# 1 Estimating fecundity and density dependence from mark-recapture data for

# making population projections

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#### 9 Abstract

10 Forecasting changes in size and distributions of populations is at the forefront of 11 ecological sciences in the 21st century. Such forecasts require robust estimators of fecundity, 12 survival and density-dependence. While survival estimation is the main focus of mark-recapture 13 modelling, fecundity and density dependence are rarely the subject of these models. Here, we 14 demonstrate that these parameters can be simultaneously estimated in a Bayesian framework 15 using only robust design mark-recapture data. Using simulated capture histories, we show that 16 this framework (which we named CJS-pop) can estimate vital rates and their density dependence 17 with little bias. When CJS-pop is applied to capture history data from Brown Creeper (Certhia 18 *americana*), it provides estimates of fecundity that is expected from the breeding biology of this 19 species. Finally, we illustrate that density dependence, even when estimated with uncertainty in the CJS-pop framework, regularizes population dynamics and reduces the frequent population 20 21 extinctions and explosions observed under density-independent models. While CJS-pop as a 22 whole is a useful addition to the current mark-recapture modelling toolbox, we argue that the 23 independent components of this framework in estimating fecundity and density dependence can 24 be integrated to other CJS frameworks, potentially creating models capable of population 25 projections.

26

Keywords: CJS, CJS-pop, Fecundity, Mark-recapture, Population Models, Population
projections, Population Viability Analysis, Simulations

### 30 Introduction

31 Mark-recapture data analysis is a staple in population ecology for estimating survival, 32 abundance, and recruitment rates (Lebreton et al. 1992, Williams et al. 2002, Cooch and White 33 2016). More recently mark-recapture methods have been extended to work in parallel with 34 different types of data in frameworks such as integrated population models (IPMs; Schaub and 35 Abadi 2011) and to estimate dispersal and animal movement in spatial capture-recapture analysis (Ergon and Gardner 2014, Schaub and Royle 2014). When considering the wide applicability of 36 37 mark-recapture methods for estimating parameters related to population dynamics, rarity of one 38 parameter in the mark-recapture literature stands out: fecundity as defined in a population 39 modelling setting, which is the number of juveniles per number of adults (for example, see Ryu 40 et al. 2016). If fecundity can be estimated from mark-recapture data, then this single data source 41 can be used on its own to parameterize stage-structured population models. 42 Ryu et al. (2016) provided a framework for estimation of fecundity and other necessary 43 population model parameters (stage-dependent survival, density dependence, and environmental 44 stochasticity) from robust design mark-recapture data. However, their framework is a mixture of 45 frequentist and Bayesian approaches of mark-recapture models and it requires multiple models to 46 be fit sequentially. As a result, Ryu et al. (2016)'s different model components do not inform one 47 another during estimation, which prevents making full use of the data at hand and propagating 48 uncertainty in a hierarchical manner. Here, we present an update on Ryu et al. (2016)'s 49 framework. We use both simulated and real data to show that; 1) fecundity can be estimated 50 alongside adult survival and capture probability in a single Bayesian framework using only 51 robust design mark-recapture data; 2) estimating fecundity reduces uncertainty in juvenile 52 survival estimates; and, 3) when these vital rates estimates are combined with density

dependence, resulting stage-structured population models are useful for calculating conservationrelevant metrics.

- 55 Material and Methods
- 56 *Model specifications*

Two basic parameters are estimated in a standard CJS model (Cooch and White 2016):
survival and capture probability. Robust design mark-recapture data separates these two

59 processes to primary capture occasions (for example years), and secondary capture occasions

60 within primary occasions (for example months). Populations are assumed to be closed

61 (individuals don't die or leave the population) among secondary occasions within a primary

62 occasion. Capture probabilities are estimated for each secondary occasion, which can then be

63 used to estimate the population size for a given primary occasion. Populations are assumed to be

open among primary occasions, so individuals can leave the population or die. Survival is

estimated with information coming across primary occasions. Below, for simplicity in

66 presentation, we assume primary occasions are years and secondary occasions are months.

67 We denote  $p_{x,k,t,h}$  as the monthly capture probability of a stage x individual at population 68 k, year t, and month h; where, x = 1,2,3...,X; k = 1,2,3...,K; t = 1,2,3...,T; and h =

69 1,2,3..., *H*. We can use this monthly capture probability to calculate a yearly capture probability:

70 
$$P_{x,k,t} = 1 - \prod_{h=1}^{H} (1 - p_{x,k,t,h})$$
(1)

Then, we can use the heuristic estimator of populations size with a correction for years
with no captures (Dail and Madsen 2011) to estimate the expected abundance of stage *x*individuals at population *k*, year *t*:

74 
$$N_{x,k,t} = \frac{n_{x,k,t}}{P_{x,k,t}} + \frac{(1 - P_{x,k,t})}{P_{x,k,t}}$$
(2)

75 Where,  $n_{x,k,t}$  is the number of captured stage x individuals in population k and year t. Using the 76 expected abundance time series of each population we calculate a density index:

77 
$$D_{k,t} = \frac{\sum_{x=1}^{X} N_{x,k,t}}{\frac{\sum_{t=1}^{T} \sum_{x=1}^{X} N_{x,k,t}}{T}}$$
(3)

where,  $D_{k,t}$  is the density index at population k, year t. The numerator in equation 3 is the total abundance of population k at year t across all stages, and denominator is the average expected total abundance across T years. D is an index for the deviation of population abundance in a given year from the long term average population abundance and it can be considered as a relative population density. We use D as a covariate for estimating density dependence strength of fecundity and survival.

All three parameters estimated by equations 1 to 3, namely, yearly capture probability,
expected abundance, and density index can be used to estimate fecundity and its density
dependence:

$$\log(F_{k,t}) = \theta + \zeta \cdot D_{k,(t-1)} + \omega_{k,t}$$
(4a)

88

87

$$\omega_{k,t} \sim \operatorname{Normal}(0, \sigma_f^2) \tag{4b}$$

89 where,  $\theta$  is the fecundity in log scale at 0 density;  $\zeta$  is the change in fecundity in log scale with 90 one unit change in population density index;  $\omega_{k,t}$  is the spatio-temporal random effect at 91 population k and time t; and  $\sigma_f^2$  is the spatio-temporal variance of fecundity at log scale. We link 92 the fecundity estimate to the data, which is the number of captured juveniles in a given year and 93 population, by using expected abundances for adults calculated in equation 2. Below we present 94 a simple case for two stages where x = 1 are juveniles and x = 2 are adults:

95 
$$N'_{1,k,t} = N_{2,k,t} \cdot F_{k,t}$$
 (5*a*)

96 
$$n_{1,k,t} \sim Poisson(P_{1,k,t} \cdot N'_{1,k,t})$$
(5b)

97 The expected number of juveniles is estimated twice in this framework: once as a derived 98 variable  $(N_{1,k,t})$  using the heuristic population size estimator, and a second time  $(N'_{1,k,t})$  as a 99 function of density and expected number of adults. We discuss this and our choice of Poisson 100 distribution in detail below.

101 So far, we have only used captured number of juveniles and adults as a data source.

102 However, this form of a capture history is not enough to estimate parameters used in the above 5

103 equations. So, we link these 5 equations with a more typical CJS model where survival and

104 capture probability are used to model capture histories of individuals:

105 
$$\operatorname{logit}(\phi_{x,k,t}) = \alpha_x + \beta \cdot D_{k,t} + \epsilon_{k,t}$$
(6a)

$$\epsilon_t \sim \text{Normal}(0, \sigma_s^2)$$
 (6b)

107 where,  $\phi_{x,k,t}$  is the apparent survival probability of a stage x individual at population k and year 108 t;  $\alpha_x$  is the survival probability of a stage x individual on logit scale at 0 density;  $\beta$  is the change 109 in survival in logit scale with one unit change in population density index;  $\epsilon_{k,t}$  is the spatio-110 temporal random effect at population k and time t; and  $\sigma_f^2$  is the spatio-temporal variance of 111 survival at logit scale.

112 Apparent survival changes the latent states of individuals in a population between time 113 steps, from t to t + 1; this latent state indicates whether an individual is alive and in the 114 population (Z = 1), or it is dead or left the population (Z = 0). The latent state of the *i*th 115 individual, then, is determined by its state at time t and its survival to time t + 1.

116 
$$Z_{i,(t+1)} \sim \text{Bernoulli}(Z_{i,t} \cdot \phi_{(S_{i,t}),(g_i),t})$$
(7)

117 where,  $\phi_{(S_{i,t}),(g_i),t}$  is the apparent survival probability at the breeding stage and population of the 118 *i*th individual from year *t* to t + 1;  $S_{i,t}$  is a matrix indicating the breeding stage of the *i*th 119 individual in year *t*, and the vector  $g_i$  indicates the population that the *i*th individual is in. Latent

120 state, Z, also determines the potential capture of an individual; dead ones cannot be captured. Hence, every element of the capture history,  $y_{i,t,h}$  (1 if an individual is captured, 0 if it is not), is 121 a Bernoulli random variable with a monthly capture probability,  $p_{(S_{i,t}),(q_i),t,h}$ , conditional on the 122 123 individual being alive and in the population,  $Z_{i,t}$ .  $y_{i,t,h} \sim \text{Bernoulli}(Z_{i,t} \cdot p_{(S_{i,t}),(g_i),t,h})$ (8)124 125 For simplicity in referring to this framework, we named it CJS-pop; pop extension comes from 126 the fact that it can estimate necessary parameters to build a stochastic and stage-based population 127 model: Fecundity, staged-based survival, density dependence, and process variance. 128 Simulated data 129 We simulated several sets of capture histories in order to test CJS-pop's ability to 130 correctly retrieve true parameter values, and to uncover any inherent biases, especially when 131 quantifying density dependence strength. We set up a simulation scheme where we explored the 132 effect of sample size on quantifying density dependence strength. We set the time series length to 133 17 years, which is the maximum time series length for Brown Creeper data set we are using (see 134 below). We simulated three cases with 1, 5, and 10 populations, and three carrying capacities 135 (which controls population size): 50, 100, 150. For each combination of the number of 136 populations and carrying capacity, we generated capture history data sets using weak, moderate 137 and strong density dependence on survival and fecundity, which created 27 separate simulation 138 sets. For each simulation set, we generated 56 capture history data sets and fitted CJS-pop to 139 each one. See Appendix S2 for more detailed discussion of the simulation framework and 140 Appendix S3 for its code.

141 Empirical data: Brown Creeper

| 142 | We applied CJS-pop to Brown Creeper (Certhia americana) data obtained from the                      |
|-----|---|
| 143 | Mapping Avian Productivity and Survivorship (MAPS) program. Brown Creeper is a widespread           |
| 144 | North American songbird species. It is a resident, forest-dwelling bird in western U.S and along    |
| 145 | the coastline to Alaska, in north-eastern U.S, and southern Canada. We treated each MAPS            |
| 146 | location (a cluster of mist-netting and banding stations) of Brown Creeper to be a separate         |
| 147 | population. We only included data from populations which were located in the contiguous U.S.,       |
| 148 | and which have been monitored for at least 5 years. This resulted in a data set with 2931           |
| 149 | individuals. We categorized any individual in its first year as a juvenile (MAPS age codes 2 and    |
| 150 | 4), and older individuals as adults (MAPS age codes 1, 5, 6, 7, and 8).                             |
| 151 | We made several adjustments and additions to basic CJS-pop framework presented above                |
| 152 | when applying to Brown Creeper data. First, we accounted for potentially transient individuals in   |
| 153 | the data set. In a CJS model, estimated survival rates are said to be "apparent" because the        |
| 154 | estimated survival rate cannot distinguish between dead individuals and the ones that just left the |
| 155 | population. This can bias survival estimates to be lower than their true values. Accounting for     |
| 156 | transients is a partial way to correct for this bias and it is a frequently used technique in CJS   |
| 157 | literature (for example, Ahrestani et al. 2017).  |
| 158 | Second, we used the priors and population modelling structure of CJS-pop to our                     |
| 159 | advantage to estimate a juvenile survival rate with less uncertainty. We use information from       |
| 160 | adult survival and fecundity estimates, and the fact that they are density dependent, to estimate   |

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juvenile survival:

$$S_A + S_J \cdot F = 1 \tag{9}$$

where,  $S_A$  and  $S_J$  are survival rates of adults and juveniles at mean population size (when D = 1) and F is the fecundity at mean population size. This equation states that population growth rate

165 ( $\lambda$ ) is equal to 1 when population abundance is at its long-term average. Using this equation, we 166 would only need priors for adult survival and fecundity, and we can calculate juvenile survival 167 as:

$$S_J = \frac{1 - S_A}{F} \tag{10}$$

169 Third, we used a zero-inflated Poisson for modelling fecundity in equation 5b because 170 there were several years and populations with no juvenile captures. Fourth, we did not use 171 populations and years with no adult captures when modelling fecundity. While we account for no 172 capture years in equation 2, we believe that limiting fecundity estimation to years with adult 173 captures provides a more robust estimate.

Fifth, we changed the spatio-temporal variance structure of survival to be only temporal. Spatio-temporal variance structure in survival for Brown Creeper proved to be problematic because it made convergence harder for multiple parameters while also reducing the effective sample size of their MCMC chains. Lastly, we standardized the density index (*D*), calculated in equation 3, to be 0 at mean population size. This allowed for faster convergence of the MCMC chains in JAGS. See Appendix S2 for details on these adjustments to basic CJS-pop framework and goodness-of-fit testing of CJS-pop .

We fit three different CJS-pop models to Brown Creeper data: 1) density dependent, 2)
density independent, and 3) Density dependent without the residency model.

183 *Population Projections* 

184 We ran population projections using a stage-structured population model with

185 environmental and demographic stochasticity in both survival and fecundity. We parameterized

these population models with 3 different parameter sets:

187 1) True simulation parameters that we used to generate capture history data.

Parameter estimates from density-dependent and density-independent CJS-pop fit to
simulated data. At each replication we randomly selected the parameters of CJS-pop fit to
one of the 56 data sets with this population and carrying capacity combination. To further
incorporate parameter uncertainty, we randomly used at each replication the 2.5%, 50%,

- 192 or 97.5% percentiles of the selected parameters.
- 193 3) Parameter estimates obtained from CJS-pop fit to the Brown Creeper data. We employed
- the full posterior distribution of the estimated parameters. At each iteration of the
- 195 projections, parameter estimates were randomly selected from the posterior distributions
- 196 of all parameters with respect to their correlation structure.

Using each of these sets of parameters, we ran single-population projections, with a 197 198 carrying capacity of 1000 and an initial population of 500 adults and 500 juveniles. We ran the 199 projections with 1000 replicates, and each replicate for 20 years. In order to incorporate 200 environmental stochasticity, at each iteration and at each year we generated random temporal effects separately for survival and fecundity using  $\sigma_s^2$  and  $\sigma_f^2$ , respectively. We recorded the 201 202 minimum abundance of the population across 20 years for each iteration, and the distribution of 203 minimum abundance among iterations. The expected value of this distribution is called expected 204 minimum abundance (EMA) and it is a more informative metric than extinction risk, because the 205 latter often has a distribution restricted to near-zero or near-one values (McCarthy and

206 Thompson 2001).

207 *Software* 

See appendix S2 for a list of R packages used in the analysis. We used JAGS as the MCMC sampler when fitting CJS-pop to data. We ran the models with 4 chains, 50000 iterations, 20000 burn in, and a thinning rate of 10 for simulated data sets, and with 4 chains,

| 211 | 100000 iterations, 50000 burn in and a thinning rate of 20 for Brown Creeper data. We checked                   |
|-----|---|
| 212 | convergence with R-hat values, and assumed chains were converged when $\hat{R}$ was <1.05. See                  |
| 213 | Appendix S4 for JAGS code of CJS-pop. Additionally, R and JAGS code of CJS-pop analysis,                        |
| 214 | example simulation data, and results of Brown Creeper analysis are accessible here:                             |
| 215 | https://github.com/bilgecansen/CJS-pop. The software source code has been archived and made                     |
| 216 | accessible in Zenodo (DOI: 10.5281/zenodo.3736702).   |
| 217 | Results   |
| 218 | Simulations   |
| 219 | CJS-pop is able retrieve true parameter estimates without any apparent bias except for                          |
| 220 | density dependence (Figs. S1-6). DD strength is estimated with no bias when strength of DD                      |
| 221 | used to generate capture history data is moderate. Strong DD in data simulation leads to slight                 |
| 222 | underestimation of DD strength. There is, however, considerable overestimation of true DD                       |
| 223 | parameters when capture history simulation was carried out with weak DD strength (Fig. S1).                     |
| 224 | Empirical Example: Brown Creeper  |
| 225 | We detected weak DD on survival ( $\beta = -0.27$ , Fig. 1a), and on fecundity ( $\zeta = -0.13$ ,              |
| 226 | Fig. 1b) for Brown Creeper. Process variance estimations are low for survival, and high for                     |
| 227 | fecundity, ( $\sigma_s = 0.23$ , $\sigma_f = 0.97$ ; Table S1). Survival at mean population size for adults and |
| 228 | juveniles were estimated at 0.42 and 0.31, respectively. Our estimate of fecundity at mean                      |
| 229 | population size was $1.94 (1.21 - 3.01)$ juveniles per adult (Table S1). In addition, Bayesian p-               |
| 230 | values for both the survival and fecundity components indicated good model fits (0.24 and 0.50,                 |
| 231 | respectively).  |
|     |   |

232 *Projections* 

| 233 | Density-independent projections parameterized with CJS-pop fit to Brown Creeper data             |
|-----|--|
| 234 | lead to frequent population extinctions and explosions, which is apparent in the population      |
| 235 | trajectory (Fig. 1c) and bi-modal distribution of minimum abundances (Fig. 2). Density           |
| 236 | dependence in population models lead to more regularized projections in which population         |
| 237 | extinctions and explosions are less frequent (Fig. 1c and Fig. 2). The distribution of minimum   |
| 238 | abundances from density-dependent projections of Brown Creeper show a generally similar          |
| 239 | pattern to projections parameterized with CJS-pop fit to simulated data irrespective of the DD   |
| 240 | strength of capture history simulations (Fig. 2).  |
| 241 | Projections made with population models that are parameterized with density-dependent            |
| 242 | CJS-pop fit to simulated data are close to projections made with true simulation parameters,     |
| 243 | especially when true simulation parameters included moderate or strong DD. This                  |
| 244 | correspondence demonstrates, in a biologically relevant context, the ability of CJS-pop to fit   |
| 245 | realistic models to data (Figs 2c-d). In contrast, projections with density-independent CJS-pop  |
| 246 | (Figs 2b-d), and with CJS-pop fit to simulated capture history data with weak DD (Fig. 2b) were  |
| 247 | not close to projections with the true simulation models. Overestimation of DD strength in CJS-  |
| 248 | pop fit to weak DD data also results in overestimation of projected minimum abundances.          |
| 249 | Density-independent projections tends to result in frequent population extinctions or explosions |
| 250 | (Figs 2b-d).   |
| 251 | Discussion   |
| 252 | CJS-pop is ready to be applied to bird species captured in the MAPS program. It can be           |

CJS-pop is ready to be applied to bird species captured in the MAPS program. It can be
extended to include weather, climate and other exogenous factors in addition to population
density. The true value of CJS-pop lies in its ability to use limited data to parameterize
population models that in turn can be used to predict changes in population sizes and

256 distributions. We believe this is especially important for developing countries that do not yet 257 have extensive bird banding and survey programs like MAPS and BBS. We don't, however, 258 think that whole CJS-pop framework needs to be used for the work we presented here to be 259 useful. Rather, we argue that the independent ideas explained in estimating fecundity, juvenile 260 survival and density dependence can be integrated to other CJS frameworks, potentially creating 261 models capable of population projections. Below we describe 4 of the main advances CJS-pop 262 provides to mark-recapture literature and discuss the trade-offs made when building the 263 framework.

205 manie work.

264 l – Fecundity Estimation

265 We estimated fecundity in the simulation data with no apparent bias (Figure S4). The 266 fecundity estimate for Brown Creeper (F = 1.94 (1.21 - 3.01); Table S1) is also biologically 267 realistic; Brown Creepers tend to have a single brood with a clutch size of 5 to 6 eggs in a 268 breeding season. The main contribution here is that every vital rate (including fecundity), capture 269 probabilities, and nuisance parameters were estimated simultaneously in a single model run. This 270 allows for propagation of uncertainty among these parameters but also makes it possible for 271 parameters that are estimated with less data (juvenile survival) to be informed by parameters 272 estimated with more data (fecundity and adult survival).

273

#### 2 – Juvenile Survival Estimation

We detected no biases in juvenile survival estimates from CJS-pop in the simulation data (Figure S2). Juvenile survival estimates of Brown Creeper were similar between a densitydependent CJS-pop, and a CJS model that did not include fecundity or density dependence estimation but accounted for "transient" juveniles that leave their population in their first year (0.32 and 0.30, respectively). However, using information from fecundity and adult survival in

279 setting the prior for juvenile survival reduced the estimation uncertainty considerably in CJS-

pop. The 95% credible interval for juvenile survival in the CJS model is 0.08 - 0.71, while in

- 281 CJS-pop this interval is 0.19 0.48.
- 282 *3 Density Dependence Strength Estimation*

283 Density dependence strength in mark-recapture studies is usually estimated using 284 abundance directly as a covariate (for example, Nater et al. 2018). This approach can become 285 problematic with more than one population, especially when each population has different 286 habitat characteristics and therefore can support different number of individuals. If the goal is to 287 estimate a species-specific density dependence strength that is applicable across all populations 288 of the species, abundance of each population in each time step should be standardized with a 289 proxy for how many individuals each population can support (e.g. carrying capacity). Here, we made this standardization using long-term abundance average of each population (equation 3). 290 291 The density dependence strength we estimate is minimally biased for capture histories generated 292 by moderate and strong density dependence (Fig. S1). There is a more apparent bias when 293 capture histories are generated with weak density dependence (Fig. S1). However, the weak 294 density dependence strength we used does not constitute a biologically realistic scenario if we 295 consider the intrinsic growth rate associated with the density dependence strength from an 296 allometric standpoint (See Appendix S2 for discussion on this). Most importantly, density 297 dependence strength estimates of survival and fecundity are ready to be used for population 298 projections.

299 *4 – Population Projections* 

300 Estimation of fecundity, juvenile survival, and density dependence strength makes it301 possible to make population projections that are useful for conservation purposes. All of these

302 three vital rates and demographic parameters are required, in addition to what is estimated in 303 standard CJS models, to build a stage-structured population model. However, instead of 304 fecundity, a parameter called recruitment rate is frequently estimated from frameworks such as 305 IPM (for example, Ahrestani et al. 2017). This parameter cannot be used in stage-structured 306 population models because it combines information from both emigration rate and the number of 307 new-born individuals. Additionally, including only fecundity estimation in a CJS framework is 308 also not enough, because without density dependence, these population projections would not be 309 biologically meaningful. Population projections tend to explode in size or go extinct under 310 exponential growth when there is environmental stochasticity that is not regularized by density 311 dependence (Fig 1). The usefulness of this regularizing effect is also visible in the distribution of 312 minimum abundances from population projections. A density-independent model cannot capture 313 the minimum abundance distribution generated with a stochastic and density-dependent 314 simulation, even when density dependence is weak. (Fig 2).

315 Trade-offs

Using robust design mark-recapture data as the sole data set for the CJS-pop framework requires several trade-offs. First, we estimate expected juvenile abundance twice ( $N_1$  in equation 2 and  $N'_1$  in equation 5a). If we only use  $N'_1$ , JAGS will give an error regarding the circular structure of the model because  $N'_1$  would also have been used in the denominator of equation 3. We see this as a minor issue because  $N'_1$  is used in the estimation of fecundity and we showed that fecundity can be estimated without bias in this structure (Figure S4).

Second, we estimate population sizes as expected values rather than random variables in
 CJS-pop framework. Modelling population sizes as random variables either requires informative
 priors on population sizes themselves or another data set, such as population counts, to make the

model more stable and allow convergence (this is essentially what IPMs do). Here, however, we
wanted to show that the vital rates necessary for population models can be estimated using only
mark-recapture data. Using expected abundance, while not ideal, ensures that this framework
requires only a single data source.

329 Third, we use a Poisson distribution instead of a binomial in equation 5b. Number of 330 captured juveniles cannot be higher than the actual number of juveniles; this relationship is 331 explicitly modelled as such with a binomial distribution. However, because we are using 332 expected abundances in CJS-pop, there could be instances when there are more captured 333 individuals than the expected abundance. Poisson distribution, by allowing such instances to 334 occur, increases model stability and eases convergence. Because Bayesian p-value for brown 335 creeper data is 0.5, we can say that this structure can represent the data well (Bayesian p-values 336 close to 0.5 indicate better fit; Kéry and Royle 2016). Last but not least, the framework we 337 present here is complex and in JAGS it takes for about 20 hours for Brown Creeper model to 338 converge.

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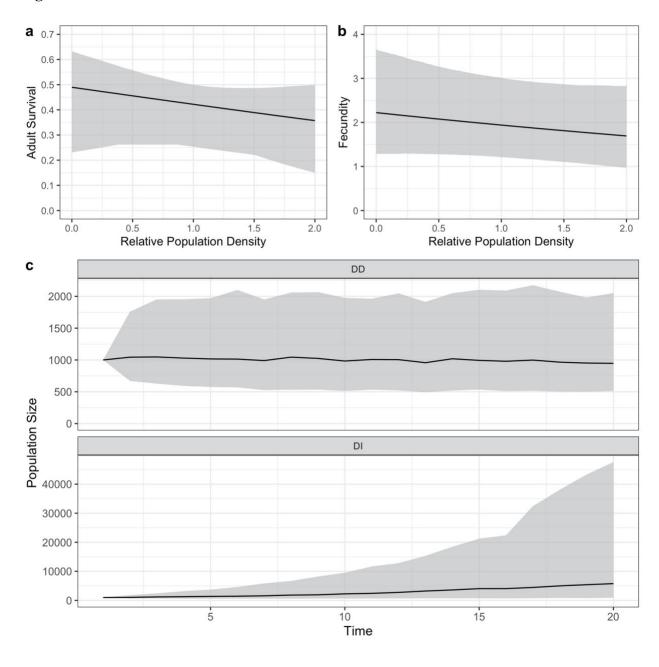
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# **Figure Legends**

| 372 | <b>Figure 1:</b> a) Relationship between adult survival and relative population density $(D)$ of  |
|-----|---|
| 373 | Brown Creeper as modeled by CJS-pop. b) Relationship between fecundity and relative               |
| 374 | population density $(D)$ of Brown Creeper as modeled by CJS-pop. c) Solid line indicates the      |
| 375 | median trajectory of population size, across 12000 trajectories, of Brown Creeper projected by a  |
| 376 | stage-structured population model that was parameterized with a Density-Dependent (DD) or         |
| 377 | Density-Independent (DI) CJS pop. Shaded areas include 50% of the population trajectories.        |
| 378 | Carrying capacity was set to 1000 in the DD projections. Note the difference in scale in          |
| 379 | population size between DD and DI projections.  |
| 380 | Figure 2: Distributions of minimum abundances resulting from population projections               |
| 381 | made with stage-structured population models that were parameterized with CJS-pop fit to          |
| 382 | Brown Creeper data (a), and with CJS-pop fit to simulation sets that was generated with different |
| 383 | density-dependence strengths (b,c,d). Light blue represents parameterizations of population       |
| 384 | models with density-independent (DI) CJS-pop, orange represents density-dependent (DD) CJS-       |
| 385 | pop, and green (TRUE) represents population models that was parameterized with original           |
| 386 | simulation parameters that was used to generate capture history data. High probability density at |
| 387 | 0 and 1000 indicates frequent population extinctions and explosions, respectively.                |
| 388 |   |

## 389 Figure 1



391

## **Figure 2**

