Flaws in Data Binning for Population Receptive Field Analyses

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Abstract

Data binning can cope with overplotting and noise, making it a versatile tool for comparing many observations. However, it goes awry if the same observations are used for *binning* and *contrasting*. This creates an inherent circularity, leaving noise and *regression to the mean* insufficiently controlled. Here, we use population receptive field analyses – where data binning is commonplace – as an example to expose this flaw through simulations and empirical repeat data.

¹ Main text

² Data binning is often applied to large data sets in order to prevent overplotting
³ and control noise. As such, it has become commonplace in population receptive
⁴ field (pRF) modeling (Dumoulin & Knapen, 2018; Dumoulin & Wandell, 2008),

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where researchers are commonly interested in comparing visual field maps with 5 thousands of observations between different (experimental) conditions. However, 6 pRF modeling is only one out of several research areas where some form of differential 7 data binning has been adopted, such as psychology (Gignac & Zajenkowski, 2020; 8 Holmes, 2009; Preacher, MacCallum, Rucker, & Nicewander, 2005; Shanks, 2017), 9 systems neuroscience (Holmes, 2009; Kriegeskorte, Simmons, Bellgowan, & Baker, 10 2009), epidemiology (Barnett, van der Pols, & Dobson, 2005), and presumably many 11 more. 12

Although differential data binning can help us see an overall pattern in the face 13 of an abundance of details, it goes awry if the same noisy observations are used for 14 *binning* (selection) and *contrasting* (selective analysis). This is because dipping into 15 noisy data more than once violates assumptions of independence, favoring some noise 16 components over others, and eventually biasing descriptive and inferential statistics 17 (Kriegeskorte et al., 2009). As such, double-dipping in differential data binning 18 prevents us from – amongst other things – controlling for regression to the mean 19 (e.g., Galton, 1886; Gignac & Zajenkowski, 2020; Holmes, 2009; Makin & De Xivry, 20 2019; Shanks, 2017). Regression to the mean is a statistical phenomenon operating 21 when two variables are imperfectly correlated (e.g., due to random noise). In this 22 case, extreme observations for one variable will on average be less extreme (closer to 23 the mean) for the other variable (Campbell & Kenny, 1999; Cohen, Cohen, West, 24 & Aiken, 2003; Shanks, 2017)¹. The magnitude of regression to the mean tends to 25 be higher the lower the correlation between the variables. 26

Regression to the mean and/or double-dipping are of particular concern in what is better known as *post hoc subgrouping* (Preacher et al., 2005), *post hoc data selection* (Shanks, 2017), and *extreme groups approach* (Preacher et al., 2005), all of which can be considered as subtypes of data binning. Post hoc subgrouping refers to collecting two measures, defining extreme subgroups post hoc using one measure (e.g., the lower and upper quantile), and then performing statistics on these mea-

¹To be precise, regression to the mean refers to standard scores (z-scores; Campbell & Kenny, 1999; Kenny, 2005).

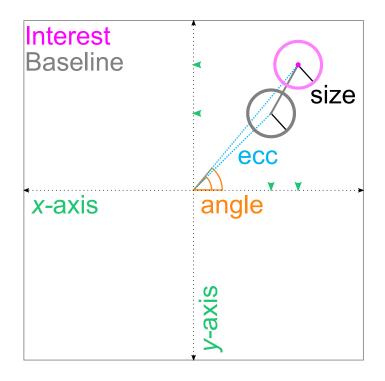


Figure 1. **Population receptive field estimates.** The two circles represent a pRF that changes its position (gray solid line) in an Interest (magenta) compared to a Baseline (gray) condition. The black solid square represents a cutout of the visual field and the black dashed arrows a Cartesian coordinate system. The pRF was modeled as a 2D Gaussian function. The center of the 2D Gaussian (tiny gray dot and small magenta dot) represents the position of the pRF. PRF position can be expressed in terms of x_0 and y_0 coordinates (green arrow heads) or eccentricity (blue dashed line) and polar angles (orange solid line). Eccentricity corresponds to the Euclidean distance between the center of gaze (origin) and the center of the 2D Gaussian. Polar angle corresponds to the counter-clockwise angle running from the positive *x*-axis to the eccentricity vector. The standard deviation of the Gaussian (1σ ; black solid line) represents pRF size. Both pRF position and size are typically expressed in degrees of visual angle. Polar angles are typically expressed in degrees. Ecc = eccentricity. pRF = population receptive field.

sures for the extreme subgroups (Preacher et al., 2005). Post hoc data selection 33 is similar but involves only one extreme subgroup (Shanks, 2017). Both of these 34 practices are different from the extreme groups approach, where extreme subgroups 35 are selected a priori based on one measure; that is, without collecting the whole 36 range of the other measure (Preacher et al., 2005). Here, we focus on a post hoc 37 scenario where essentially all subgroups are considered, not just the extreme ones 38 (see also Gignac & Zajenkowski, 2020; Holmes, 2009). We label this procedure post 30 hoc binning analysis. 40

Imagine we conduct a retinotopic mapping experiment (Dumoulin & Wandell,

2008), where we estimate pRF position and size for each voxel in the brain under 42 a Baseline condition as well as a condition of Interest (see Figure 1 for a single 43 pRF). We can think of the Interest and Baseline conditions as repeat data (e.g., 44 Benson et al., 2018; van Dijk, de Haas, Moutsiana, & Schwarzkopf, 2016), different 45 attention conditions (e.g., de Haas, Schwarzkopf, Anderson, & Rees, 2014; Klein, 46 Harvey, & Dumoulin, 2014; van Es, Theeuwes, & Knapen, 2018; Vo, Sprague, & 47 Serences, 2017), mapping sequences (e.g., Binda, Thomas, Boynton, & Fine, 2013; 48 Infanti & Schwarzkopf, 2020), mapping stimuli (e.g., Alvarez, de Haas, Clark, Rees, 49 & Samuel Schwarzkopf, 2015; Binda et al., 2013; Le, Witthoft, Ben-Shachar, & 50 Wandell, 2017; Yildirim, Carvalho, & Cornelissen, 2018), scotoma conditions (e.g., 51 Barton & Brewer, 2015; Binda et al., 2013; Haak, Cornelissen, & Morland, 2012; 52 Prabhakaran et al., 2020), pRF modeling techniques (e.g., Carvalho et al., 2020) or 53 uni- and multisensory conditions (Holmes, 2009) – to name but a few examples. As 54 a pRF model, we adopt a 2D Gaussian, where pRF position represents the center of 55 a pRF in visual space (the center of the Gaussian) and pRF size its spatial extent 56 (the standard deviation of the Gaussian; see Figure 1). We then fit this model to 57 the voxel-wise brain responses we measured in the retinotopic mapping experiment 58 (Dumoulin & Wandell, 2008). To compare pRF positions in the Interest and Baseline 59 condition voxel-by-voxel, we bin the pRF positions from both conditions according 60 to the pRF positions from the Baseline condition. Subsequently, we quantify for each 61 voxel the position shift from the Baseline to the Interest condition (see Figure 1 for 62 a single pRF). Finally, we calculate the bin-wise mean shift. This is conceptually 63 equivalent to calculating the bin-wise simple means for each condition and comparing 64 them subsequently, be it descriptively or inferentially. 65

Either way, by adopting such a post hoc binning analysis, we essentially assume that the mean pRF position we quantify for each bin in the Baseline condition approximates the true mean pRF position. In particular, we presuppose that binning voxels according to pRF positions from the Baseline condition and aggregating them subsequently for this condition ensures that bin-wise noise components cancel out on average (see also Shanks, 2017). This, however, is not the case.

To illustrate this flaw, we generated a simplified contrast scenario with a null ef-

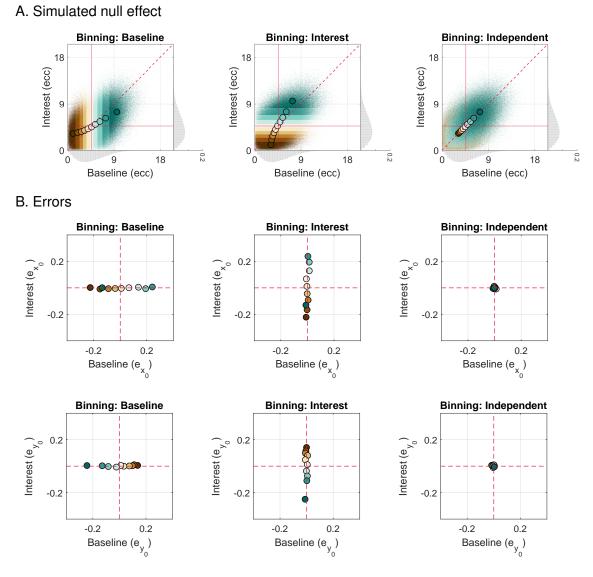


Figure 2. Simulated 1D post hoc binning analysis on eccentricity | Null effect. A. Bin-wise eccentricity values and means in the Interest and Baseline condition for a simulated null effect and different data binning scenarios. Eccentricity values in the Baseline and Interest condition were either binned according to eccentricity values in the Baseline (1st column), Interest (2nd column), or an Independent condition (equivalent to repeat data of the Baseline condition; 3rd column). The gray marginal histograms (bin width = 0.5 dva; *y*-axis: relative frequency) show the simulated eccentricity distributions for each condition, obtained by repeatedly disturbing the x_0 and y_0 values of an empirical visual field map with random Gaussian noise (sd = 2 dva) and subsequently converting them to eccentricity values. Note that the range of the marginal *y*-axis is the same for all histograms. The red crosshair indicates the location of the overall mean for the Interest and Baseline condition. The red dashed line corresponds to the identity line. **B.** Bin-wise mean errors for the x_0 and y_0 values in the Interest and Baseline condition for the same binning scenarios as in A. The dashed red lines reflect the zero error line. Dark brown colors correspond to lower and dark blue-green colors to higher decile bins. The maximal eccentricity of the stimulated visual field area subtended 8.5 dva. Dva = Degrees of visual angle. Ecc = Eccentricity.

fect. In particular, we used random Gaussian noise to repeatedly disturb voxel-wise 73 x_0 and y_0 coordinates (Figure 1) of a V1 visual field map from a single participant 74 $(N_{repeat} = 200; sd_{noise} = 2 \text{ degrees of visual angle, dva})$. We did this twice to gener-75 ate a Baseline and an Interest condition. We then converted the voxel-wise x_0 and 76 y_0 samples to eccentricity values (Figure 1), as is often done in the pRF literature 77 (see Figure 1-figure supplement 1 for interpretational difficulties with eccentricity 78 when it comes to position shifts). This resulted in a gamma-like eccentricity dis-79 tribution. Lastly, we binned the eccentricity values in both conditions according 80 to the eccentricity values in the Baseline condition using deciles and calculated the 81 bin-wise means for each condition². 82

We plotted the bin-wise eccentricity means in the Baseline and Interest condi-83 tion against one another along with individual observations per bin and marginal 84 histograms (bin width = 0.5 dva) reflecting the simulated distributions³ (Figure 2, 85 A., 1st column). Importantly, since there was no true difference between conditions, 86 the bin-wise means should lie on the identity line. Contrary to this prediction, the 87 bin-wise means systematically diverged from the identity line. Strikingly, when us-88 ing the Interest instead of the Baseline condition for binning, the systematic pattern 89 of divergence flipped (Figure 2, A., 2nd column). This bidirectionality is a typical 90 sign of regression to the mean (Campbell & Kenny, 1999; Shanks, 2017) and due 91 to circularity that leads to asymmetric bins (see bin-wise ranges of observations for 92 Baseline and Interest, Figure 2, A., 1st and 2nd columns) and biases bin-wise noise 93 components. In particular, for the condition that was used for contrasting and bin-94 ning (henceforth *circular* condition), the bin-wise noise components of the x_0 and 95 y_0 values were skewed on average. For the other condition (henceforth non-circular 96 condition), however, the bin-wise noise components cancelled out on average (Fig-97

²Note that when evaluating data distributions with unequal means, variances, or non-linearity, z-standardization might be necessary to detect regression to or away from the mean (Campbell & Kenny, 1999; Shanks, 2017). In particular, z-standardization makes data distributions directly comparable. As such, bin-wise means should regress to wherever they intersect the identity line. Here, we always display data in native space, as this is typically done in the pRF literature. However, we use crosshairs to indicate the location of the mean and thus provide a visual guideline.

 $^{^{3}}$ Note that apart from the visualizations provided here, it might be beneficial to additionally look at Galton squeeze diagrams to detect regression to or away from the mean (Campbell & Kenny, 1999; Shanks, 2017).

 $_{98}$ ure 2, B., 1st and 2nd columns).

The skew in average noise renders the bin-wise eccentricity means of the circular 99 condition more extreme, especially for lower and higher decile bins. As a result, 100 the bin-wise eccentricity means for the non-circular condition regress – by statistical 101 necessity - to the overall mean⁴ for this condition (red crosshair); that is, they are 102 less extreme (see different ranges of bin-wise means for the circular and non-circular 103 conditions in Figure 2, A., 1st and 2nd columns). If the Interest condition is then 104 contrasted to the Baseline condition, a mean increase in eccentricity for lower deciles 105 and a mean decrease for higher deciles or vice versa occurs, depending on whether 106 the data are binned on the Baseline or Interest condition (Figure 2, A., 1st and 2nd 107 column). This artifact arises because we did not use independent conditions for 108 binning and contrasting; that is, conditions with independent noise components. 109

Importantly, how the artifact manifests can change when data are thresholded 110 across conditions (i.e., corresponding observations are deleted in a pair-wise fashion; 111 Figure 2-figure supplement 1-2, A. and B., 1st and 2nd columns) and/or noise scales 112 with eccentricity (heteroskedasticity; Figure 2-figure supplement 3, A. and B., 1st 113 and 2nd columns; see also Holmes, 2009). In fact, in the event of cross-thresholding, 114 noise components are modified and might not necessarily cancel out for the non-115 circular condition (Figure 2-figure supplement 1-2, B., 1st and 2nd columns). The 116 case of eccentricity-scaled noise furthermore shows that the artifact can include some 117 clear regression away from the mean⁵ (egression; Figure 2-figure supplement 3, A., 118 1st and 2nd columns; e.g., Campbell & Kenny, 1999; Schwarz & Reike, 2018). 119

¹²⁰ Condition cross-thresholding is common practice in the pRF literature where ¹²¹ data are cleaned across conditions according to eccentricity, goodness-of-fit (R^2) , ¹²² pRF size, missing data or other criteria from one or multiple conditions. Eccentricity-¹²³ scaled noise is an equally likely scenario that might arise from fitting errors due to

⁴Note that for skewed distributions (such as the gamma-like distribution here), the regression effect might be actually towards the mode and away from the mean of the overall distribution (Schwarz & Reike, 2018). If the location of the overall mode and mean are sufficiently close, our visualizations would be unable to distinguish these two cases.

⁵Note that the regression was presumably towards the nearest modes of the simulated bimodal distribution (see marginal histograms in Figure 2-figure supplement 3, A., 1st and 2nd columns; Schwarz & Reike, 2018).

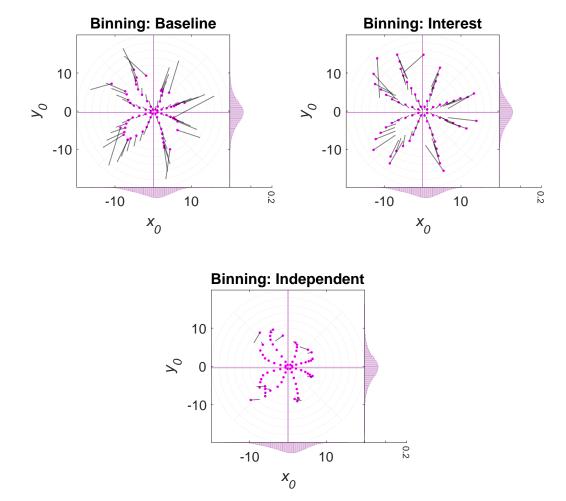


Figure 3. Simulated 2D post hoc binning analysis on x_0 and y_0 | Null effect. Bin-wise x_0 and y_0 means in the Interest and Baseline condition for a simulated null effect and different data binning scenarios. X_0 and y_0 values in the Baseline and Interest condition were either binned according to eccentricity and polar angle values in the Baseline (1st column, 1st row), Interest (2nd column, 1st row), or an Independent condition (equivalent to repeat data of the Baseline condition; 2nd row). The marginal histograms (bin width = 0.5 dva; *y*-axis: relative frequency) show the simulated x_0 and y_0 distributions for each condition, obtained by repeatedly disturbing the x_0 and y_0 values of an empirical visual field map with random Gaussian noise (sd = 2 dva). Magenta histograms correspond to the Interest condition and gray histograms to the Baseline condition. Note that the range of the marginal *y*-axis is the same for all histograms. The large magenta dots (arrow tip) correspond to the means in the Interest condition and the tiny gray dots (arrow knock) to the means in the Baseline condition. The gray line (arrow shaft) depicts the shift from the Baseline to the Interest condition and the tory of the overall means for the Baseline condition. Please note that if there is no systematic difference between the Baseline and Interest condition, the histograms and crosshairs coincide (as is the case here). The light gray radar grid demarks the bin segments. Polar angle bins ranged from 0° to 360° with a constant bin width of 45° and eccentricity bins from 0 to 20 dva with a constant bin width of 2 dva. The maximal eccentricity of the stimulated visual field area subtended 8.5 dva. Dva = Degrees of visual angle.

Simulated null effect

partial stimulation of pRFs (especially near the edge of the stimulated mapping
area), higher variability in pRF position estimates for wider pRFs as well as fluctuations in the signal-to-noise ratio of brain responses due to central fixation and/or
manipulating attention across visual space⁶.

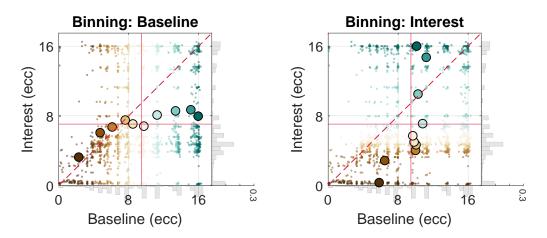
The artifact also replicated when simulating a true effect (i.e., a radial shift of 2 128 dva in the Interest condition; Figure 2-figure supplement 4, A. and B., 1st and 2nd 129 columns). The same was true for equidistant binning (Figure 2-figure supplement 5, 130 A. and B., 1st and 2nd columns), which is frequently applied in the pRF literature. 131 However, unlike decile binning, equidistant binning resulted in a lower number of 132 observations for higher equidistant bins (due to the gamma-like eccentricity distri-133 bution; Figure 2-figure supplement 5, A., 1^{st} and 2^{nd} columns). Consequently, for 134 higher equidistant bins, the skew in average noise for the circular condition was 135 generally larger here. Similarly, for higher equidistant bins, noise components did 136 not always cancel out for the non-circular condition (see all Figure 2-figure supple-137 ment 5, B., 1^{st} and 2^{nd} columns). This is because for random noise to cancel out on 138 average, the number of observations needs to be sufficiently large. 139

For all presented simulation cases, the artifact likewise manifested for another kind of binning analysis, namely, when binning the x_0 and y_0 values according to both eccentricity and polar angle (i.e., 2D segments) and computing shift vectors (Figure 1 as well as Figure 3 and Figure 3-figure supplement 1-4, 1st row). Here, the bin-wise means regressed towards and away from the overall means of the x_0 and y_0 distribution.

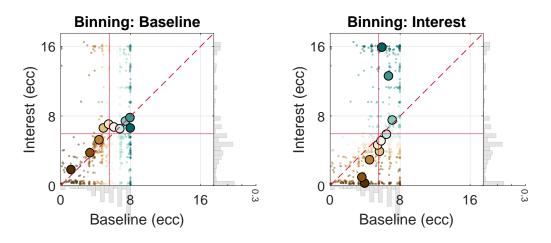
Notably, for empirical repeat data from the Human Connectome Project (Benson et al., 2018, 2020), both kinds of binning analyses produced patterns consistent with the artifact (Figure 4-5 and Figure 4-figure supplement 1-3 and Figure 5-figure supplement 1-3, A.-C.). This establishes its practical relevance. Moreover, some of us recently retracted an article on attention-induced differences in pRF position

⁶Note that floor/ceiling effects (due to physiological and methodological constraints on the minimum and maximum observable value) and/or the calculation of absolute (raw) vs proportional (%) differences are further factors influencing the artifact's appearance (de Haas et al., 2014; de Haas, Schwarzkopf, Anderson, & Rees, 2020; Holmes, 2009).

A. Empirical repeat data | 25th %ile | Dorsal



B. Empirical repeat data | 25th %ile | Dorsal – Cross-thresholding (Baseline)



C. Empirical repeat data | 25th %ile | Dorsal – Cross-thresholding (Baseline and Interest)

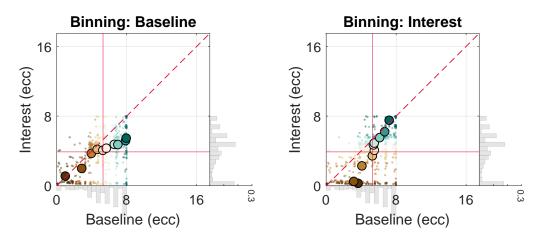


Figure 4. Caption on next page.

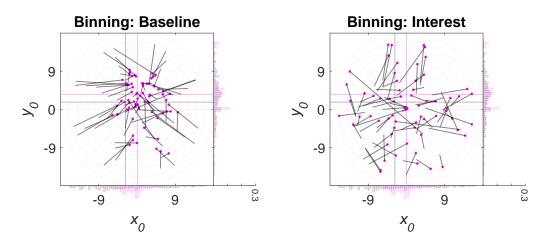
Figure 4. Empirical 1D post hoc binning analysis on eccentricity | Repeat data | 25th %ile participant | Dorsal. Bin-wise eccentricity values and means in the Interest and Baseline condition for repeat data from the HCP belonging to the 25th %ile participant of the median R^2 distribution and different data binning scenarios. **A.** Data from the dorsal complex (V3A/B and IPS0–5) without condition cross-thresholding. **B.** Same as A., but with condition cross-thresholding. To this end, eccentricity values falling outside a certain eccentricity range (≥ 0 and ≤ 8 dva) and below a certain R^2 cut-off ($\leq 2.2\%$) in the Baseline condition were removed from both conditions. **C.** Same as B., although here, condition cross-thresholding was based on both the Baseline and Interest condition. Eccentricity values in the Baseline and Interest condition were either binned according to eccentricity values in the Baseline (1st column in A.-C.) or Interest (2nd column in A.-C.) condition. The gray marginal histograms (bin width = 0.5 dva; y-axis: relative frequency) show the eccentricity distributions for each condition. Note that the range of the marginal y-axis is the same for all histograms. The red crosshair indicates the location of the overall mean for the Interest and Baseline condition. The red dashed line corresponds to the identity line. Dark brown colors correspond to lower and dark blue-green colors to higher decile bins. The maximal eccentricity of the stimulated visual field area subtended 8 dva. HCP = Human connectome project. Dva = Degrees of visual angle. Ecc = Eccentricity. %ile = percentile.

and size in V1-V3 (de Haas et al., 2014) because an in-house reanalysis suggested that post hoc binning along with condition cross-thresholding and heteroskedasticity yielded artifactual (or artifactually inflated) results in the form of egression from the mean (de Haas et al., 2020). In this case, the apparent significant effect was an increase in eccentricity and pRF size in the Interest vs Baseline condition for eccentricity bins in the middle of the tested range.

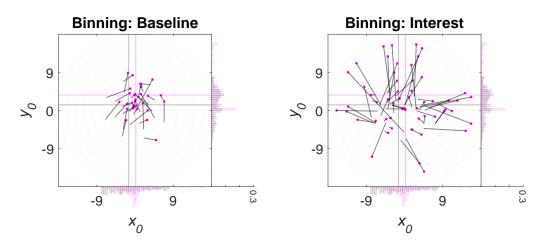
Taken together, the heterogeneity in manifestation we exposed here makes it hard to spot the artifact by visual inspection alone and highlights its dependency on exact distributional properties of the data at hand (see also Campbell & Kenny, 1999; Holmes, 2009; Schwarz & Reike, 2018, for similar points).

How can we omit double-dipping and control for regression to the mean? We 161 could, for instance, use an Independent condition for binning (such as repeat data or 162 odd or even runs for the Baseline condition; Figure 2 and Figure 2-figure supplement 163 1-5, A., 3rd column as well as Figure 3 and Figure 3-figure supplement 1-4, 2rd row) 164 or an anatomical criterion (Kriegeskorte et al., 2009), such as cortical distance. 165 This way, noise components should nullify on average in both the Baseline and 166 Interest condition (Figure 2 and Figure 2-figure supplement 1-5, B., third column), 167 albeit not necessarily for sparsely populated bins (Figure 2-figure supplement 5, 168 B., 3rd column as well as Figure 3 and Figure 3-figure supplement 1-3, 2rd row). 169 Similarly, given that cross-thresholding reshapes noise components, they might not 170

A. Empirical repeat data | 25th %ile | Dorsal



B. Empirical repeat data | 25th %ile | Dorsal – Cross-thresholding (Baseline)



C. Empirical repeat data | 25th %ile | Dorsal – Cross-thresholding (Baseline and Interest)

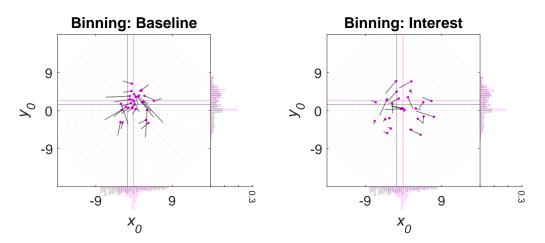


Figure 5. Caption on next page.

Figure 5. Empirical 2D post hoc binning analysis on x_0 and $y_0 \mid$ Repeat data \mid 25th %ile participant \mid **Dorsal.** Bin-wise x_0 and y_0 means in the Interest and Baseline condition for repeat data from the HCP belonging to the 25th percentile participant of the median R^2 distribution and different data binning scenarios. A. Data from the dorsal complex (V3A/B and IPS0-5) without condition cross-thresholding. B. Same as A., but with condition cross-thresholding. To this end, eccentricity values falling outside a certain eccentricity range (≥ 0 and \leq 8 dva) and below a certain R^2 cut-off (\leq 2.2%) in the Baseline condition were removed from both conditions. C. Same as B., although here, condition cross-thresholding was based on both the Baseline and Interest condition. X_0 and y_0 values in the Baseline and Interest condition were either binned according to eccentricity and polar angle values in the Baseline (1st column in A.-C.) or Interest (2nd column in A.-C.) condition. The marginal histograms (bin width = 0.5 dva; y-axis: relative frequency) show the x_0 and y_0 distributions for each condition. Magenta histograms correspond to the Interest condition and gray histograms to the Baseline condition. Note that the range of the marginal y-axis is the same for all histograms. The large magenta dots (arrow tip) correspond to the means in the Interest condition and the tiny gray dots (arrow knock) to the mean in the Baseline condition. The gray line (arrow shaft) depicts the shift from the Baseline to the Interest condition. The magenta crosshair indicates the location of the overall x_0 and y_0 means for the Interest condition and the gray crosshair the location of the overall means for the Baseline condition. Please note that for subtle differences between the Baseline and Interest condition, the histograms and crosshairs almost coincide (see figure supplements). The light gray radar grid demarks the bin segments. Polar angle bins ranged from 0° to 360° with a constant bin width of 45° and eccentricity bins from 0 to 18 dva with a constant bin width of 2 dva. The maximal eccentricity of the stimulated visual field area subtended 8 dva. HCP = Human connectome project. Dva = Degrees of visual angle.

average out with an Independent condition (Figure 2-figure supplement 1-2, B., 3rd 171 column as well as Figure 3-figure supplement 1-2, 2nd row). The same can evidently 172 also happen with an anatomical criterion if the Baseline and Interest condition 173 are subjected to cross-thresholding. Consequently, unless cross-thresholding can be 174 omitted or demonstrated to be unbiased, an Independent condition might not be a 175 safe option. Alternatively, we could use analyses without binning that control for 176 circularity and regression artifacts or effects could be evaluated against appropriate 177 null distributions that take into account all statistical dependencies (e.g., Holmes, 178 2009; Kriegeskorte et al., 2009). A combination of these approaches might be most 179 fruitful. Regardless of the specific mitigation strategy, we believe that in light of 180 the many layers of complexity in our analysis pipelines, we need to make it common 181 practice to perform sanity checks using null simulations and empirical repeat data. 182 Uncontrolled post hoc binning analyses come in many flavours (e.g., centroids, 183 shift vectors, eccentricity differences, x_0 and y_0 differences, and 1D or 2D bins) and 184

are not restricted to pRF position estimates. For instance, biases should manifest
equally when binning pRF size in a Baseline and Interest condition according to
pRF positions from either of these conditions. Moreover, partial stimulation of

pRFs likely results in heteroskedasticity and positively correlated errors for pRF 188 size and position. This would, for instance, bias bin-wise pRF size vs eccentricity 189 or pRF size vs pRF size comparisons where binning is based on non-independent 190 eccentricity values. Likewise, fitting errors due to partial stimulation should be more 191 pronounced whenever pRF size is larger, leading to stronger artifactual effects (for 192 simulations using different levels of noise see Holmes, 2009). The same is to be 193 expected based on a higher variability in pRF position estimates for wider pRFs. 194 These factors might potentially explain why pRF position and size differences have 195 been reported to be larger in higher-level areas where pRFs are wider. Moreover, the 196 distribution of errors likely depends on the toolbox that was used for fitting (Lerma-197 Usabiaga, Benson, Winawer, & Wandell, 2020), making it hard to generalize across 198 studies. Importantly, uncontrolled single bin (i.e., region of interest) analyses are 199 equally affected by post-hoc binning (Kriegeskorte et al., 2009). And of course, 200 delineations of visual areas in post hoc binning analyses should ideally also be based 201 upon independent criteria as this is where selection starts. 202

The application of uncontrolled post hoc binning analyses in the pRF literature might have led to spurious claims about the plasticity of pRFs (see de Haas et al., 2014, 2020, for a possible example). Consequently, we urge researcher who engaged in post hoc binning to check for the severity of biases in their analyses by running adequate simulations and reanalyzing the original data wherever possible.

Without doubt, circularity and/or regression to the mean are thorny and omnipresent problems that can manifest subtly and diversely (e.g., Ball, Squeglia, Tapert, & Paulus, 2020; Barnett et al., 2005; Campbell & Kenny, 1999; Eriksson & Häggström, 2014; Gignac & Zajenkowski, 2020; Holmes, 2009; Kilner, 2013; Kriegeskorte et al., 2009; Preacher et al., 2005; Shanks, 2017; Vul, Harris, Winkielman, & Pashler, 2009). As such, we need to ensure that the validation of analysis procedures becomes part and parcel of the scientific process.

²¹⁵ Materials and Methods

²¹⁶ Post hoc binning using simulations

217 Stimuli and procedure

For the simulation analyses, we used data from a population receptive field (pRF) 218 experiment involving a dynamic horizontal bar aperture (length of major axis: 17.15 219 degrees of visual angle, dva; length of minor axis: 1.27 dva). The bar aperture was 220 centered and presented within the boundaries of a circular mapping area (diameter: 221 17.15 dva). It moved consecutively across the mapping area along cardinal $(0/180^{\circ})$ 222 and $90/270^{\circ}$) and oblique axes ($45/225^{\circ}$ and $135/315^{\circ}$) and was superimposed onto a 223 random dot kinematogram (RDK). The RDK comprised moving black dots (diame-224 ter: 0.13 dva) positioned within a square field (size: 17.03×17.03 dva). If a dot left 225 the square field, it was moved back by 1 field width/height. The dots had a density 226 of 6.89 dots/dva^2 , a lifetime of 36 frames, were repositioned randomly once they had 227 died, and oscillated according to a sine wave (A = 1.29 dva, f = 1 Hz, $\omega = 6.28$ 228 rad/s, $\phi = 0$ rad). The sine wave was rotated with the current orientation of the 229 bar aperture. The bar aperture and RDK were centered at the screen's midpoint. 230

A semi-transparent ($\alpha = 50\%$) array of 5 vertical ovals was superimposed onto 231 the bar aperture. One of the ovals was centered at the screen's mid-point (length 232 of major axis: 0.43 dva; length of minor axis: 0.28 dva) and the remaining ovals 233 at an eccentricity of 4.29 dva (length of major axis: 0.86 dva; length of minor 234 axis: 0.57 dva) and different polar angles (45°, 135°, 225°, and 315°). The ovals 235 were presented as a rapid serial visual presentation (RSVP) task, where each trial 236 started with 200 ms of oval presentation, followed by a blank (no ovals) of 600 ms. 237 The ovals' orientation (45° left- or rightwards from vertical) and color (red, yellow, 238 cyan, orange, brown, white, black, green, and blue) changed pseudorandomly in 239 each trial with the exception that ovals of the same color were never presented 240 simultaneously. Participants had to press a button whenever a rightwards oriented 241 oval was presented in blue or green color. A black radar grid (line width: 0.02 dva) 242 at low opacity ($\alpha = 20\%$) with 12 radial lines (at polar angles: 0 to 330° with a step 243

size of 30°) and 18 circles (diameters: 0.95 to 51.42 dva with a step size of 2.97 dva)
was superimposed onto the screen. The radial lines ran from the midpoint of the
screen to the outermost circle.

The experiment comprised 4 attention conditions, in which participants were required to perform the RSVP task on different oval streams whilst ignoring other streams and the bar aperture. The condition of relevance here is the Center condition, where participants performed the task on the central oval stream. This condition resembles a standard pRF mapping experiment. Participants performed 2 sessions à 4 runs per condition on consecutive days. The order of conditions was pseudorandomized.

Within each run, the bar aperture moved along each axis twice, so that the 254 starting point covered all chosen polar angles. Specifically, the sequence of starting 255 points in each run was: 90°, 225°, 180°, 315°, 270°, 45°, 0°, and 135°. One bar sweep 256 lasted 28 s (1 step/s). Consecutive bar apertures overlapped by 50%. After 4 bar 257 sweeps, a blank interval of 28 s (without the bar apertures and RDK) was presented, 258 during which participants had to refrain from doing the RSVP task (a brief tone 259 cued the beginning and end of this interval). The position and lifetime of each 260 dot in the RDK at the start of every 28s-interval was randomized. Experimental 261 procedures were implemented in Matlab 2014a (8.3; https://uk.mathworks.com/) 262 using Psychtoolbox-3 (3.0.11; Brainard, 1997; Kleiner et al., 2007) and approved 263 by the University College London ethics committee. Written informed consent was 264 obtained from all participants. 265

266 Apparatus

Functional and anatomical images were acquired at a field strength of 1.5 T on a Siemens Avanto magnetic resonance imaging (MRI) scanner. All stimuli were projected onto a screen (resolution: 1920×1080 pixels; refresh rate: 60 Hz; background color: gray) at the back of the MRI scanner. Participants viewed the experiment through a head-mounted mirror. The viewing distance was approximately 67 cm. To ensure that participants could view the screen without obstruction, the front visor of a 32 channel coil was removed, leaving 30 effective channels.

274 MRI acquisition

We collected anatomical images using a T1-weighted magnetization-prepared rapid 275 acquisition with gradient echo sequence (repetition time, TR = 2.73 s; echo time, 276 TE = 3.57 ms; voxel size = 1 mm isotropic; flip angle = 7°; field of view, FoV = 256 277 mm \times 224 mm; matrix size = 256 \times 224; 176 sagittal slices) and functional images 278 using a T2^{*}-weighted multiband 2D echo-planar imaging sequence (Breuer et al., 279 2005, TR = 1 s; TE = 55 ms; voxel size = 2.3 mm isotropic; flip angle = 75°; FoV = 280 224 mm \times 224 mm, no gap, matrix size: 96 \times 96, acceleration = 4, 36 transverse 281 slices). The slice tab for the functional images was aligned to be roughly parallel to 282 the calcarine sulcus so that the posterior third of the cortex was well covered. 283

284 Preprocessing

The initial 10 volumes of each run were discarded to allow for magnetisation to 285 reach equilibrium. Using SPM8 (6313; https://www.fil.ion.ucl.ac.uk/spm/ 286 software/spm8/), functional images were then bias-corrected, realigned, unwarped, 287 coregistered to the anatomical image, and finally projected onto an anatomical sur-288 face model constructed in FreeSurfer (5.3.0; Dale, Fischl, & Sereno, 1999; Fischl, 289 Sereno, & Dale, 1999). We generated vertex-wise functional MRI (fMRI) time se-290 ries per run by determining the functional voxel at half the distance between corre-291 sponding vertices in the pial surface and gray-white matter mesh. We then applied 292 linear detrending to the time series of each run and z-standardized them. Sur-293 face projection, detrending, and z-standardization were performed in Matlab 2016b 294 (9.1; https://uk.mathworks.com/) using SamSrf7 (7.05; https://github.com/ 295 samsrf/samsrf/tree/3c7a0e25090e9097d5e2fd95696c00774acd26d6). 296

²⁹⁷ PRF estimation and delineations

The vertex-wise preprocessed time series of the Center condition were averaged across the 2 sessions. We then fit a 2D isotropic Gaussian pRF model with 5 free parameters $(x_0, y_0, \sigma, \beta_0, \text{ and } \beta_1)$ to the vertex-wise average time series. To this end, we first predicted pRF responses by calculating the overlap between the pRF model and an indicator function of the bar aperture for each volume using a 100 × 100 pixel matrix. Specifically, we used a 3D search space of possible values for σ (8.5×2^{-5.6:0.2:1}), x_0 and y_0 , and generated pRF responses for each combination of these values. Values for x_0 and y_0 were first sampled from the polar angle system (polar angles: 0:10:350°; eccentricities: 8.5×2^{-5:0.2:0.6}) and then transformed to Cartesian coordinates. The pRF response per volume was expressed as mean percent overlap with the pRF model.

To obtain a predicted fMRI time series, we then convolved these pRF responses 309 with a canonical hemodynamic response function (de Haas et al., 2014). Next, we 310 calculated the Pearson correlation between the predicted and the observed fMRI 311 time series and retained the combination of parameter values showing the largest 312 R^2 with all R^2 s \geq .01. These initial parameter estimates were then used as seeds 313 for an optimization procedure aimed at further maximizing the Pearson correlation 314 between the observed and predicted fMRI time series using a Nelder-Mead algo-315 rithm (Lagarias, Reeds, Wright, & Wright, 1998; Nelder & Mead, 1965). Lastly, 316 we estimated β_0 and β_1 by performing linear regression between the observed and 317 predicted time series. The final parameter maps were smoothed with a spheri-318 cal Gaussian kernel (FWHM = 3mm). Vertices with a very poor R^2 (< .01) or 319 artifacts ($\sigma \leq 0, \beta_1 \leq 0$ or $\beta_1 > 3$) were removed prior to smoothing. V1 hemi-320 field maps were manually delineated based on smooth polar angle maps using polar 321 angle reversals (Engel, Glover, & Wandell, 1997; Sereno et al., 1995; Wandell, Du-322 moulin, & Brewer, 2007). These delineations were used as a mask to extract V1 ver-323 tices. Fitting, smoothing, and manual delineations were performed in Matlab 2016b 324 (9.1; https://uk.mathworks.com/) using SamSrf7 (7.05; https://github.com/ 325 samsrf/samsrf/tree/3c7a0e25090e9097d5e2fd95696c00774acd26d6). 326

327 Simulations

As outlined in the main text, we generated 6 simulation cases: a null effect, a null effect with condition cross-thresholding based on the Baseline condition, a null effect with condition cross-thresholding based on both the Baseline and Interest condition, a null effect with eccentricity-scaled noise, a true effect, and a null effect with equidistant binning (instead of decile binning which was applied to the other cases). These cases were chosen to illustrate a given issue in a clear fashion using an empirical pRF parameter distribution as a basis, not to mimic the exact properties of empirical data (which is unfeasible without explicit knowledge of the noise distribution).

For all simulation cases, x_0 and y_0 estimates from both cortical hemispheres were pooled and empty data points or obvious artifacts removed ($\sigma \leq 0$ and $\beta_1 \leq 0$). Moreover, all simulation cases followed the same general procedure of the null effect involving eccentricity as outlined in the main text (including parameters settings and the same seed for random number generation) with exceptions as follows.

1D post hoc binning analyses on eccentricity. For the simulation cases in-342 volving condition cross-thresholding, we removed simulated observations falling out-343 side a certain eccentricity range (≥ 0 and ≤ 6 dva) in the Baseline or Baseline and 344 Interest condition from all conditions (i.e., Baseline, Interest, and Independent). 345 For the simulation case involving eccentricity-scaled noise, we used a small standard 346 deviation (sd = 0.25 dva) of random Gaussian noise to disturb original observations 347 with smaller eccentricities (≥ 0 and < 3 dva) and a larger standard deviation (sd =348 2 dva) to disturb original observations with larger eccentricities (≥ 3 dva). For the 349 simulation case involving a true effect, we induced a radial increase in eccentricity 350 of 2 dva in the Interest condition. For the simulation case involving equidistant bin-351 ning, we used a constant bin width of 1.75 dva and an overall binning range of 0 to 352 19.25 dva eccentricity. For all simulation cases, the Independent condition consisted 353 of a second draw (resample) of the Baseline condition. 354

³⁵⁵ **2D** post hoc binning analyses on x_0 and y_0 . Apart from a 1D binning analysis ³⁵⁶ on eccentricity, we also conducted a 2D binning analysis on the simulated x_0 and ³⁵⁷ y_0 values. To this end, we converted the x_0 and y_0 values to polar coordinates, that ³⁵⁸ is, polar angle and eccentricity (Figure 1). We then binned the x_0 and y_0 values ³⁵⁹ in the Baseline or Interest condition according to their polar coordinates in the ³⁶⁰ Baseline, Interest, or Independent condition using equidistant bins and calculated ³⁶¹ the bin-wise x_0 and y_0 means for each condition. The condition-wise means were

visualized as vector graphs. The polar angle bins ranged from 0° to 360° with a constant bin width of 45°. The eccentricity bins ranged from 0 to 22 dva (for the simulation case involving a true effect) or from 0 to 20 dva (for all other simulation cases) with a constant bin width of 2 dva. The 2D binning analysis was performed for all aforementioned simulation cases (apart from the case of equidistant binning of course).

³⁶⁸ Post hoc binning using repeat data

For the repeat data analysis, we used publicly available pRF estimates from the 369 Human Connectome Project 7 T Retinotopy Dataset (Benson et al., 2018, 2020). 370 These estimates stem from a split-half analysis where a 2D isotropic Gaussian with 371 a subadditive exponent was fit to fMRI time series from the first and second half of 372 6 pRF mapping runs. For each half, 6 estimates were obtained for each gravordinate 373 (vertex), that is, pRF polar angle, pRF eccentricity, pRF size, pRF gain, percentage 374 of R^2 , and mean signal intensity. The maximal eccentricity of the mapping area 375 subtended 8 dva. For further details, see Benson et al. (2018). 376

Following Benson et al. (2018), we analysed complexes of visual areas across 377 hemispheres for the 25th and 75th percentile participants of the R^2 distribution using 378 delineations from Wang et al.'s (2015) atlas. Benson et al. (2018) generated the R^2 379 distribution by calculating the median R^2 for each participant across grayordinates 380 from both cortical hemispheres within all areas of Wang et al.'s (2015) atlas. The 381 posterior complex consisted of V1-V3, the ventral complex of VO-1/2 and PHC-1/2, 382 the dorsal complex of V3A/B and IPS0–5, and the lateral complex of LO-1/2 and 383 TO-1/2. For our purposes, we focused on the posterior and dorsal complexes, as 384 those came with a larger number of available data points (which was particularly 385 necessary to perform the 2D post hoc binning analysis and generate vector graphs). 386

To obtain x_0 and y_0 estimates, polar angle and eccentricity estimates were converted to Cartesian coordinates. The eccentricity, x_0 , and y_0 estimates of the first half were used as a Baseline condition and those of the second half as an Interest condition. Grayordinates with unusual/implausible values ($R^2 \leq 0\%$ or $\sigma \leq 0$) in either condition were removed from both conditions.

Similar to the simulation-based analyses, binning was either based on the Interest or Baseline condition and bin-wise means were calculated. Moreover, binning was either performed with or without condition cross-thresholding. As for the latter case, we removed observations falling outside a certain eccentricity range (≥ 0 and ≤ 8 dva) or below a certain R^2 cut-off ($\leq 2.2\%$) in the Baseline or Baseline and Interest condition from both conditions. The R^2 cut-off of 2.2% was adopted from Benson et al. (2018).

The 1D binning analysis involving eccentricity and the 2D binning analysis involving x_0 and y_0 were conducted as for the simulated data, although, here, the eccentricity bins for the 2D analysis ranged from 0 to 18 dva with a constant bin width of 2 dva. All binning analyses (including those on simulated data) were implemented in Matlab 2016b (9.1; https://uk.mathworks.com/) using custom code.

⁴⁰⁴ Data and code availability

Preprocessed data, custom code, and figures are available at https://doi.org/
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A8).

412 Declaration of competing interest

⁴¹³ The authors declare no conflict of interest.

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558 Supplementary figures

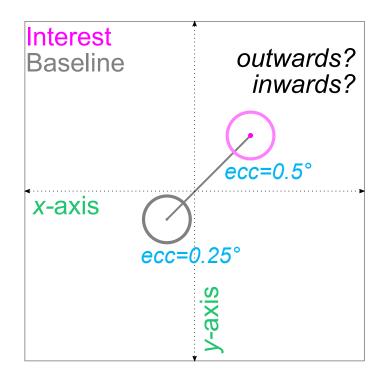
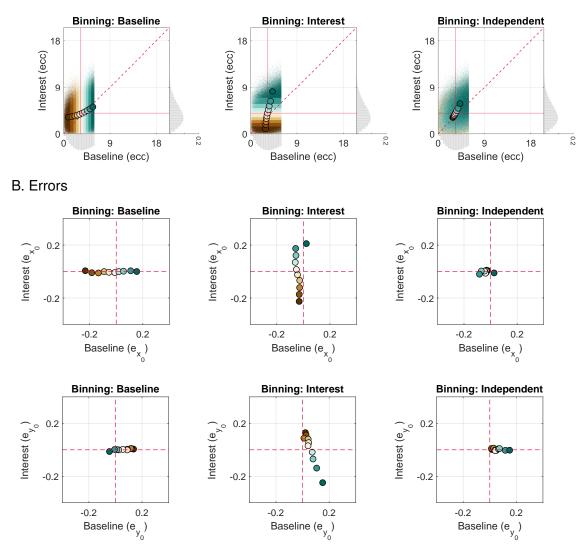
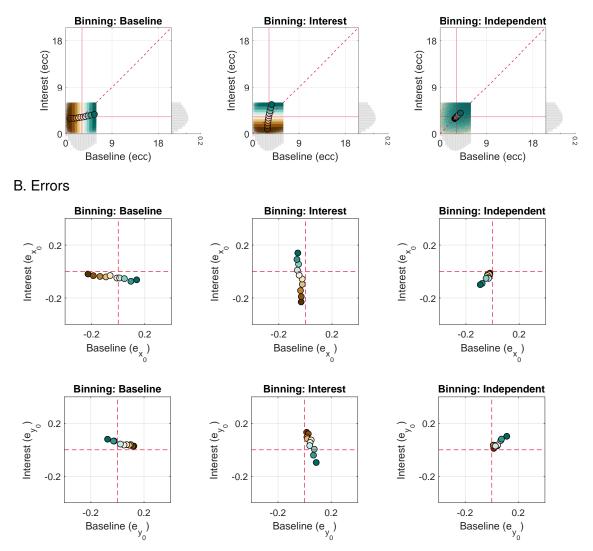


Figure 1-figure supplement 1. Interpretation of changes in eccentricity. The same as Figure 1, although here, the pRFs shifts from one visual field quadrant to another in the Interest compared to the Baseline condition. This can happen due to noise or when visual field maps partially cover the ipsilateral hemifield. In such cases, an increase or decrease in eccentricity does not necessarily correspond to an outwards or inwards shift in the traditional sense. For instance, imagine that a pRF sits at $x_0 = -0.18$ dva and $y_0 = -0.18$ dva in the Baseline condition (ecc = 0.25 dva) but at $x_0 = 0.36$ dva and $y_0 = 0.36$ dva in the Interest condition (ecc = 0.5 dva). This would result in an increase in eccentricity, which might be interpreted as an outwards shift, although the pRF shifts effectively radially inwards until it reaches the origin and then outwards. We can likewise imagine that the pRF shifts horizontally to $x_0 = 0.36$ dva and $y_0 = -0.36$ dva in the Interest condition. Importantly, removing such shifts would again bias noise components in non-predictable ways (see condition cross-thresholding in the main text and Figure 2-figure supplement 1-2) and therefore does not seem a valid option. Dva = Degrees of visual angle.



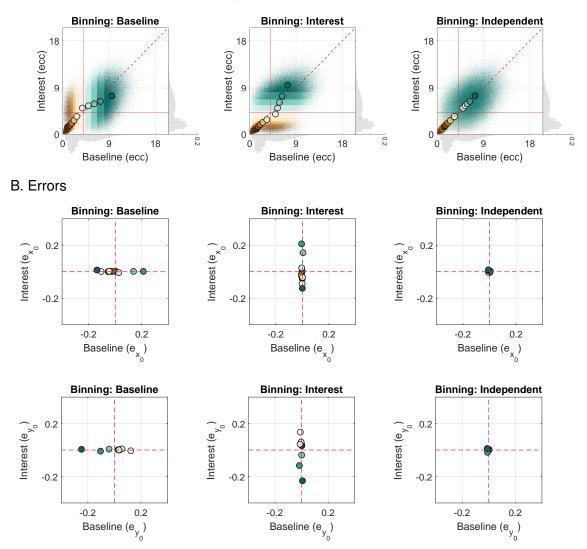
A. Simulated null effect - Cross-thresholding (Baseline)

Figure 2-figure supplement 1. Simulated 1D post hoc binning analysis on eccentricity | Null effect — Cross-thresholding (Baseline). The same as in Figure 2, although here, simulated observations falling outside a certain eccentricity range (≥ 0 and ≤ 6 dva) in the Baseline condition were removed from all conditions — a simulation case we term *cross-thresholding (Baseline)*.



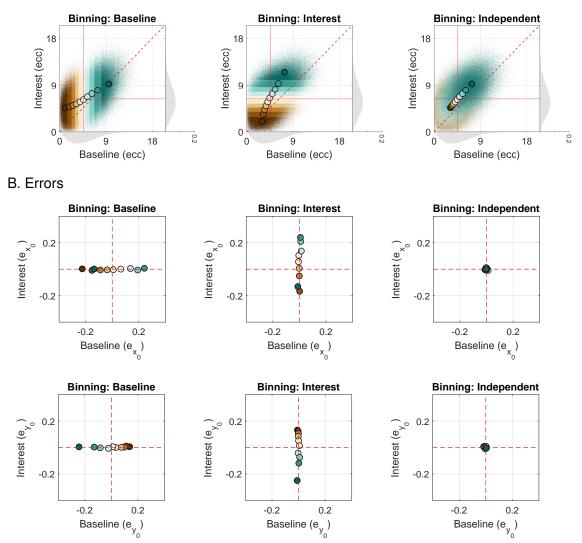
A. Simulated null effect - Cross-thresholding (Baseline and Interest)

Figure 2-figure supplement 2. Simulated 1D post hoc binning analysis on eccentricity | Null effect — Cross-thresholding (Baseline and Interest). The same as in Figure 2-figure supplement 1, although here, condition cross-thresholding was based on both the Baseline and Interest condition — a simulation case we term cross-thresholding (Baseline and Interest).



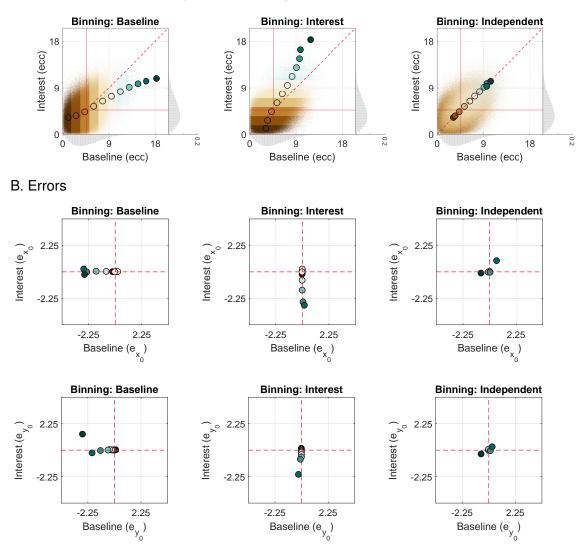
A. Simulated null effect - Eccentricity-scaled noise

Figure 2-figure supplement 3. Simulated 1D post hoc binning analysis on eccentricity | Null effect — Eccentricity-scaled noise. The same as in Figure 2, although here, original observations having smaller eccentricities (≥ 0 and < 3 dva) were disturbed by random Gaussian noise with a smaller standard deviation (sd = 0.25 dva) and those having larger eccentricities (≥ 3 dva) by random Gaussian noise with a larger standard deviation (sd = 2 dva) — a simulation case we term *eccentricity-scaled noise*.



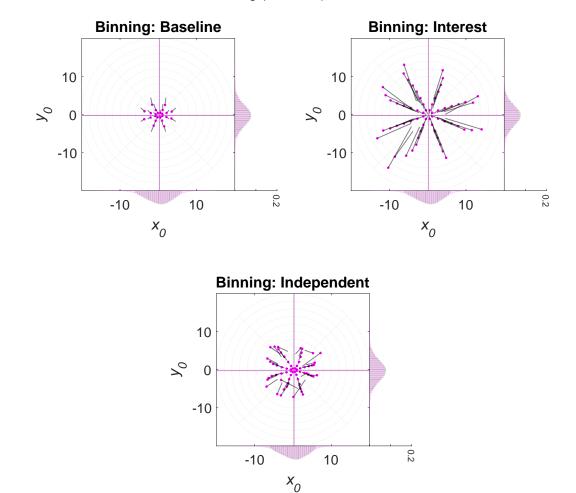
A. Simulated true effect - Radial shift

Figure 2-figure supplement 4. Simulated 1D post hoc binning analysis on eccentricity | True effect — Radial shift. The same as in Figure 2, although here, we simulated a true effect, that is, a radial increase in eccentricity of 2 dva in the Interest as compared to the Baseline condition.



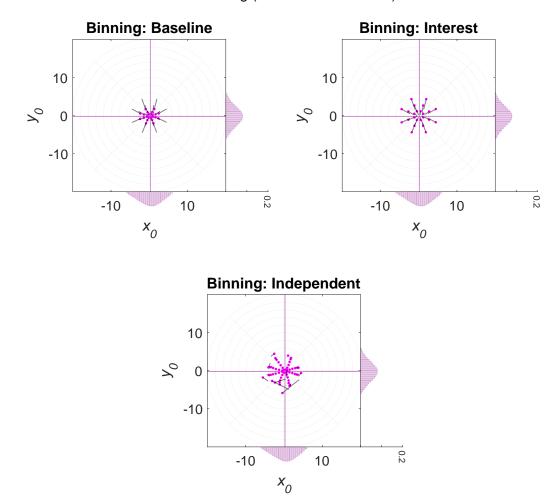
A. Simulated null effect - Equidistant binning

Figure 2-figure supplement 5. Simulated 1D post hoc binning analysis on eccentricity | Null effect — Equidistant binning. The same as in Figure 2, although here, equidistant binning was used. The equidistant bins ranged from an eccentricity of 0 dva to an eccentricity of 19.25 dva with a constant bin-width of 1.75 dva. Please note the different x- and y-axis ranges in B. relative to Figure 2 and other figure supplements (-4.5 to -4.5 vs -0.4 to 0.4, respectively) as well as the different number of bins (11 vs 10, respectively).



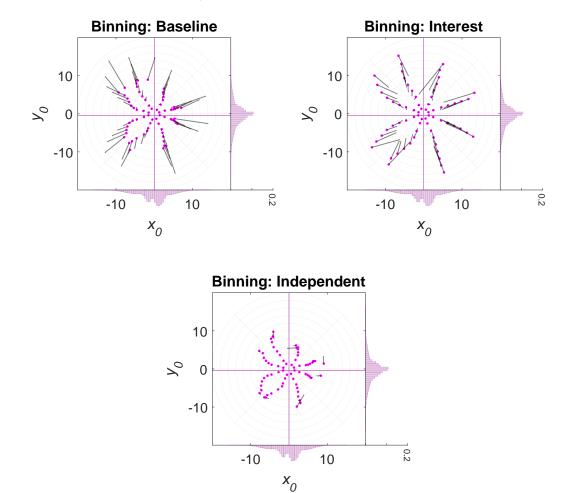
Simulated null effect - Cross-thresholding (Baseline)

Figure 3-figure supplement 1. Simulated 2D post hoc binning analysis on x_0 and $y_0 |$ Null effect — Crossthresholding (Baseline). The same as in Figure 3, although here, simulated observations falling outside a certain eccentricity range (≥ 0 and ≤ 6 dva) in the Baseline condition were removed from all conditions — a simulation case we term *cross-thresholding (Baseline)*.



Simulated null effect - Cross-thresholding (Baseline and Interest)

Figure 3-figure supplement 2. Simulated 2D post hoc binning analysis on x_0 and $y_0 |$ Null effect — Cross-thresholding (Baseline and Interest). The same as in Figure 3-figure supplement 1, although here, condition cross-thresholding was based on both the Baseline and Interest condition — a simulation case we term cross-thresholding (Baseline and Interest).



Simulated null effect - Eccentricity-scaled noise

Figure 3-figure supplement 3. Simulated 2D post hoc binning analysis on x_0 and $y_0 |$ Null effect — Eccentricity-scaled noise. The same as in Figure 3, although here, original observations having smaller eccentricities (≥ 0 and < 3 dva) were disturbed by random Gaussian noise with a smaller standard deviation (sd = 0.25 dva) and those having larger eccentricities (≥ 3 dva) by random Gaussian noise with a larger standard deviation (sd = 2 dva) — a simulation case we term *eccentricity-scaled noise*.

Simulated true effect - Radial shift

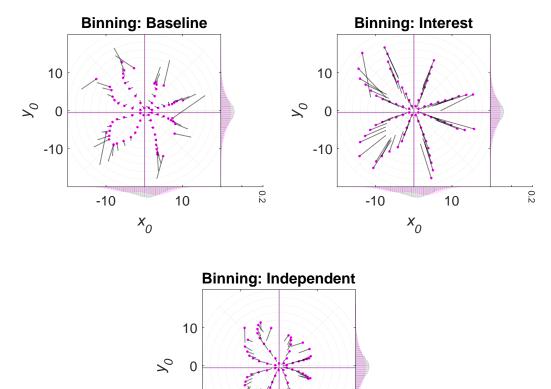


Figure 3-figure supplement 4. Simulated 2D post hoc binning analysis on x_0 and $y_0 |$ True effect — Radial shift. The same as in Figure 3, although here, we simulated a true effect, that is, a radial increase in eccentricity of 2 dva in the Interest as compared to the Baseline condition. Note that the eccentricity bins ranged from 0 to 22 dva (instead of 0 to 20 dva) here.

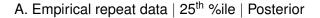
х₀

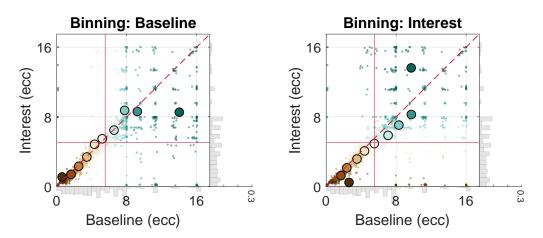
10

-10

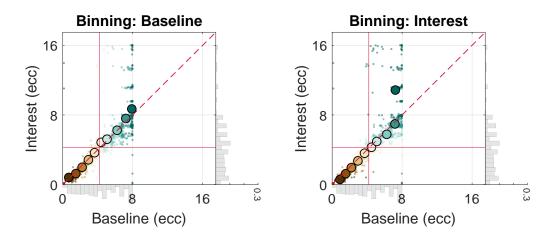
0.2

-10





B. Empirical repeat data | 25th %ile | Posterior – Cross-thresholding (Baseline)



C. Empirical repeat data | 25th %ile | Posterior – Cross-thresholding (Baseline and Interest)

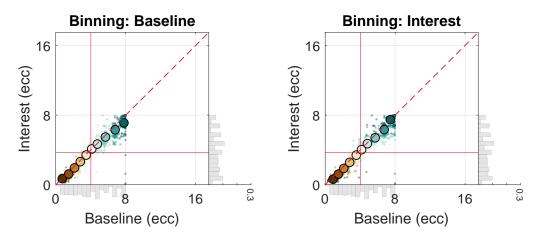
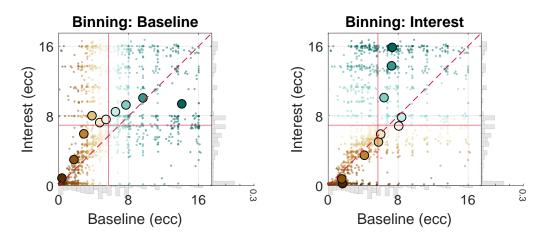
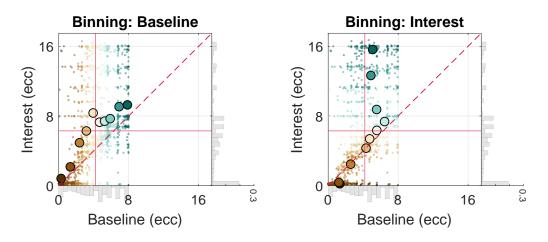


Figure 4-figure supplement 1. Empirical 1D post hoc binning analysis on eccentricity | Repeat data | 25^{th} %ile participant | Posterior. The same as in Figure 4, although here, we used data from the posterior complex (V1-V3).

A. Empirical repeat data | 75th %ile | Dorsal



B. Empirical repeat data | 75th %ile | Dorsal – Cross-thresholding (Baseline)



C. Empirical repeat data | 75th %ile | Dorsal – Cross-thresholding (Baseline and Interest)

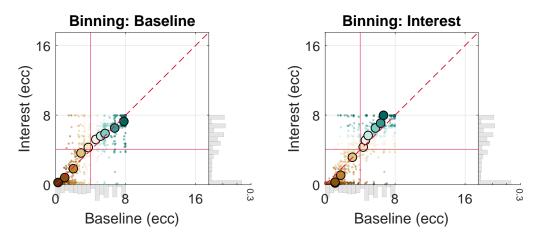
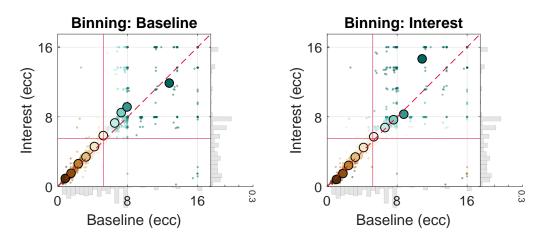
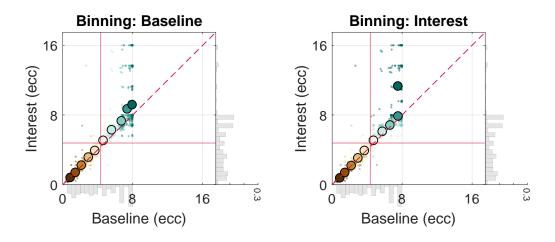


Figure 4-figure supplement 2. Empirical 1D post hoc binning analysis on eccentricity | Repeat data | 75^{th} %ile participant | Dorsal. The same as in Figure 4, although here, we used the 75^{th} %ile participant of the median R^2 distribution.





B. Empirical repeat data | 75th %ile | Posterior – Cross-thresholding (Baseline)



C. Empirical repeat data | 75th %ile | Posterior – Cross-thresholding (Baseline and Interest)

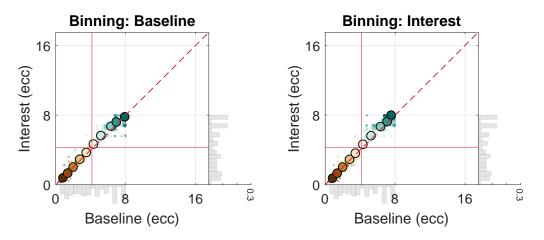
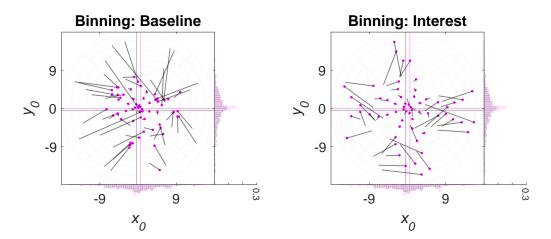
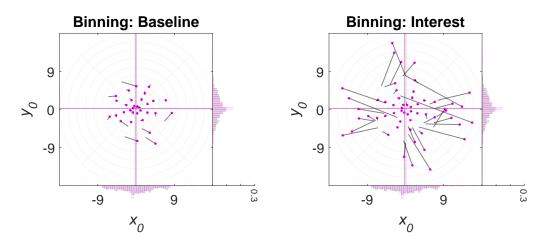


Figure 4-figure supplement 3. Empirical 1D post hoc binning analysis on eccentricity | Repeat data | 75th %ile participant | Posterior. The same as in Figure 4-figure supplement 1, although here, we used the 75th %ile participant of the median R^2 distribution.

A. Empirical repeat data | 25th %ile | Posterior



B. Empirical repeat data | 25th %ile | Posterior – Cross-thresholding (Baseline)



C. Empirical repeat data | 25th %ile | Posterior – Cross-thresholding (Baseline and Interest)

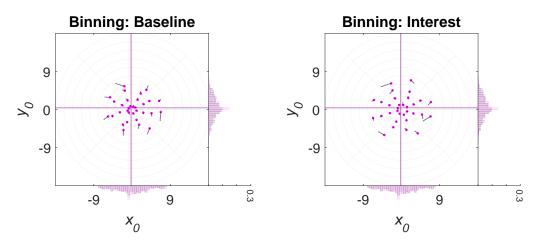
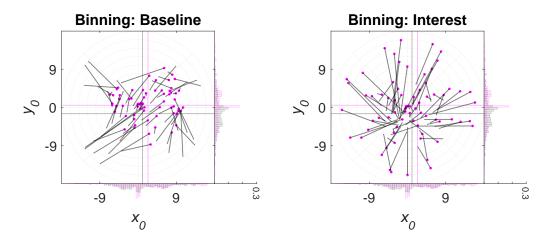
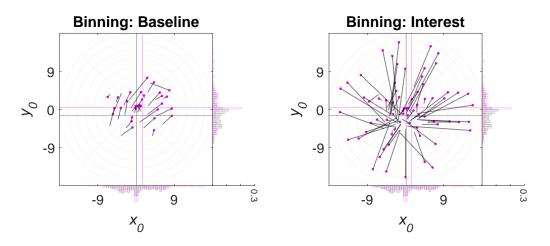


Figure 5-figure supplement 1. Empirical 2D post hoc binning analysis on x_0 and y_0 | Repeat data | 25th %ile participant | Posterior. The same as in Figure 5, although here, we used data from the posterior complex (V1-V3).

A. Empirical repeat data | 75th %ile | Dorsal



B. Empirical repeat data | 75th %ile | Dorsal – Cross-thresholding (Baseline)



C. Empirical repeat data | 75th %ile | Dorsal – Cross-thresholding (Baseline and Interest)

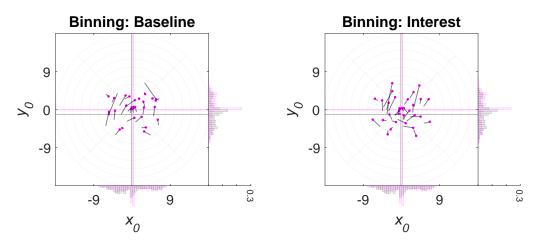
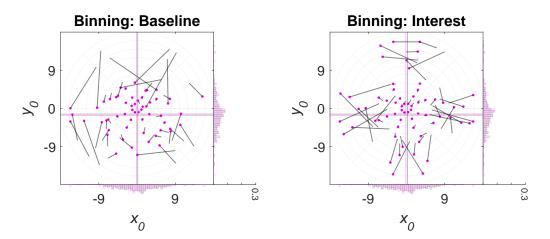
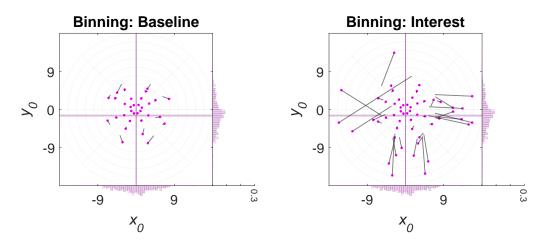


Figure 5-figure supplement 2. Empirical 2D post hoc binning analysis on x_0 and y_0 | Repeat data | 75th %ile participant | Dorsal. The same as in Figure 5, although here, we used the 75th %ile participant of the median R^2 distribution.

A. Empirical repeat data | 75th %ile | Posterior



B. Empirical repeat data | 75th %ile | Posterior – Cross-thresholding (Baseline)



C. Empirical repeat data | 75th %ile | Posterior – Cross-thresholding (Baseline and Interest)

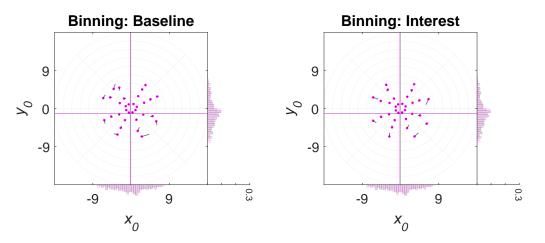


Figure 5-figure supplement 3. Empirical 2D post hoc binning analysis on x_0 and y_0 | Repeat data | 75th %ile participant | Posterior. The same as in Figure 5-figure supplement 1, although here, we used the 75th %ile participant of the median R^2 distribution.