability of a recurrence occurring after T time steps.

177 The estimation of P(T) is dependent on ϵ . A choice of ϵ too small would result in many empty

178 neighborhoods and thus in a high degree of statistical errors. If ϵ is chosen too large recurrences are

179 not local anymore and recurrence periods are underestimated. The recurrence period gets

180 approximately underestimated by two samples for every increase of ϵ by a multiple q of the sampling

181 period f_s (e.g. see the light yellow area in Figure 3A):

$$R_{err}(T, \epsilon_{err}) = R(T) - 2q, \quad (9)$$

182 with

$$\frac{\epsilon_{err}}{2} = \frac{\epsilon}{2} + q * \frac{1}{f_s}, \quad (10)$$

183 To better understand the influence of the parameter ϵ on recurrences, P(T) may be estimated over a

184 wide range of neighbourhood-sizes, resulting in a spatially-resolved recurrence period spectrum

185 (SREPS). In the SREPS, one would expect to find three regions of interest depending on ϵ . For very small

186 ϵ the SREPS is governed by statistical errors and a uniform distribution across all T. For very high ϵ the

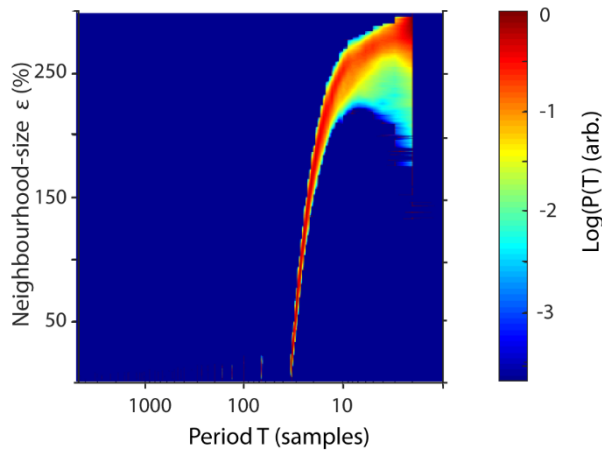
187 distribution of P(T) is heavily shifted to small T with only few state vectors leaving and reentering any

188 neighbourhood, with the extreme case of a neighbourhood-size fully engulfing the phase-space. If the

189 signal contains any oscillatory activity slowly shifting but continuous “spectral” peaks occur in the

190 intermediate range of ϵ . As stated above the best estimate of the recurrence period may thus be found

191 at the crossing of the continuous spectral peaks and the noise regime for low ϵ (Figure 4).



192

193 **Fig. 4: Spatially resolved recurrence probability.** The plot shows recurrence probabilities $P(T)$ of 50 s of a 3 Hz
 194 signal as a function of periods $T=1-5000$ samples and increasing neighbourhood-sizes $\epsilon=1-300$. ϵ is represented
 195 in % of the standard deviation of the raw time series.

196

197 3. Time-resolved recurrence amplitude

198 In neuroscientific research it is often of interest to analyse spectral activity changes relative to some
 199 intervention, e.g. some stimulus or response. For this purpose, methods like short-term Fourier or
 200 Wavelet transform estimate power spectral density as a function of time (Hramov et al. 2015).
 201 Similarly, the recurrence amplitude spectrum may be estimated for n short overlapping time windows
 202 w_n of definite length:

$$P(T, w_n) = \frac{R_*(T, w_n)}{\sum_{i=T_{\min}}^{T_{\max}} R(i, w_n)}, T = T_{\min} \dots T_{\max} \quad (11)$$

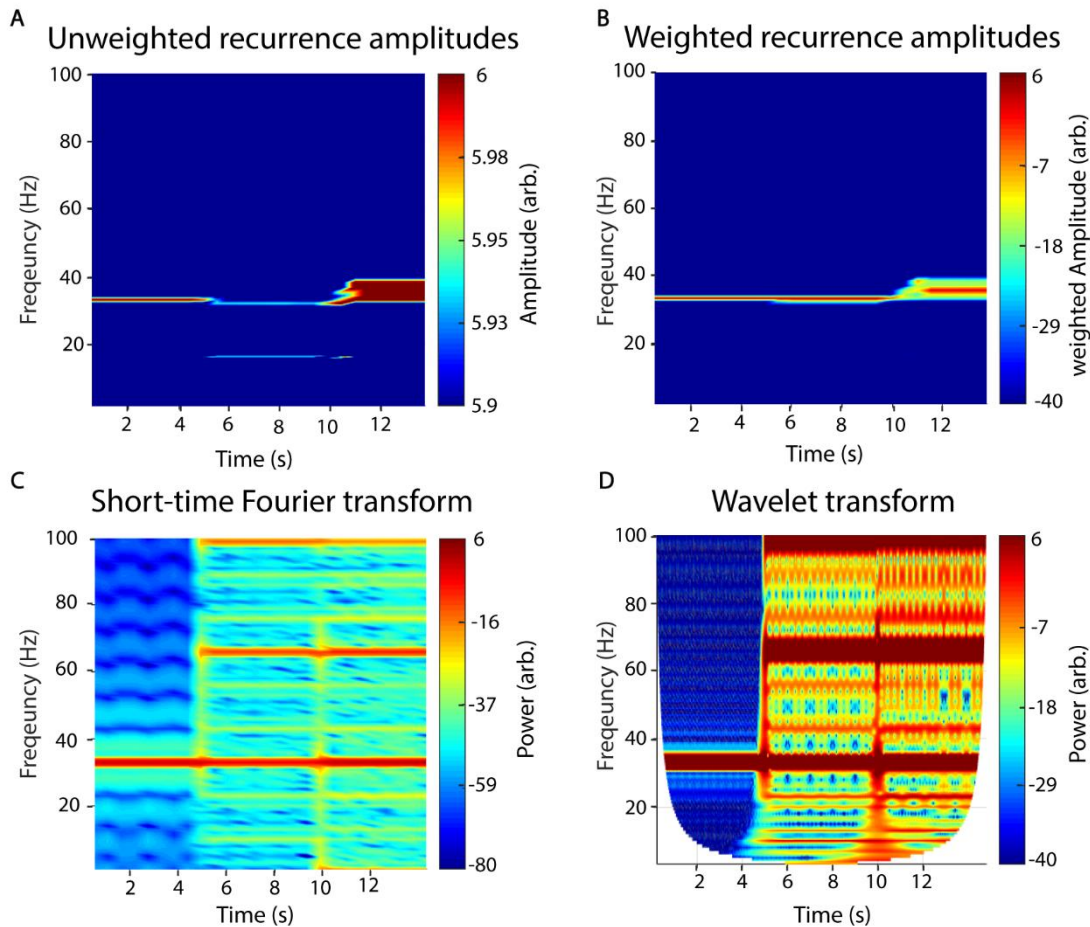
203 The length of each time window determines the maximum resolvable recurrence period and should
 204 thus be chosen with respect to the minimum frequency of interest.

205

206

207 4. Comparison between recurrence estimation, Fourier transform and wavelet transform

208 In Figure 5 we demonstrate the raw (Figure 5A) and weighted recurrence amplitude spectrum (Figure
209 5B) using an artificial signal of three signals of different concatenated waveform shapes, each with a
210 length of five seconds, a frequency of 33 Hz and an amplitude of two: 1) a sinusoid, 2) a sawtooth wave
211 and 3) a rectangle wave. While the frequency resolution succeedingly decreases for the three
212 waveform types using the raw amplitude spectrum, it stays nearly the same for the weighted
213 spectrum. However, the amplitude of the rectangle curve is slightly under- and its frequency slightly
214 overestimated. Using the weighted amplitude spectrum increased the frequency resolution for the
215 non-sinusoidal signals. For comparison with classic approaches, we analysed the same signal with
216 short-time Fourier Transform (STFT, Figure 5C) and Wavelet analysis (Figure 5D). For the recurrence
217 amplitude spectrum and the short-time Fourier spectrum we used 50 % overlapping windows of 600
218 ms lengths. For Wavelet analysis we used 30 cycles in order to approximate the window length for the
219 other methods (1s). For STFT and Wavelet analysis, spurious harmonics can be seen for the non-
220 sinusoidal waveform shapes in addition to the true frequency at 33 Hz. In contrast, the weighted
221 recurrence amplitude spectrum shows only one spectral peak at a relatively narrow frequency band.



222

223 **Fig. 5: Recurrence amplitude spectrum.** The recurrence amplitude spectrum of a compound signal of three 33

224 Hz oscillatory signals of different shapes is shown. The first five seconds are composed of a sine wave, the next

225 five seconds of a sawtooth wave and the last five seconds of a rectangle wave. A: Raw unweighted amplitudes.

226 B: Raw amplitudes were weighted with their respective probability densities. C: Short-time Fourier transform of

227 the same signal. Window length was set to 1s with 50% overlap. Note the spurious harmonics for the nonlinear

228 waveform shapes, i.e. rectangle (5-10s) and sawtooth shape (10 -15s). D: Wavelet transform of the signal.

229 Wavelet width was set to 18. Note the spurious harmonics for the nonlinear waveform shapes, i.e. rectangle (5-

230 10s) and sawtooth shape (10 -15s).

231

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233 5. Waveform-specific filter

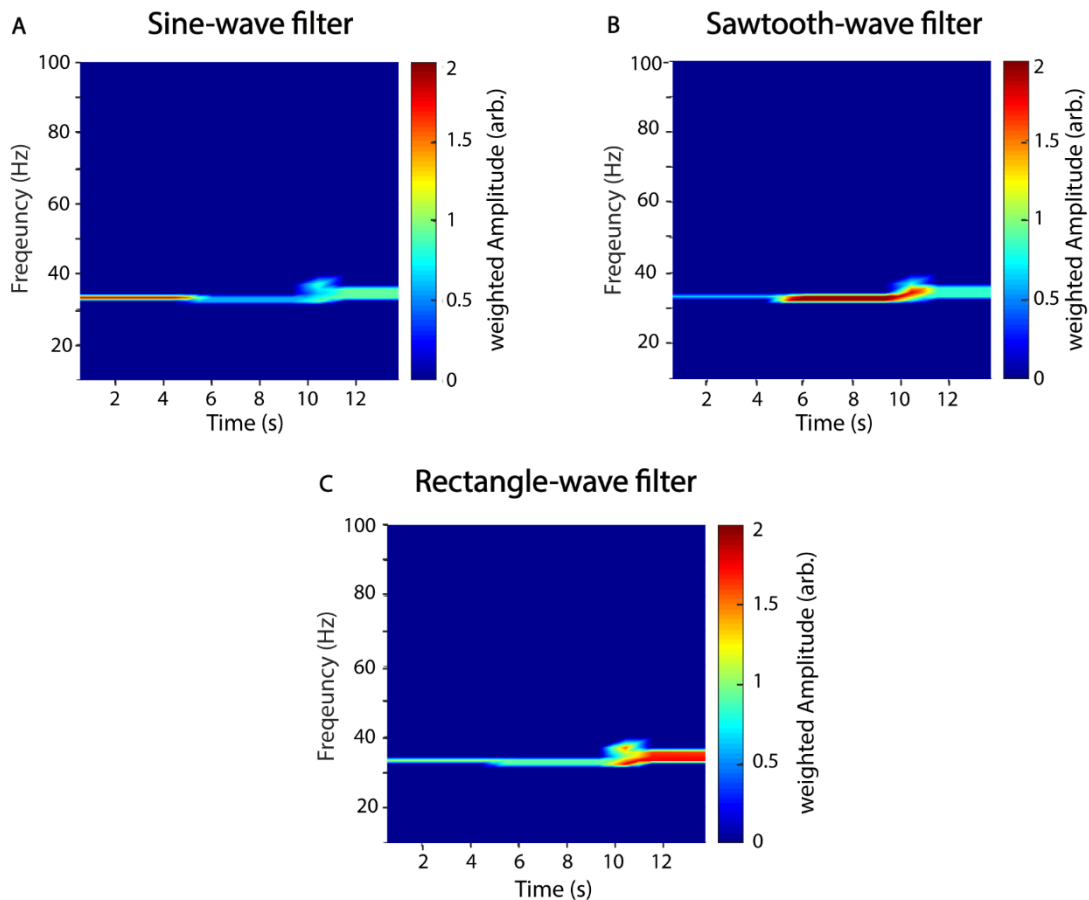
234 While the proposed estimator is independent of waveform, it is possible to tailor it to distinct
235 waveform shapes. For this, we introduce a gain factor to the amplitude estimation step which is simply
236 the Pearson correlation of the waveform shape of each recurrence and a scaled template waveform ζ .

$$\bar{a}(T) = \sum_{k=1}^q \max_{i,j} \left| \mathbf{x}_i - \mathbf{x}_j \right| * G^\alpha * q^{-1}, \forall i, j \in n \quad (12)$$

237 With α being chosen arbitrary and G being the gain factor:

$$G(k) = \max \left(\frac{\text{cov}(x, \zeta_m)}{\sigma_x \sigma_\zeta^m} \right), m = \zeta_m \dots \zeta_{m+T}, \quad (13)$$

238 with cov being the covariance, σ being the variance and ζ_m being the template waveform from sample
239 m to $m+T$. For perfectly matching waveforms, the gain is unity and thus the amplitude estimation is
240 unaffected (Figure 6). In Figure 6 we used the same artificial signal as in Figure 5 and analysed it using
241 waveform templates of a sinusoid (Figure 6A), sawtooth (Figure 6B) and rectangle shape (Figure 6C),
242 respectively. The exponent α determines the strength of the gain factor and thus how much specific
243 waveform shapes are filtered. In this example, it was set to five.



244

245 **Fig. 6: Recurrence amplitude spectrum with templates.** The recurrence amplitude spectrum of a compound
246 signal of three 33 Hz oscillatory signals of different shapes and a waveform dependent gain is shown. The first
247 five seconds are composed of a sine wave, the next five seconds of a sawtooth wave and the last five seconds of
248 a rectangle wave. Shown are the raw unweighted amplitudes. A: Five cycles of a sine wave were used as a shape
249 template. B: Five cycles of a sawtooth wave were used as a shape template. C: Five cycles of a rectangle wave
250 were used as a shape template. α was always set to 5. Window length was set to 1s with 50% overlap.

251

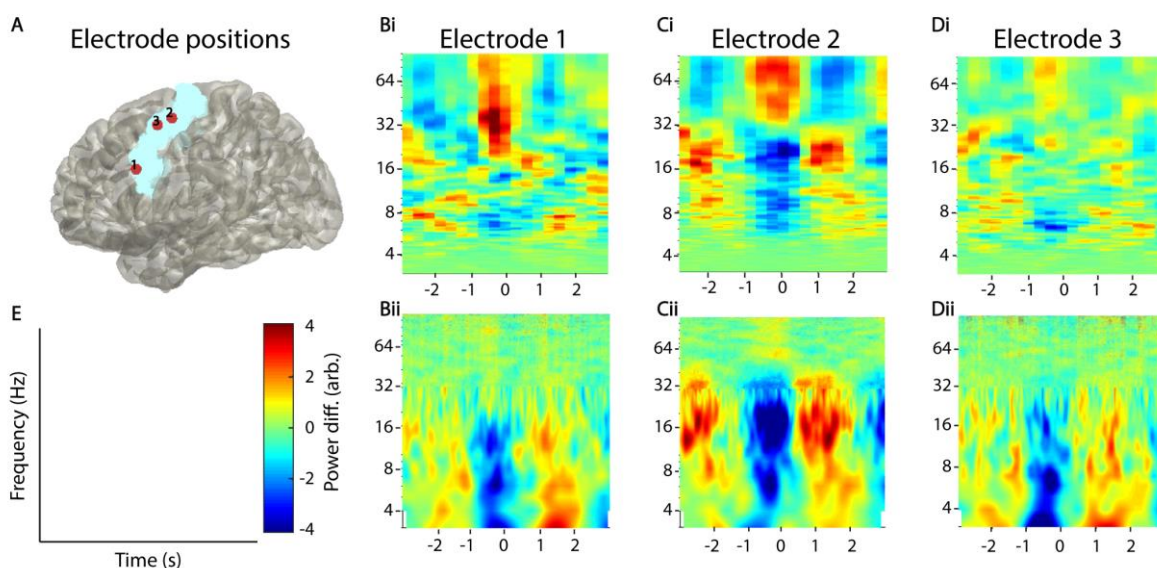
252 Example application

253 While the recurrence amplitude spectrum might be estimated for all types of oscillatory activity, it is
254 particularly suited for the analysis of electrophysiological neural activity. Thus, we briefly demonstrate
255 its application using intracranial brain recordings, from the motor cortex of one epilepsy patient. The
256 patient had received a 48 electrode electrocorticography (ECoG) grid for diagnostic purposes.
257 Electrodes were localized by co-registration of pre-operative MRI and post-operative CT scans using

258 the Fieldtrip toolbox (Oostenveld et al. 2011) (Figure 7A). As oscillatory activity in the motor cortex
259 has been well characterized in previous studies, we selected three electrodes located on the precentral
260 gyrus, i.e. the motor cortex (two medial electrodes in the proximity of the hand area and one lateral
261 electrode). Anatomical selection was based on the AAL atlas implemented in FieldTrip (Tzourio-
262 Mazoyer et al. 2002) (Figure 7A). We recorded electrophysiological data by means of the Neurofax-
263 system of Nihon Kohden (Nihon Kohden, Rosbach, Germany) at a sampling rate of 1000 Hz. The patient
264 participated in a study where he was asked to press a button on a standard computer keyboard. The
265 study protocol was approved by the medical ethics committee Marburg and conducted in accordance
266 with the latest version of the Declaration of Helsinki. To minimize edge effects occurring after
267 convolution with a wavelet kernel, we segmented the data into relatively large time intervals of two
268 seconds before until two seconds after response onset and discarded two seconds on each end of the
269 segment after wavelet convolution. We removed line-noise, visually rejected artifacts and performed
270 trend correction. We performed a response-locked data analysis, i.e. neural data is analysed time-
271 locked to the patient's button press. To this end, we used time-recurrence amplitude analysis and
272 compared results to classic time-frequency analysis, i.e. wavelet convolution, in order to analyse power
273 in different frequency bands.

274 We used window lengths of 600 samples (=1.67s) and 50% overlap for the time-resolved estimation of
275 recurrence amplitudes (Figure 7Bi, Ci, Di). Phase-space parameters, i.e. dimension d and delay τ were
276 optimized for each time window using false nearest-neighbourhood algorithm and auto-mutual
277 information, respectively. Neighbourhood-size was chosen ad-hoc at 70% of the standard deviation of
278 each time series. For comparison with classic methods, we used a combined wavelet (for frequencies
279 3-30 Hz) and multitaper approach (for frequencies above 30 Hz; Figure 7Bii, Cii, Dii), as suggested for
280 better frequency resolution and frequently adopted in the literature (van Vugt et al. 2007). To this end,
281 we convolved the data with a continuous complex Morlet wavelet with seven cycles. From the wavelet-
282 transformed signal, we extracted power values between 3 and 30 Hz in 1 Hz steps (lower frequencies
283 are difficult to estimate using wavelet convolution in short time windows). For the multi-taper analysis,

284 we used five tapers and a sliding 600 ms time window centered at one ms steps. Both spectra were
285 normalized, using the complete time-period as baseline. Using wavelet analysis, we found a
286 desynchronisation around the button press ($\sim -1 - 0$ ms), ranging across frequency bands delta to beta
287 ($\sim 3-32$ Hz) in all three electrodes (Figure 7C*Bii,Cii,Dii*). After the motor response (~ 1 s post-response),
288 we observed an enhancement in activity in this broad spectrum approximately one second after the
289 response. This this so-called rebound activity occurred in a broad frequency range from delta to low
290 gamma with it being most prominent in the beta band of electrode two. This beta rebound is a well-
291 described phenomenon in the motor cortex during motor tasks (Crone et al. 1998; Pfurtscheller and
292 Da Lopes Silva 1999; Jurkiewicz et al. 2006; Miller et al. 2007). Recurrence analysis showed a more
293 specific beta desynchronisation and rebound for electrodes two, which was also more narrow band.
294 In contrast to wavelet analysis, we additionally found a broad gamma activation during the button
295 press, which was most prominently followed by a gamma desynchronisation in electrode two, but also
296 visible in electrodes one and three to a lesser degree. In contrast, recurrence analysis did hardly reveal
297 any changes in the theta band. Taken together, recurrence analysis was more sensitive for broad band
298 high frequency activity that was not detected by wavelet convolution.



299

300 **Fig. 7: Example application on real invasive EEG data.** A: Selected electrodes in the motor area of one epilepsy
301 patient. The blue area indicates the precentral gyrus located with the AAL atlas in fieldtrip. Bi, Ci, Di: Recurrence
302 analysis of three example electrodes. Plots have been convolved with a 5x5 smoothing kernel for visualization
303 purposes. Bii, Cii, Dii: Corresponding Wavelet analysis of the same electrodes. All power values were normalized
304 with respect to the total power of the analysed time window.

305 Discussion

306 Here, we introduce a new method to analyse oscillatory activity in neural systems. We validated our
307 approach with synthetic data and demonstrate its application with real experimental ECoG data of one
308 epilepsy patient. Using artificial data, we show that the power estimates resulting from our method
309 are more frequency-specific for non-sinusoidal waveforms and are not associated with spurious
310 harmonics visible in the estimated frequency spectra. However, by applying specific waveform
311 templates we demonstrate that our method is also able to detect specific shapes if necessary. Using
312 human intracranial recordings from the motor cortex of one epilepsy patient, we show that recurrence
313 analysis compares to conventional methods, such as wavelet analysis and Fourier transformation, in
314 detecting movement-related oscillatory activity in the motor cortex.

315 With both methods, we found beta desynchronisation in the motor cortex around the button press
316 followed by beta rebound (Salmelin et al. 1995; Jurkiewicz et al. 2006; Parkes et al. 2006). Both
317 methods indicate that this effect is spatially specific, as it was most prominent in one of the two medial
318 electrodes in proximity of the hand area of the primary motor cortex.

319 Further, recurrence analysis was more sensitive for detecting broad band gamma activity that is
320 thought to represent multi-unit activity rather than narrow-band oscillations (Leszczyński et al. 2020).
321 Recurrence estimation was seemingly less sensitive for theta and delta oscillations revealed by wavelet
322 analysis. In contrast to beta activity in electrode two, theta/delta was more broadband in all three
323 electrodes for wavelet analysis and much more narrowband for recurrence analysis. It is possible that
324 this activity does not represent true oscillatory or recurrent activity, but rather local nonstationarities
325 or drifts, which can hardly be detected with recurrence analysis. This is because states of local
326 nonstationarities, even if they are oscillatory, do not come sufficiently close to each other after the full
327 period to enter their respective neighbourhoods.

328 Though only meant as a proof-of-principle analysis, this is the first time directly comparing classic
329 methods (i.e. wavelets and taper) with a recurrence based tool. Despite their fundamental differences
330 in estimation procedures it is nevertheless evident that both capture recurrent neural activity, which

331 validates both methodological concepts from different angles. However, discussing the mathematical
332 equivalence of recurrence analysis and classic methods is beyond the scope of this study and should
333 be analysed in future research.

334 Classically, neural oscillatory activity is analysed using methods derived from Fourier transform. Using
335 these methods, time series get decomposed into prototypical waveforms or “wavelets” e.g. sinusoids.
336 While this approach is justified by the understanding that e.g. EEG activity is a summation or
337 superposition of thousands of synchronously active cells (Buzsáki and Draguhn 2004), interpretation
338 of spectral estimation may be limited in some cases. This is because the generating models of neural
339 activity and thus the basal waveform shape is most often unknown. Decomposing an asymmetric or
340 nonlinear waveform into a series of sinusoids results in an infinite number of spurious harmonics (as
341 demonstrated in Figure 5C-D), which may be misinterpreted as independent oscillatory activity. Thus,
342 for such nonlinear signals classic techniques may generate a high degree of redundant information.
343 Note, however, that wavelet analysis is in theory capable of redundantly quantifying nonsinusoidal
344 oscillations by applying special mother wavelets e.g. like the Daubechies wavelets (Zhang et al. 2016).
345 However, one drawback is that using a specific mother wavelet would still restrict analysis to one
346 specific waveform shape and would also require prior knowledge, while recurrence based methods
347 may detect unspecified arbitrary shapes. It is also still very uncommon to use any other mother wavelet
348 than the Morlet wavelet for oscillatory analysis, although few studies exist that used other types to
349 detect recurring spiking events in the EEG (Milton 1994; Grubov et al. 2017). The problem of
350 nonsinusoidal waveform shape has been especially demonstrated for connectivity measures i.e. cross-
351 frequency coupling (Yeh et al. 2016; Lozano-Soldevilla et al. 2016). Occurrences of nonlinear signals in
352 electrophysiology are increasingly recognized to be commonly present in physiological (Arroyo et al.
353 1993; Gebber et al. 1999; Lozano-Soldevilla et al. 2016; Muthukumaraswamy et al. 2004) and
354 pathological states (Cole et al. 2017). The physiological meaning of waveform shape, however, is still
355 insufficiently understood (Cole and Voytek 2017).

356 The approach applied in this study utilizes the concept of recurrences in phase-space. The probability
357 of a state recurrence as a function of its period has been previously introduced by Little et al. (2007).
358 Our method builds upon this by also estimating amplitudes, i.e. energy content of a recurrence by
359 estimating the phase-space volume of the recurrence. Additionally, by windowing the estimation
360 procedure it is also possible to calculate a time-resolved recurrence amplitude spectrum, similar to
361 short-time Fourier transform or wavelet analysis. The major difference to Fourier-based techniques is
362 that time series are not fitted to basal waveforms in a “model-based” kind of way. Instead, it is
363 quantified after what time the system reassumes a previous state, independent of the specific
364 waveform in between these recurrences. Thus, as has been demonstrated in this study, simple
365 asymmetric waveforms can be described more parsimoniously, without any spurious harmonics
366 (Figure 5A-B). The most extreme example of this is a rhythmic idealized Dirac pulse, which has unity
367 power over all frequencies in Fourier space (Beerends 2006), but can be parsimoniously represented
368 with recurrence based methods. Thus, another possible application of our proposed method might be
369 analysis of spike train or electromyography data (EMG). The problems regarding the analysis of the
370 latter with Fourier-based methods is widely recognized, which is why EMG data is often additionally
371 preprocessed by e.g. extracting the Hilbert envelope or taking the absolute value (Myers et al. 2003).
372 These preprocessing steps may, however, lead to spurious results depending on further analysis
373 (Negro et al. 2015; McClelland et al. 2012).

374 *Parameters of recurrence analysis*

375 While the concept of recurrences in phase-space is well established in other scientific fields e.g.
376 climatology (Beaufort et al. 2001), proteomics (Webber et al. 2001) or geology (Donner et al. 2019), it
377 is still scarcely applied in neurosciences. Examples include classification of mild cognitive impairment
378 (Timothy et al. 2017), multiple sclerosis (Carrubba et al. 2019) or emotional states (Khodabakhshi and
379 Saba 2020). One possible reason for this might be the number of parameters which need to be
380 adjusted. While the algorithm is not parametric, i.e. not model-based *per se*, the estimation procedure
381 may be sensitive to several key parameters due to the finiteness of measured data. These most

382 prominently include the neighbourhood-size ϵ and the embedding parameters d and τ . For perfectly
383 periodic recurrences and infinitely precise sampled data, the neighbourhood-size may be chosen
384 arbitrarily small. However, for experimental data ϵ should be ideally chosen to barely engulf most of
385 recurrent states. If the neighbourhood-size is chosen too large, recurrence periods get underestimated
386 for every multiple of the sampling frequency. If ϵ is chosen slightly too small, recurrences might be
387 missed. This may result in “harmonics”, i.e. multiples of recurrence periods appearing in the spectrum,
388 as recurrences missed in one period might get detected in the next one (as can be seen in Figure 4).
389 However, as our algorithm weights amplitudes by their probability of occurrences, few missed
390 recurrences do not severely impact the overall spectrum. In the case that ϵ is chosen much too small,
391 all meaningful recurrences might be missed and the spectrum gets dominated by measurement noise.
392 The choice of ϵ thus depends on experimental data. However, it is important to note, that for real
393 experimental data, there is no true neighbourhood-size as neural systems are hardly ever perfectly
394 periodic. For intermediate ranges of ϵ recurrence spectra are rather stable and frequencies should only
395 slowly shift (Figure 4). Nevertheless, when reporting results, neighbourhood and embedding
396 parameters should always be reported for reproducibility. One possible approach to optimise
397 neighbourhood-size is to estimate the recurrence amplitude spectrum as a function of ϵ and visually
398 identify the noise regime for small neighbourhood-sizes (Figure 4). However, as this might be quite
399 computationally demanding, it suffices to estimate the non-time resolved spectrum for a subsample
400 of the data. This is justified if the variance of noise is static over time. The subset should be chosen
401 long enough to cover the longest recurrence period of interest.

402 Of similar importance is an appropriate embedding of the measured data in phase-space. If the
403 embedding dimension is too low, points which are far away from each other might get projected into
404 close proximity. Thus, the time in between might be spuriously characterized as a specific recurrence
405 period. On the other hand, if the embedding dimension is too high, estimation of recurrence periods
406 becomes increasingly computational demanding and neighbouring points difficult to detect due to the
407 increasing spaces between points otherwise known as “curse of dimensionality”. The embedding delay

408 is important for spreading out the phase-space volume. A delay which is too small would result in all
409 points laying on the first intersect and thus no closed trajectories to measure. For our algorithm we
410 used the well-established false-nearest neighbours algorithm (Hegger and Kantz 1999) for the
411 optimization of the embedding dimension and the auto-mutual information (Fraser and Swinney
412 1986). However, other techniques like e.g., the Ragwitz-algorithm are also frequently reported to
413 optimize embedding parameters (Ragwitz and Kantz 2002; Michael Lindner et al. 2011; Weber et al.
414 2020, supplementary methods). By automatically optimizing d and τ we effectively eliminate these
415 parameters, which makes the estimation procedure much easier to apply. This procedure is well
416 established and implemented in many toolboxes utilizing the concept of phase-space analysis (Michael
417 Lindner et al. 2011; Lizier 2014; Donges et al. 2015).

418 One limitation of the recurrence analysis is that it is by design not able to decompose a linear
419 superposition of sine waves. For such artificially generated signals classic approaches are better suited.
420 We thus propose to apply the demonstrated technique complementary in conjunction with classic
421 approaches e.g. to discern possible spurious harmonics.

422

423 Conclusion

424 In this study, we introduced a new time-resolved technique to measure amplitudes of oscillatory
425 signals in a waveform independent manner. This method estimates the energy of recurrent activity by
426 measuring distances of closed trajectories in phase-space, which are subsequently weighted by their
427 respective probability densities. Using artificial data, we demonstrate that the measure generates less
428 spurious harmonics due to nonlinear waveform shapes in comparison to classic techniques like Fourier
429 Transform. Further, the analysis of intracranial data of one epilepsy patient indicates that recurrence
430 might be better suited to estimate high frequency activity than congenital methods, such as wavelet
431 analysis or the Fourier transform. In addition, we show that recurrence analysis can be used to
432 specifically analyse signals with defined waveform shapes. In summary, the proposed measure might

433 be well suited to complement classic frequency techniques, especially when the analysed signals are
434 of nonlinear origin.

435 Code availability statement

436 All code used in this study is readily available at https://nolitia.com/Code_recurrence_paper.zip.

437

438 Literature

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