Exact Bayesian lineage tree-based inference identifies Nanog negative autoregulation in mouse embryonic stem cells

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Abstract

The autoregulatory motif of Nanog, a heterogeneously expressed core pluripotency factor in mouse embryonic stem cells, remains debated. Although recent time-lapse microscopy data provide the unparalleled ability to monitor Nanog expression at the single-cell level, the extraction of mechanistic knowledge is precluded by the lack of inference techniques suitable for noisy, incomplete and heterogeneous data obtained from proliferating cell populations.

This work identifies Nanog's autoregulatory motif from quantified time-lapse fluorescence lineage trees with STILT (Stochastic Inference on Lineage Trees), a novel particle-filter based algorithm for exact Bayesian parameter inference and model selection of stochastic models. We first verify STILT's ability to accurately infer parameters and select the correct autoregulatory motif from simulated data. We then apply STILT to time-lapse microscopy movies of a fluorescent Nanog fusion protein reporter and reject the possibility of positive autoregulation. Finally, we use STILT for experimental design, perform *in silico* overexpression simulations, and experimentally validate model predictions via exogenous Nanog overexpression. We finally conclude that the protein expression dynamics and overexpression experiments strongly suggest a weak negative feedback from the protein on the DNA activation rate.

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35   We find that a simple autoregulatory mechanism can explain the observed heterogeneous

36   Nanog dynamics. This finding has implications on the understanding of the core pluripotency

37   network, such as supporting the ability of mESC populations to diversify their proteomic profile

38   to respond to a spectrum of differentiation cues. Beyond this application STILT constitutes a

39   generally applicable fully Bayesian approach for model selection of gene regulatory models on

40   the basis of time-lapse imaging data of proliferating cell populations. STILT is freely available at:

http://www.imsb.ethz.ch/research/claassen/Software/stilt---stochastic-inference-on-lineage-trees.html

Introduction

43

44   Nanog is a key regulator of pluripotency, whose expression is fundamentally stochastic, involv-

45   ing the chance synthesis, degradation and interaction of biochemical species [1,2]. It is heteroge-

46   neously expressed [3–5], exhibiting strong fluctuations in expression [4,6] which may serve to prime

47   mESCs for differentiation [6,7]. Nanog binds its own enhancer as a homodimer [8], and Nanog-

48   dependent feedback loops are thought to be critical to mESC regulation [9]. However, Nanog's

49   mode of autoregulation has been debated. While Nanog has long been thought to exhibit posi-

50   tive autoregulation [10,11], recent studies have provided evidence for both negative feedback [12,13]

51   and no direct feedback [14].

52

53   Nanog's intriguing heterogeneity and its associated biological implications have motivated sev-

54   eral deterministic and stochastic models of Nanog regulation [15–19]. While reported deterministic

55   models provide a population level description [15,17], they are unable to capture pluripotency fac-

56   tor heterogeneity [20,21] and the existence of subpopulations [5,22–24]. Previous stochastic models

57   describe single-cell dynamics but neglect heterogeneity arising from intrinsic noise generated by

58   bursty production of mRNA [25] or slow promoter-switching dynamics [26] which may vary between

59   cells. Based on the available data, a variety of mechanisms have been proposed to recapitulate

60   Nanog's bimodal expression distribution [3] including bistable switches, stochastic oscillations [16],

61   and excitatory systems [18]. To ultimately discriminate between such mechanisms, quantitative

62   model selection based on single-cell data is required.

63

64   Time-lapse fluorescence microscopy provides a means to unambiguously label, track and quan-

65   tify individual cells, thus providing critical insight into dynamics of gene expression [27,28]. Cells

66   may be monitored as they proliferate, thereby establishing a cellular lineage tree, capturing

67   long-term regulatory programs such as the onset of expression of lineage-determining markers

68   in progenitor cells [29] or heterogeneous response to external perturbation [30] at the transcript and

69   protein level. Time-lapse fluorescence microscopy is thus well suited for investigating causative

70   relationships between genes [31,32], and has recently been applied to Nanog dynamics in mESCs

71   [4,5,14,33]. However, to our knowledge, no attempt has been made to directly fit time-lapse Nanog

72   data with stochastic dynamical models, infer parameters, and perform model selection such as

73   of competing autoregulatory motifs.

74

75   Statistical inference based on single-cell time-lapse data presents several challenges. Stochas-

76   tic models typically elude analytical solution except for simple models in the steady-state [34,35] or

77   transient dynamics under simplifying assumptions [36–38]. Simplifications of fully stochastic mod-

78   els, such as the linear noise approximation, are often not appropriate in the context of low copy

79   numbers where moments are poorly estimated [39]. Particle filter based methods for inferring the

80   unknown copy number of chemical species and associated model parameters have been suc-

81   cessfully applied to single-cell time series data [40]. However, proliferating cell populations require

82   special models capturing cellular relatedness, and observations are typically noisy and incom-

83   plete. Thus, extracting mechanistic knowledge from single-cell time-lapse fluorescence micros-

84   copy data requires methods suited to noisy, partially- and discretely-observed, heterogeneous

85   data with small molecule numbers, small, proliferating cell populations, and intrinsic stochastici-

86   ty.

87

88   To address these challenges and infer Nanog's autoregulatory mechanism, we introduce **St**o-

89   chastic **I**nference on **L**ineage **T**rees (STILT), for fitting stochastic gene regulation models to

90   time-lapse data of proliferating cells with known genealogy (lineage tree). STILT originally ex-

91   tends exact Bayesian parameter estimation and model selection for stochastic models to tree-

92   structured data, thus enabling the investigation Nanog autoregulation using time-lapse fluores-

93   cence microscopy movies and providing a valuable, general tool for the analysis of single-cell

94   time-lapse data. We demonstrate STILT's capability to infer parameters and select among three

95   models of transcriptional autoregulation: positive, negative and no transcriptional feedback. We

96   then investigate the autoregulatory motif governing Nanog dynamics in a recently published

97   Nanog single-cell time-lapse dataset [4]. We compute the evidence for each model, enabling us to

98   reject positive feedback as a likely mode of Nanog autoregulation. To resolve between no feed-

99   back and negative feedback, we design an informative perturbation experiment, predict and

100 subsequently verify its response, finally identifying weak negative feedback as Nanog's most
101 probable autoregulatory motif.

Results

STILT: A stochastic inference algorithm using tree-structured time-lapse fluorescence microscopy data

105 We introduce STILT for performing parameter inference and model comparison for stochastic
106 chemical reaction networks from fluorescence microscopy movies of proliferating cells; details
107 are contained in the Online Methods. STILT requires as input quantitative single-cell time series
108 data derived from time-lapse fluorescence microscopy along with the corresponding cellular lin-
109 eage trees (Fig. 1A). STILT iteratively proposes new samples (particles) for both the unknown
110 latent history of the system (including potentially unobserved species) and the distribution of pa-
111 rameters given the observed data. It novelly couples the bootstrap particle filter [41] to a model of
112 cell division to facilitate inference of stochastic gene regulation models, compute evidences,
113 perform model comparison, and infer parameters. By comparing proposed trajectories with the
114 data, incompatible particles are removed, enriching the population for informative particles. Pa-
115 rameter posterior distributions are approximated by the particle mixture distribution after itera-
116 tively including all observations.

117

118 STILT requires the specification of one or more candidate models in the form of chemical reac-
119 tion networks (Fig. 1B), which relate chemical species via their reactions' stoichiometry and ki-
120 netic constants. Since the true values of parameters are generally not known, a prior distribution
121 (i.e. from literature) is required for each parameter (Fig. 1B). STILT (Fig. 1C) then combines the
122 experimental data, prior distributions and model structures to estimate parameters and latent
123 histories, and approximate model evidence (Fig. 1D). Using the evidence, one can compute
124 Bayes factors to assess the relative probability of each model and potentially reject models that
125 cannot explain the data.

Autoregulatory motifs

126

127 We considered three motifs for Nanog autoregulation: No Feedback (Fig. 2A), Negative Feed-
128 back (Fig. 2B), and Positive Feedback (Fig. 2C); protein affects the DNA activation/inactivation
129 rate in case of feedback. Each model comprises a single gene in either an inactive conformation
130 (D) with no transcription, or an active conformation (D*) with stochastic transcription, and mRNA
131 (M) and protein (P) (see Online Methods for details). These molecular species are governed by
132 six reactions for activation/inactivation of DNA, and production and degradation of
133 mRNA/protein (Table 1). In the following we first validated model selection with STILT using
134 synthetic data, and subsequently applied STILT to real Nanog time-lapse data.

In silico validation

135

136 We evaluated STILT on synthetic datasets generated from the above-described autoregulatory
137 motifs (Fig. 2A-C). We simulated each model to yield lineage trees with 3 generations and 7
138 cells (Fig. 2D-F, solid lines). Parameters were chosen such that cells have similar protein levels
139 (10^3-10^4 molecules) in each model (Supplementary Table 1). We assume that only protein
140 abundance was measured. Gaussian noise (=200 proteins) was added to simulate measure-
141 ment error.

142

143 We applied STILT to each lineage tree using suitable priors (Supplementary Fig. 1, Supple-
144 mentary Table 2), with three runs per dataset to assess robustness. Importantly, we find that
145 STILT proposes trajectories which completely contain the observed time series for each simu-
146 lated dataset (Fig. 2D-F, shaded areas); if sampled trajectories would not contain the data it
147 would strongly indicate against that model and/or priors. The unobserved mRNA trajectories are
148 also well inferred by the particle filter (Supplementary Fig. 2). Using fractional errors of each pa-
149 rameter, $\frac{\theta_i - \theta_i^{true}}{\theta_i^{true}}$, where θ_i^{true} is the true value of parameter *i*, we find general improvement
150 compared to priors (Fig. 2G-I). While many parameters are estimated accurately and well con-
151 tained in the posterior, some parameters are poorly identifiable, probably due to insufficient in-
152 formation content of the simulated data. Parameters are robustly estimated when the model is
153 correct (Supplementary Fig. 3); inference with an incorrect model may result in local optima
154 when the observed transitions are very unlikely to occur.

155

156   We evaluated the ability to select among different models by computing the model evidence

157   (defined as the marginal log likelihood of the model), of each model/dataset combination. We

158   then compute the (log) Bayes factors, i.e. differences in the evidence (Fig. 2J), and find that the

159   true model is preferred in each case. Typically a log Bayes factor larger than 3 is considered

160   strong evidence [42]. For example, the difference in evidence of the (correct) No Feedback and

161   (incorrect) Negative Feedback model (Fig. 2J, top row) is -43.48 ± 1.54 (mean ± s.d., n=3 runs),

162   indicating strong preference for the No Feedback model. Moreover, the log Bayes factor be-

163   tween the correct model and the incorrect models is strong (≥ 3) and robust for the true model in

164   each scenario. We compared STILT to a conventional particle filter-based algorithm which ig-

165   nores cellular genealogy, inferring parameters for each cell independently. In several instances

166   the correct model was not identified, and the Bayes factors were generally smaller when ne-

167   glecting genealogy (Supplementary Fig. 4, Supplementary Table 3). Thus, STILT presents a

168   substantial improvement over this simpler approach.

169

170   Although Bayes factors facilitate model selection, it is not in general possible to determine

171   whether a model is "compatible" with a particular dataset, i.e., if the data could have realistically

172   been generated by that model with the inferred parameters. Thus, we developed a simple test to

173   assess the correctness of the inferred model and parameters by comparing the likelihood of the

174   data with the likelihood of synthetic datasets using the assumed model and inferred parameters.

175   We categorized each model as either reject (test statistic outside 98% confidence interval),

176   marginal (outside 95% confidence interval), or accept (within 95% confidence interval). Our

177   goodness-of-fit test accepts the true model for each dataset (green diagonal in Fig. 2K). By con-

178   trast, the goodness-of-fit test rejects the Negative Feedback model fit to the Positive Feedback

179   and No Feedback datasets, and the Positive Feedback model fit to the Negative Feedback and

180   No Feedback datasets (red), from which we can deduce that the model is unlikely to be correct

181   for that dataset. However, the No Feedback model shows agreement with simulated datasets

182   from both the Negative and Positive Feedback models. This level of agreement is likely due to

183   the less constrained expression dynamics of the No Feedback model compared to the other

184   models.

Inference of Nanog autoregulatory motifs using time-lapse fluorescence genealogies rejects positive autoregulation

We next applied STILT to study the debated autoregulation mechanism of Nanog, using time-lapse data from a recent single-cell study [4]. In these experiments, the fluorescence intensity of NanogVENUS, a reporter for the protein expression of the pluripotency factor Nanog, was quantified for single cells over several generations (Fig 3A). We converted fluorescence intensities in 15 subtrees (7 cells per subtree) to absolute protein numbers (see Online Methods) and performed minimal data cleaning to remove incorrectly segmented or quantified measurements (Supplementary Fig. 5). Finally we used STILT to perform inference with the three autoregulatory motifs introduced above. Prior distributions for each model parameter were estimated from available knowledge (Supplementary Table 4).

First, we evaluated the inference results on the Nanog time-lapse data. STILT produced sampled trajectories that agree well with the measured time series (Fig. 3A-B shows one subtree fit with the No Feedback model; see Supplementary Fig. 7 for all models and subtrees), indicating that all models are capable of reproducing the observations with the assumed parameter distributions, albeit with varying likelihoods. The estimated latent mRNA abundances (Fig. 3B) agree well with recent estimates of approximately 100-300 copies per cell [5,43]. We find that the subtrees are informative in the sense that they cause shifts in the parameter posterior distributions relative to the priors (Fig. 3C, Supplementary Fig. 8, Supplementary Table 5). Moreover, parameters are robustly estimated over three technical replicates (Supplementary Fig. 8). Next, we estimated the evidence of each model for each subtree (Supplementary Table 6). We find that the No Feedback model is preferred in most cases (11/15), and is significantly greater than the next best model in 10 of these instances (Fig. 3D). For four subtrees the Negative Feedback model is preferred, and is significantly greater in two of these. By contrast, the evidence was consistently much lower for the Positive Feedback model.

Finally, we used the goodness-of-fit test to assess the ability of each model to explain the data. We found that both the No Feedback and Negative Feedback models agree well with the observed datasets when using the median of the estimated posteriors (Fig. 3E; Supplementary Fig. 9, Supplementary Table 7). The Negative Feedback model is compatible with the most subtrees (13/15 accepted); in contrast only 8/15 subtrees were compatible with the No Feedback model (5 subtrees were marginally accepted). However, the Positive Feedback model is ac-

218 cepted for only 5/15 subtrees, and marginally for one additional subtree. For two subtrees no

219 model could be rejected, and for subtree 14 all models are rejected (Supplementary Table 7).

Model-based experimental design for selection of Nanog autoregulation motif

222 Based on the goodness-of-fit test and Bayes factors analysis, we can reject positive feedback

223 as a putative motif for Nanog autoregulation for the analyzed datasets. To discriminate between

224 the remaining two alternatives, we used STILT to devise an experiment whose outcome would

225 differ significantly for the No/Negative feedback models. We consider exogenous transgenic

226 Nanog, which would increase the effective rate of DNA inactivation in the Negative Feedback

227 model (Fig. 4A). We simulated negative feedback using the previously inferred parameters,

228 while introducing varying levels of exogenous Nanog (P_{ex}). We found a strong shift in endoge-

229 nous Nanog dynamics at only a few hundred thousand molecules of exogenous Nanog, and

230 complete down-regulation for $P_{ex} > 10^6$ (Fig. 4B). By introducing exogenous Nanog we expect

231 rapid decrease in endogenous Nanog levels for the Negative Feedback model, in contrast to

232 constant levels for the No Feedback model (evaluated at 46h, Fig. 4C).

233

234 We tested our model prediction using an mESC line with fluorescent reporters for both endoge-

235 nous and exogenous Nanog (Supplementary Fig. 10A). We quantified exogenous Nanog and

236 defined 5 compartments of expression: No Exogenous, 1x, 2x, and 3x overexpression (OE), and

237 "very high", relative to endogenous expression in untransfected cells (Supplementary Fig.

238 10B,C). In agreement with recent reports [12,13], expression of transgenic exogenous Nanog was

239 found to induce a dose-dependent down-regulation of endogenous Nanog production (Fig. 4D).

240 We then replicated the experimental perturbation using STILT. Using the estimated parameters,

241 we simulated exogenous Nanog corresponding to the quantity of exogenous Nanog of each

242 overexpression compartment. We found excellent agreement between the predicted and meas-

243 ured decrease in endogenous Nanog expression levels upon perturbation (Fig. 4E). Note that

244 the prediction uses only parameters inferred from the time-lapse data and the estimated quanti-

245 ties of exogenous Nanog. The agreement suggests that the data are well explained by negative

246 feedback with the assumed mechanistic model, and not by the No Feedback model.

247

Comparative validation of estimated parameters for the Negative Feedback model

STILT yields estimates of parameters including the rate of switching between active and inactive DNA conformations, transcription and translation rates, and degradation rates of mRNA and protein. These estimates agree well with previous estimates. The inferred median mRNA degradation rate for each subtree ranges from 0.1145-0.4255 (mean 0.2262, n=15) per molecule per hour, which agrees well with the previous estimate of 0.147 [14] (see Online Methods). Protein degradation rates range from 0.0310-0.4410 (mean 0.2197) per molecule per hour, consistent with the previous estimates of 0.14-0.35 [4,44]. Thus, both Nanog protein and mRNA have a comparable half-life of ~3 hours. Transcription rates range from 67.2-181.8 (mean 110.3) per hour, consistent with the estimate of 126.6 per hour [14]. Translation rates range from 215.9-1142.0 per mRNA per hour. This quantity is not well characterized in literature, but agrees roughly with the estimate of up to 1000 estimated for mouse fibroblasts [45,46]. The mean value of these estimates across subtrees is similar between the No Feedback and Negative Feedback models: 115.0 vs 110.3 for translation; 0.258 vs 0.226 for mRNA degradation; 637.8 vs 619.5 for translation; and 0.241 vs 0.220 for protein degradation, for the No Feedback and Negative models, respectively.

DNA activation and inactivation rates cannot be easily assessed since they represent an abstraction of a more complicated biochemical process. For example, activation might correspond to changes in the DNA and histone modification state of the promoter which permit greater transcriptional activity [5]. Nonetheless, the estimated rate of activation ranges from 0.2737-1.737 (mean 0.6854) per hour, which is consistent with the estimate of 1.692 per hour in the simple unregulated telegraph model of Ochiai et al. [14]. The inactivation rate ranges from 0.1338×10^{-11}-1.123×10^{-10} (mean 5.6910×10^{-11}) per hour. In the Negative Feedback model this rate scales quadratically with the number of proteins to give a total rate of approximately 2.5-5.0 per hour (assuming $2-4 \times 10^5$ Nanog protein molecules per cell). This estimate is substantially smaller than the estimate of 36.54 per hour in the telegraph model [14]. However, there the model assumes DNA to be inactive whenever active transcription is not detected. In contrast, the stochastic nature of our model allows DNA to remain in the active state even between transcription events, which may contribute to a reduced overall rate of DNA inactivation. We also note that the estimated number of mRNAs inferred by STILT, which ranges from approximately 0-300, agrees well with previous estimates of approximately approximately 100 ± 100 [5,43,47], see Supplementary Fig. 7. In summary, STILT achieves comprehensive rate constant estimates of the different

281 processes governing Nanog dynamics solely from a time-lapse study. These are in good
282 agreement with the results from various dedicated studies, each independently focusing on se-
283 lected aspects such as DNA (in-) activation or mRNA/protein synthesis and degradation.

284 Discussion

285 A variety of hypothetical mechanisms for Nanog regulation have previously been proposed, in-
286 cluding bistability or oscillations [16], and excitatory excursions from a stable state [18]. Such mech-
287 anisms can produce heterogeneous steady state distributions similar to those observed in
288 snapshot experiments [3,48]. On the other hand, Nanog transcriptional dynamics have been de-
289 scribed statistically using a simple unregulated telegraph model, fit to the timing of periods of
290 gene activity [14]. However, until now extracting mechanistic knowledge from fluorescent fusion
291 protein trajectories has been hampered by the lack of suitable inference techniques. In particu-
292 lar, the intrinsic stochasticity of Nanog expression at the single-cell level and the proliferating
293 nature of mESC populations necessitate an approach that is fully stochastic, Bayesian, and
294 suited to tree-structured data. Using STILT, we overcome these challenges to make use of the
295 full information content of time-lapse fluorescence movies, and quantitatively fit and select
296 among putative models of autoregulation.

297

298 Interestingly, STILT indicates greater evidence for the No Feedback model for many subtrees,
299 and Negative Feedback for fewer subtrees; Positive Feedback consistently has the lowest evi-
300 dence. However, the goodness-of-fit test indicates superior agreement with data for the Nega-
301 tive Feedback model. The stronger evidence for No Feedback arises because the fitted parame-
302 ter values are *a priori* more likely with the assumed priors compared to those of the Negative
303 Feedback model; the Negative Feedback model agrees with the data for a more limited set of
304 parameters, which were assumed to be less likely. However, as for all Bayesian inference
305 methods, this result is influenced by the choice of priors and thus should be considered in con-
306 text of the goodness-of-fit test results.

307

308 To discriminate between No Feedback and Negative Feedback, we used STILT as an experi-
309 mental design tool, and quantitatively predicted the strength of down-regulation upon overex-
310 pression. Further investigation using novel experiments revealed the expected strong down-
311 regulation upon high expression of transgenic Nanog, in very good agreement with model pre-
312 dictions. Taken together, we conclude that Nanog negative autoregulation is indeed likely, but

313   has a prominent effect only at relatively high levels of protein expression, which renders model

314   discrimination based on Bayes factors alone difficult . The lack of strong autoregulation sug-

315   gests stable oscillations [16] to be unlikely, in accordance with previous analysis [4], and supports

316   the notion that Nanog undergoes broad fluctuations which serve to diversify the mESC popula-

317   tion's ability to respond to differentiation cues [6,7].

318

319   The inferred motif naturally represents a simplification of Nanog's true regulatory mechanism.

320   For example, although Nanog autoinhibition is thought to be mediated by Zfp281 and the NuRD

321   complex [12], these factors are omitted for simplicity; this is equivalent to assuming Zfp281 abun-

322   dance to be approximately constant. We further neglect the possibility of monoallelic expression

323   of Nanog. However, it has been previously shown that Nanog that both Nanog mRNA and pro-

324   tein are highly correlated between alleles [47,48], motivating this assumption. Despite these simpli-

325   fications, the Negative Feedback model i) produces sample trajectories which reproduce the

326   observed data, ii) agrees quantitatively with observed fluorescence lineage trees using the

327   goodness-of-fit test, and iii) accurately predicts the magnitude of downregulation in overexpres-

328   sion experiments. Thus we conclude that the autoinhibitory motif provides a simple but accurate

329   description of Nanog protein dynamics, superior to the considered alternatives.

330

331   Fitting mechanistic models to time-lapse data facilitates the analysis of latent variables and en-

332   ables the design of informative experiments. The sampled trajectories provide valuable insight

333   into the dynamics of latent variables, including DNA activity and mRNA copy number. The in-

334   ferred trajectories can also be analyzed to provide information about gene activity, such as infer-

335   ring continuous versus bursty transcription, possible oscillations, refractory periods, etc. [49] For

336   example, examining the mRNA trajectories (Supplementary Fig. 7) we observe both burst-like

337   and sustained transcriptional modes.

338

339   Lastly, while we have focused on Nanog autoregulation, STILT may be used for inference and

340   model selection for arbitrary stochastic gene regulation models applied to fluorescence lineage

341   trees (e.g. in *B. subtilis* or *E. coli* [31,50]), thus enabling quantitative and exact analysis of lineage-

342   tracked time-lapse fluorescence data. The generic MATLAB implementation is provided as open

343   source with SBML compatibility for easy import of user-specified models.

Author contributions

344

345 TS and FJT conceived the interdisciplinary approach. CM and MC designed and supervised the
346 study. JF designed, developed and implemented STILT. SG developed the STILT package. JF
347 performed simulations and analysis. TS, SH planned and SH performed the exogenous Nanog
348 experiments. FJT and TS provided critical comments. JF, CM, MC wrote the manuscript.
349

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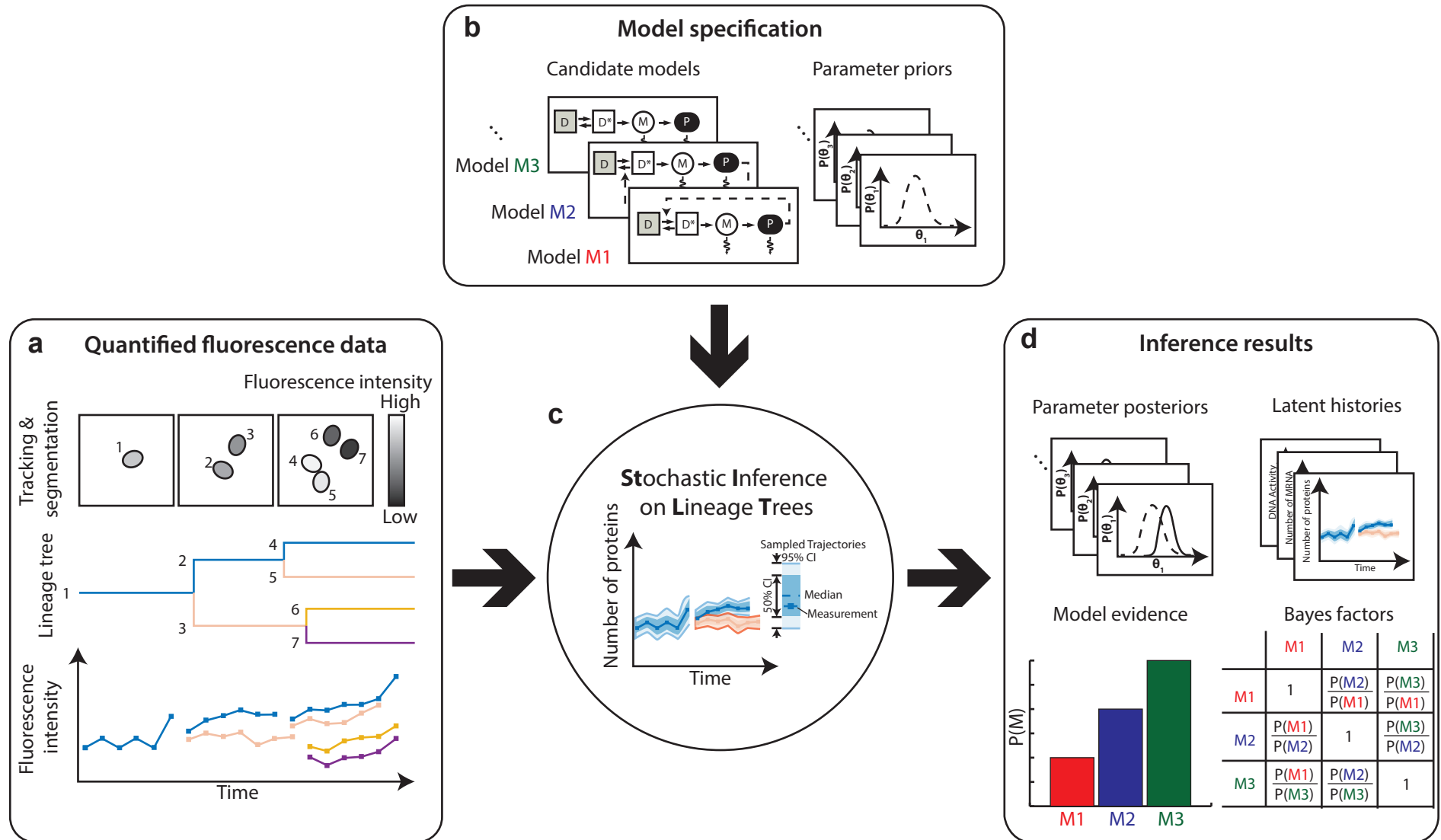
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469

Figure 1

b Model specification

Candidate models   Parameter priors

Model M3

Model M2

Model M1

$P(\theta_3)$ $P(\theta_2)$ $P(\theta_1)$

θ_1

a Quantified fluorescence data

Tracking & segmentation

Fluorescence intensity

High

Low

Lineage tree

Fluorescence intensity

Time

c

Stochastic **I**nference on **L**ineage **T**rees

Number of proteins

Sampled Trajectories

95% CI

50% CI

Median

Measurement

Time

d Inference results

Parameter posteriors   Latent histories

$P(\theta_3)$ $P(\theta_2)$ $P(\theta_1)$

θ_1

DNA Activity   Number of mRNA   Number of proteins

Time

Model evidence   Bayes factors

P(M)

M1   M2   M3

	M1	M2	M3
M1	1	$\frac{P(M2)}{P(M1)}$	$\frac{P(M3)}{P(M1)}$
M2	$\frac{P(M1)}{P(M2)}$	1	$\frac{P(M3)}{P(M2)}$
M3	$\frac{P(M1)}{P(M3)}$	$\frac{P(M2)}{P(M3)}$	1

a No Feedback **b** Negative Feedback **c** Positive Feedback

d

e

f

g

h

i

j

log Bayes factor (fitted vs. true)

strong ← → weak

-50 ——— 0

Fitted model

	No Feedback	Negative Feedback	Positive Feedback
True model No Feedback	0.00 (0.99)	-43.48 (1.54)	-35.82 (3.91)
Negative Feedback	-16.61 (0.25)	0.00 (0.48)	-27.78 (0.61)
Positive Feedback	-3.07 (0.05)	-20.19 (0.71)	0.00 (0.09)

k

Fitted model

No Feedback   Negative Feedback   Positive Feedback

Simulations ———
Data - - -

Accept
Marginal
Reject

Average log likelihood per transition

Figure 2

Figure 3

a

$$D \xrightleftharpoons[k_{on}]{} D^* \xrightarrow{k_m} M \xrightarrow{k_p} P_{en}$$

g_m g_p

$k_{off}(P_{en}+P_{ex})^2$

P_{ex}

b

No Exogenous ($P_{ex}=0$)

1x OE ($P_{ex}=2\times10^5$)

very high ($P_{ex}=10^6$)

Endogenous Nanog protein

Time (h)

c

Endogenous Nanog protein (P_{en})

No Feedback

Negative Feedback

Exogenous Nanog protein (P_{ex})

d

Density

No Exogenous
1x OE
2x OE
3x OE
very high
Detection limit

$\log_{10}$ Endogenous Nanog [a.u.]

Text

e

Endogenous Nanog protein

Model prediction
Measurement

No Exo.   1x OE   2x OE   3x OE   very high

Exogenous Nanog protein

Figure 4

Table 1

Reaction	Description	Reaction Propensity		
		No Feedback	Negative Feedback	Positive Feedback
DNA ➔ DNA*	DNA activation	k_{on} D	k_{on} D	k_{on} D P^2
DNA* ➔ DNA	DNA inactivation	k_{off} D*	k_{off} D* P^2	k_{off} D*
DNA* ➔ DNA* + mRNA	Transcription	k_m D*		
mRNA ➔ Ø	Degradation of mRNA	g_m M		
mRNA ➔ mRNA + Protein	Translation	k_p M		
Protein ➔ Ø	Degradation of protein	g_p P		

Figure captions

Figure 1: Exact Bayesian inference of stochastic gene regulation models using single-cell time-lapse fluorescence lineage trees. (A) Quantified fluorescence lineage trees are extracted from time-lapse fluorescence microscopy movies. The trees are combined with (B) candidate models and their respective parameter prior distributions and serve as input to the (C) particle filter-based inference algorithm STILT. (D) STILT generates estimates for the posterior distribution of each model parameter, latent histories, and evidence of each model. The latter is used for model comparison using Bayes Factors, which is the ratio of the marginal likelihoods of two models.

Figure 2: STILT correctly identifies autoregulatory models in synthetic data.
We consider three simple models of transcriptional control: (A) No Feedback, (B) Negative Feedback and (C) Positive Feedback. Models differ in the propensity of DNA (D/D*) activation and inactivation. Further components of the system comprise mRNA (M) and protein (P) (see Table 1 for details on system reactions). (D-F) We simulate each model to generate quantified lineage trees of measured protein numbers, and subsequently perform inference using STILT. The median (dashed line) and 50%, 95% confidence intervals of the trajectories sampled by the particle filter (band plots) show excellent agreement with the simulated data (dots). (G-I) STILT estimates posterior distributions of model parameters (red, 99% confidence interval). For many parameters the posterior shows improved estimates compared to the prior distribution (gray) in terms of the fractional error, defined as the error of each parameter sample divided by the true value of that parameter. A fractional error of zero indicates a perfect inference result. (J) Log Bayes Factors (mean, s.d., n=3 inference runs), i.e. the difference in the marginal log likelihood P of each model from that of the true model for each dataset, indicate that the correct model is always strongly preferred (white diagonal). (K) The goodness-of-fit test (see Methods) approximates the distribution of simulated average log likelihood per transition for simulations generated using the inferred parameters for each model (solid). If the average log likelihood of the actual dataset (dashed) falls within this distribution, it indicates good agreement of the dataset with the chosen simulated model.

Figure 3: Model comparison suggests that NanogVENUS expression dynamics in ESCs are best explained by the No Feedback or Negative Feedback model. (A) STILT yields samples for the latent trajectories of proteins that reproduce and contain the observed data (shown for the No Feedback model). Colony images are shown at the first time point of each

generation. (B) The latent history of mRNA is inferred and agrees with previous estimates of the mRNA copy number of Nanog in ESCs (shown for the No Feedback model). (C) We compare the estimated posterior distributions of model parameters for the same subtree fit with each of the models. We find that estimates for mRNA and protein parameters are robust between technical replicates and across models. (D) We compute the evidence of each model, shown relative to the average over all models for that subtree (mean, s.e.m., n=3), scaled by evidence range for that subtree (see Table S6 for absolute values). We find that the No Feedback model provides the largest evidence in most cases (*, significant with p<0.01), while the Negative Feedback model is preferred for four subtrees. The evidence for the Positive Feedback model is generally lower than the other models. The frequency for which each model is significantly more likely than remaining models is shown with a pie chart. (E) The goodness-of-fit test indicates that the Negative Feedback model is accepted for most subtrees (13/15) compared to 8/15 for No Feedback and 5/15 for Positive Feedback. Each model is rated as accept, marginal or reject based on the result of the goodness-of-fit test.

Figure 4: We experimentally verify the predicted response of the Negative Feedback model to Nanog overexpression. (A) We modify the Negative Feedback model to incorporate exogenous Nanog (P_{ex}) which acts with endogenous Nanog (P_{en}) to increase the propensity of DNA inactivation. (B) Using the previously inferred model parameters we generate synthetic trees for various levels of exogenous Nanog, illustrated for 0 molecules, 2×10^5 molecules (100% increase) and 10^6 molecules (500% increase). (C) We predict strong downregulation (fold-change relative to median expression of unperturbed cells) of endogenous Nanog (mean, ± 2 s.e.m., n=30 simulations) for the Negative Feedback model; the No Feedback model is unperturbed by exogenous Nanog. (D) Endogenous Nanog levels decrease as the amount of exogenous Nanog increases. Detection threshold shown as dashed line (see Figure S10A). (E) Using the Negative Feedback model with exogenous Nanog, we compare the predicted fold-change (box-and-whiskers) in endogenous Nanog in response to exogenous Nanog overexpression with the experimentally determined median fold-change (mean, s.e.m. of 3 replicates) (line). Fold-change is relative to median expression level of endogenous Nanog in the unperturbed (No Exogenous) compartment.

Table captions

Table 1: Propensity functions for the three autoregulation models (Negative, Positive, and No Feedback). Each model is characterized by different DNA activation and inactivation reaction propensities. The remaining propensities for transcription, translation, and degradation of mRNA and protein are identical for the three models.

a No Feedback
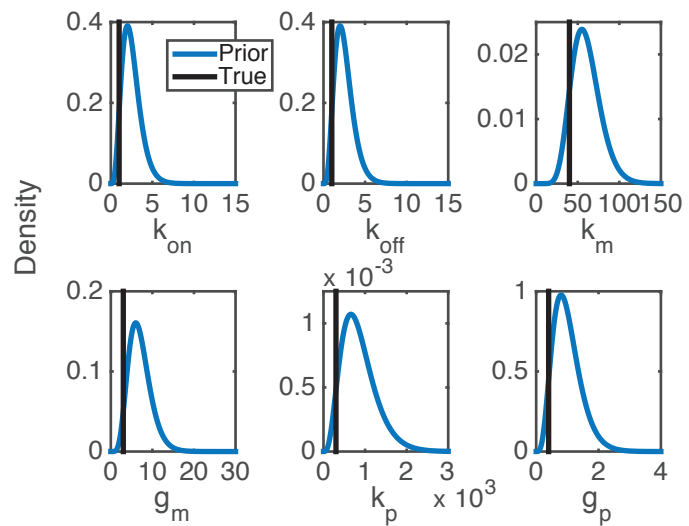
b Negative Feedback
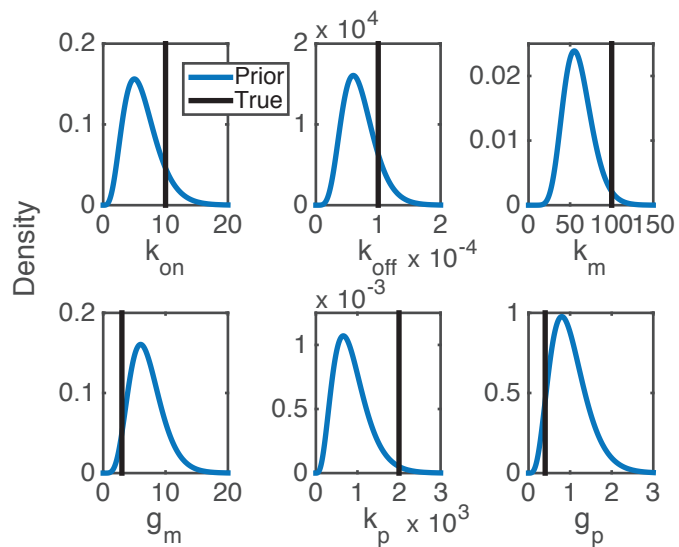
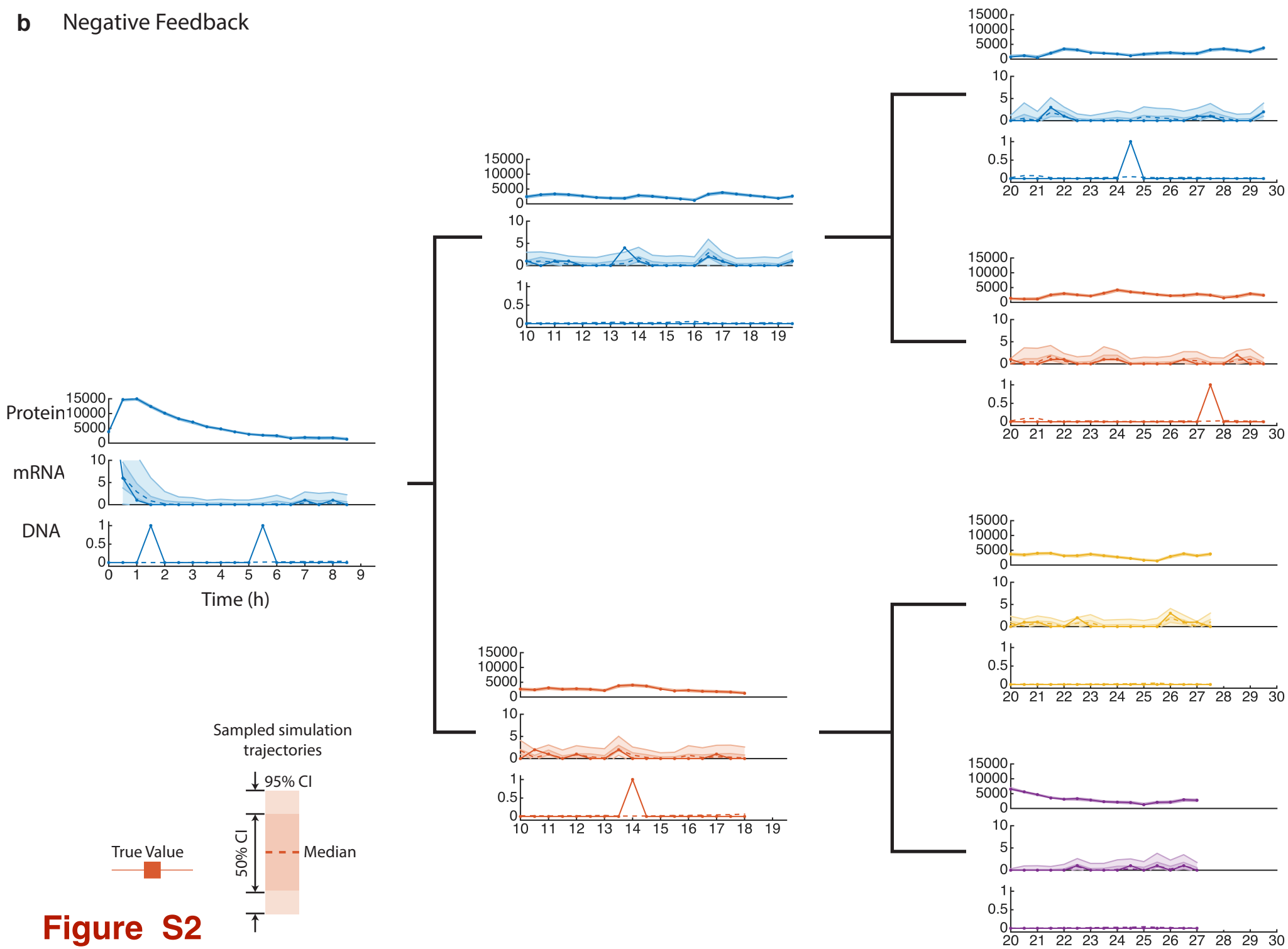**c** Positive Feedback
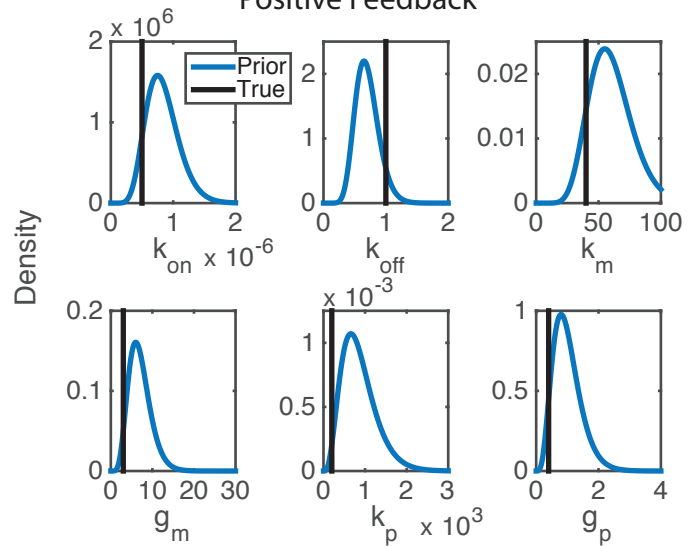
Figure S1

a No Feedback

Protein

mRNA

DNA

Time (h)

Sampled simulation
trajectories

95% CI

50% CI

Median

True Value
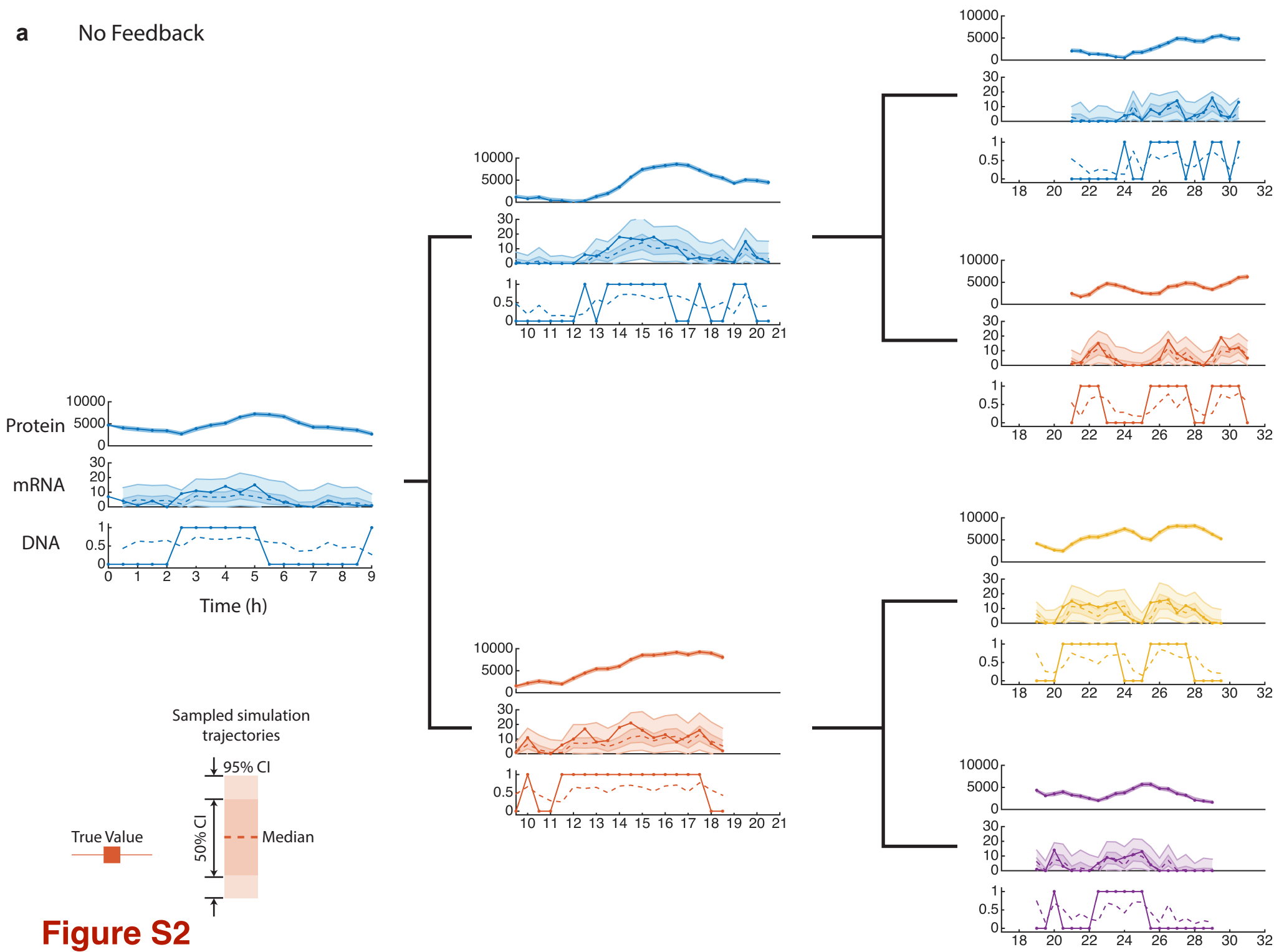
Figure S2

b Negative Feedback

Figure S2

c Positive Feedback

Protein

mRNA

DNA

Time (h)

Sampled simulation trajectories

95% CI

50% CI

True Value

Median
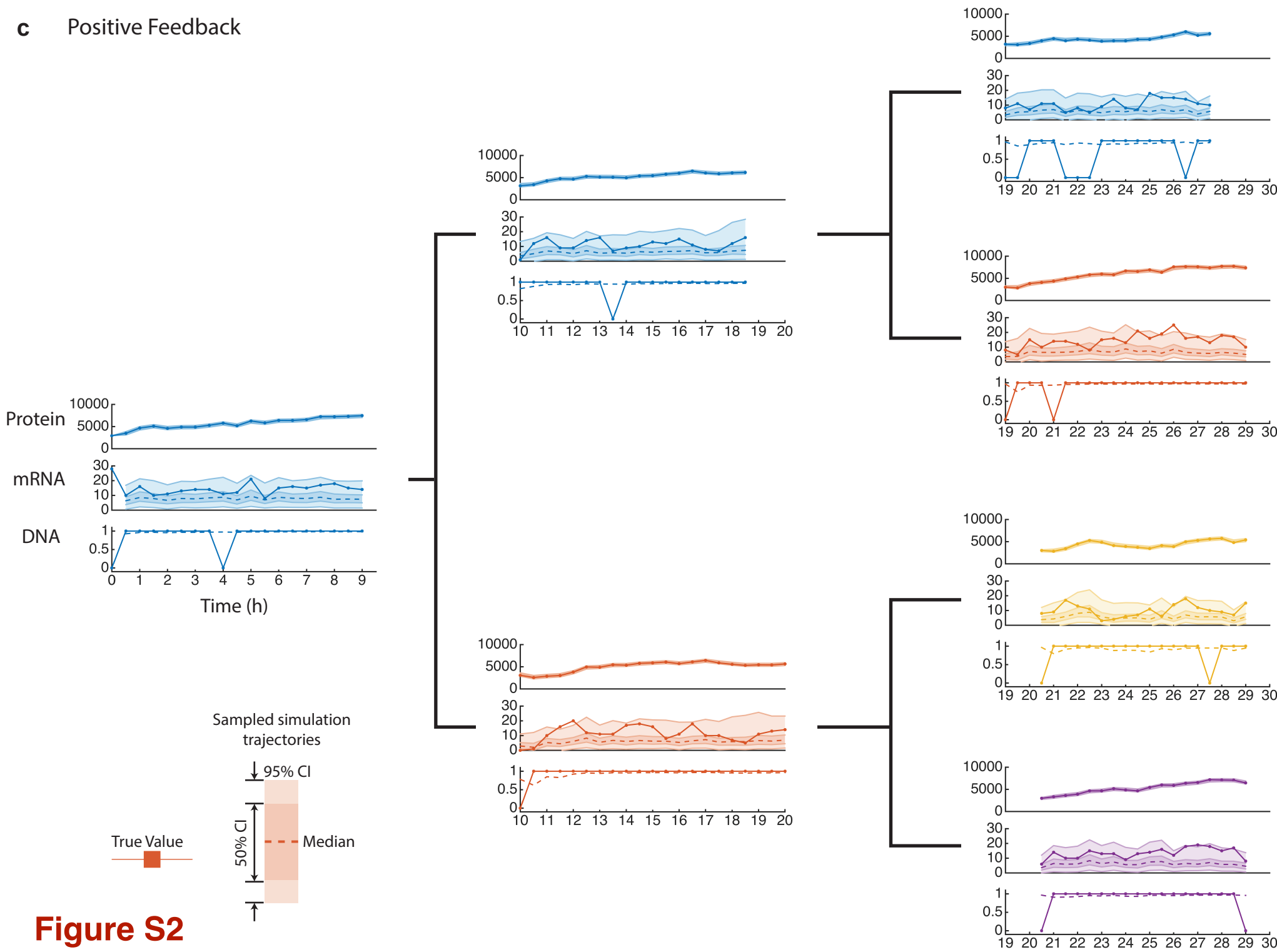
Figure S2

Figure S3

Model used for fitting
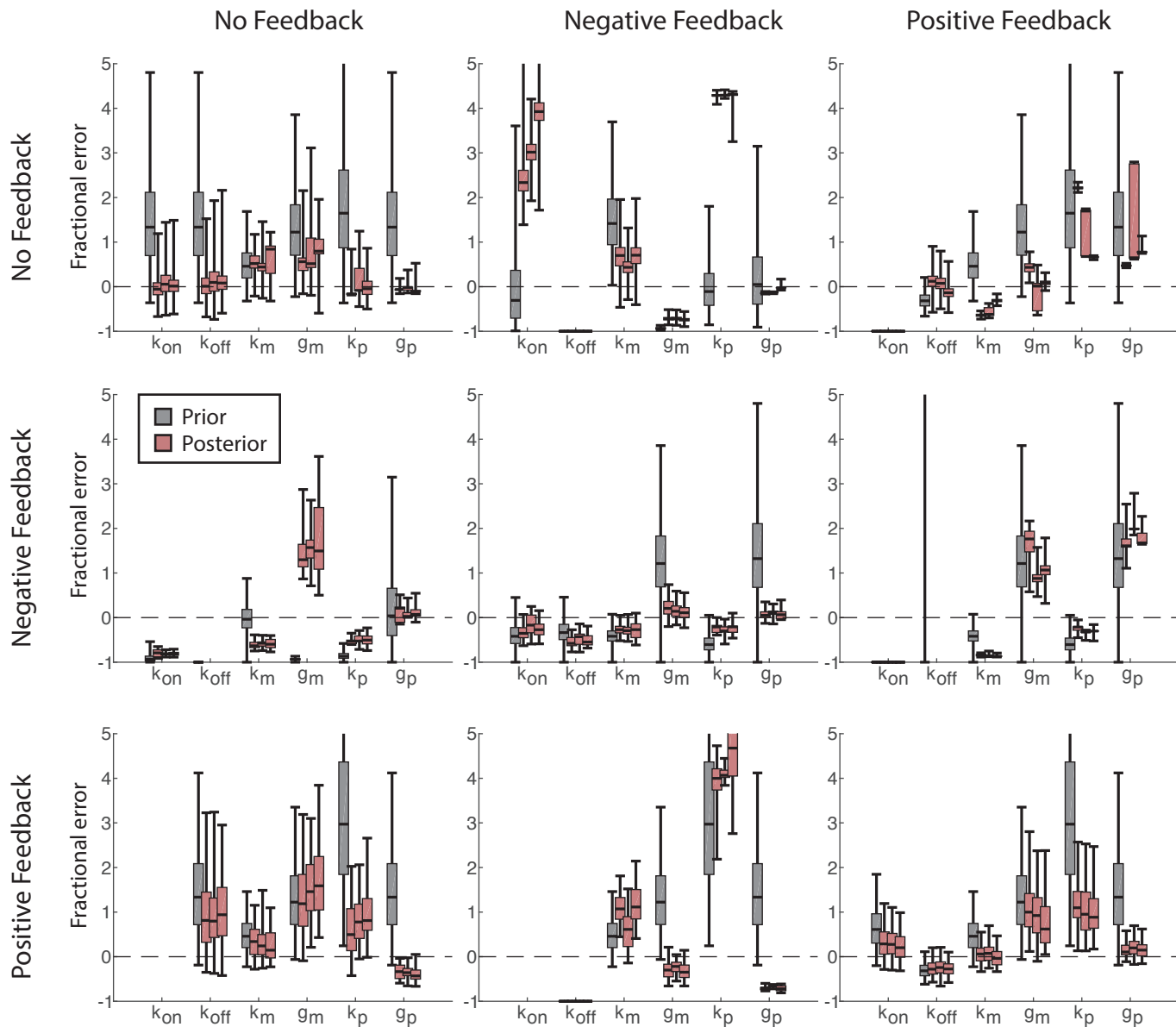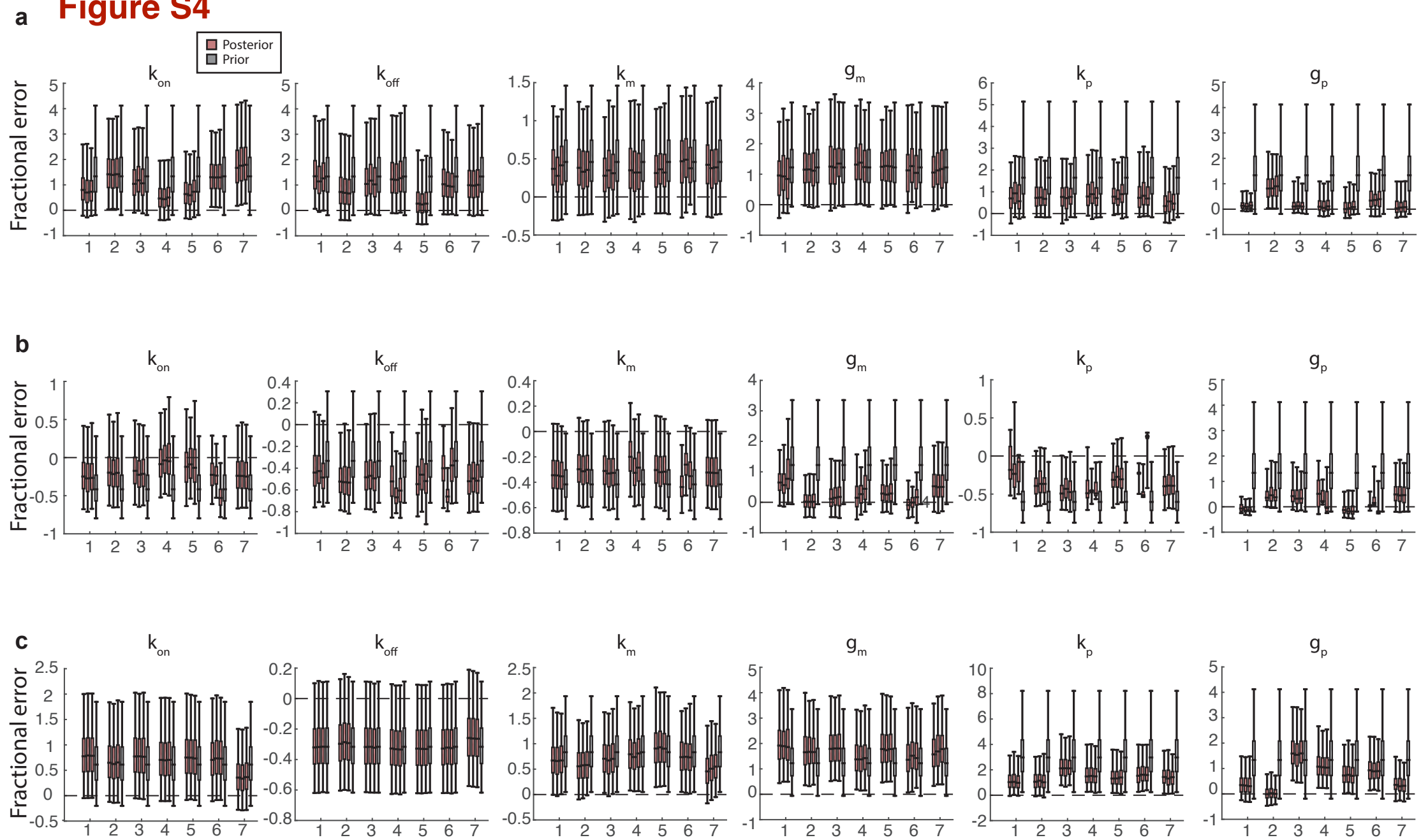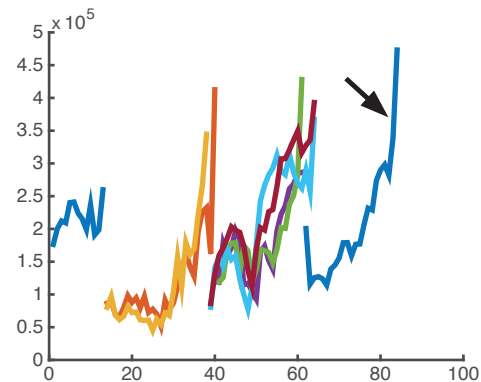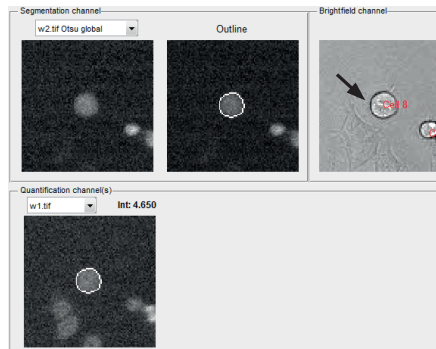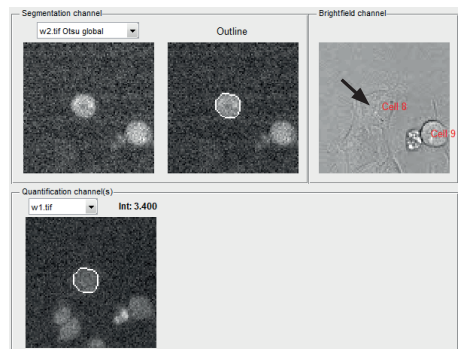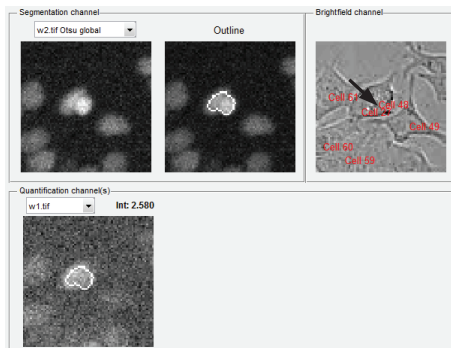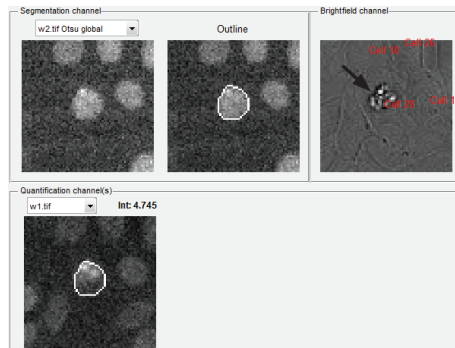
Figure S4

Figure S5

Figure S6

• Data point not used

Experiment 1

Experiment 2

Experiment 3
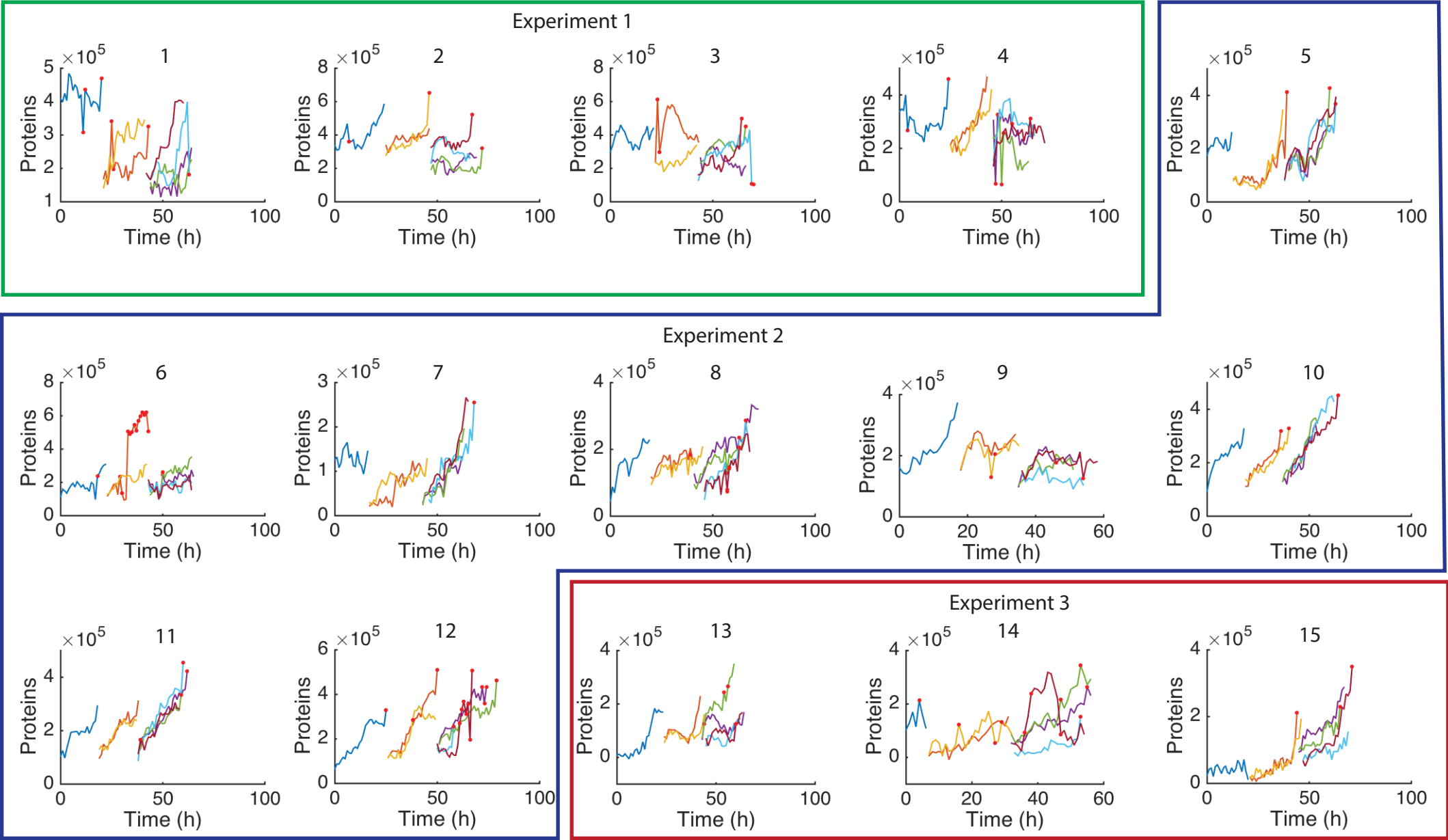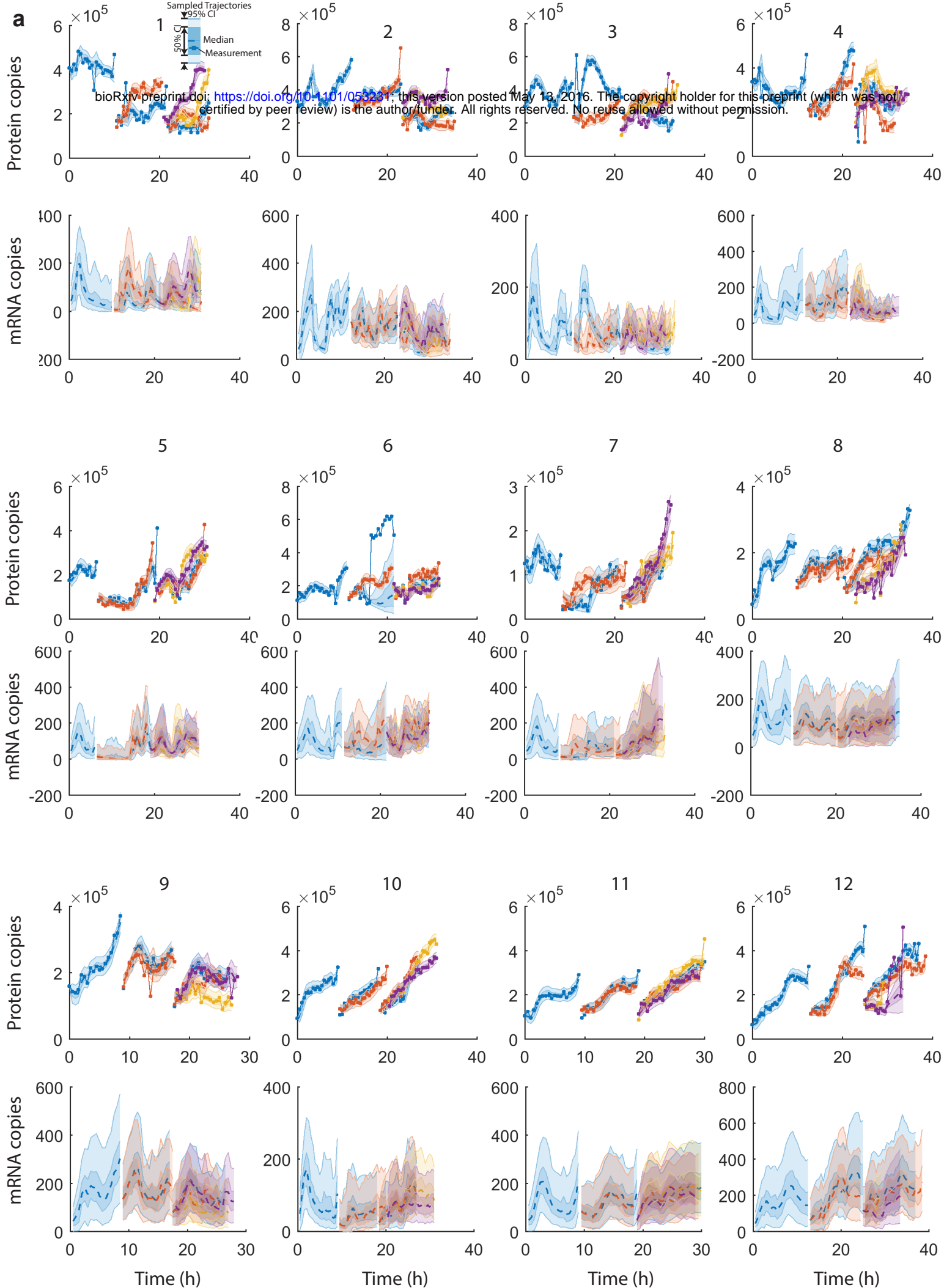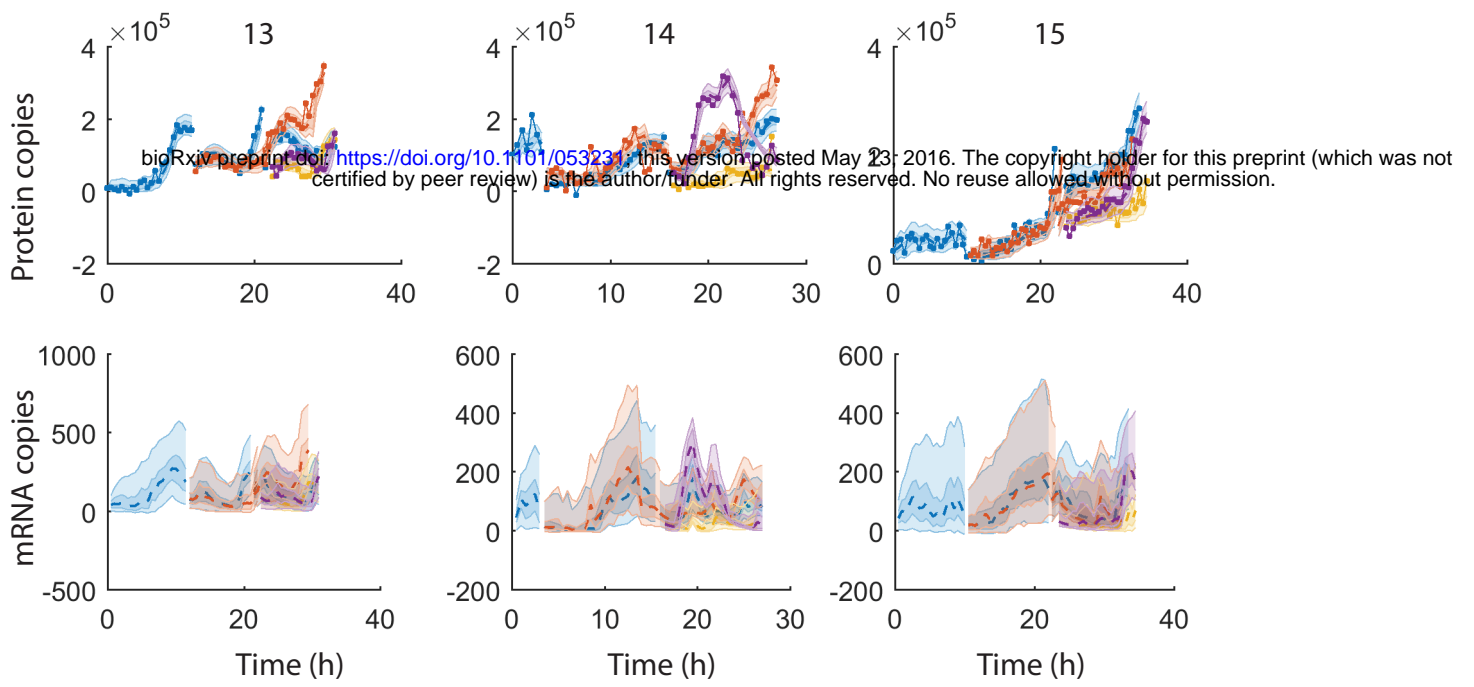
Figure S7

Figure S7

b

Figure S7

Figure S7

c
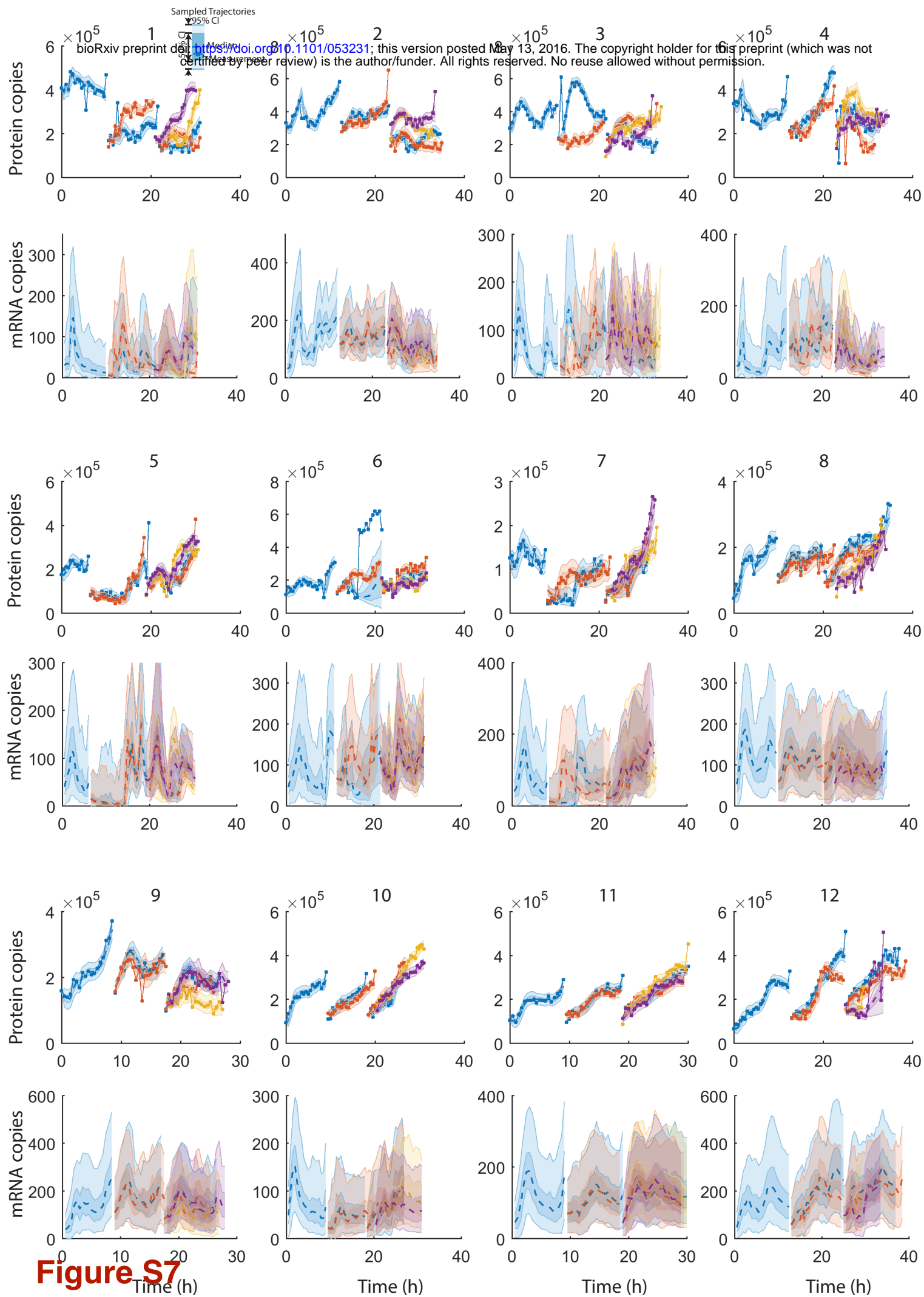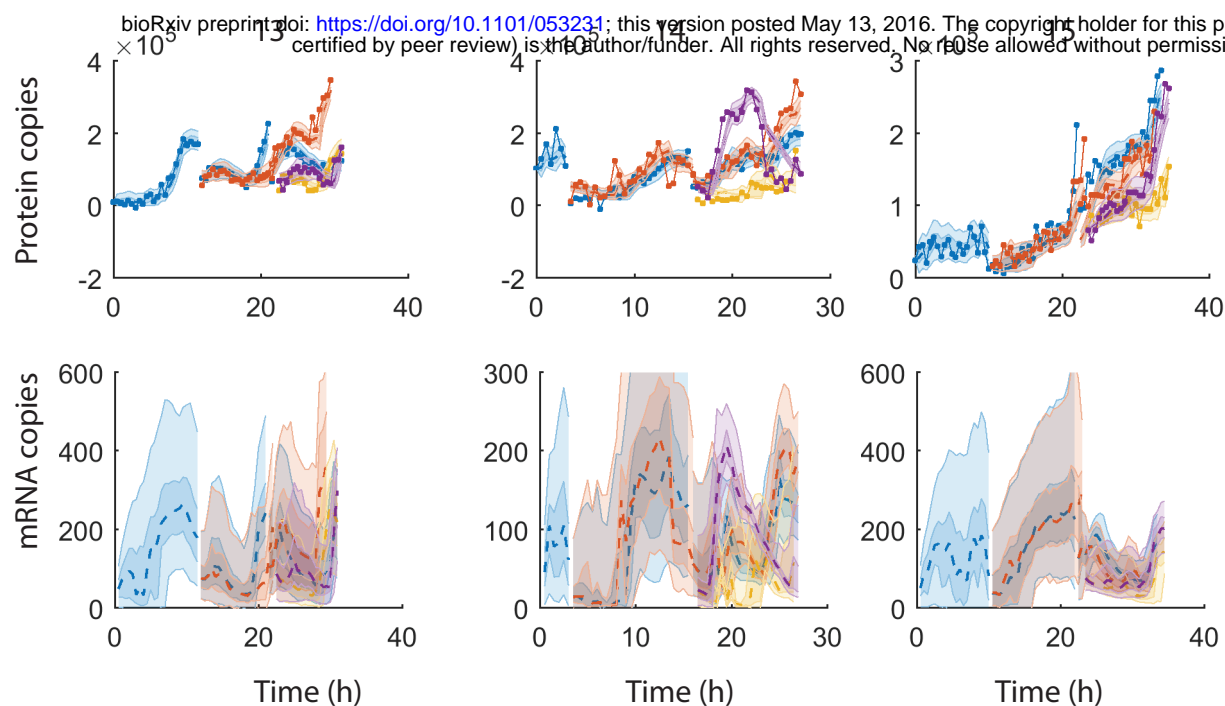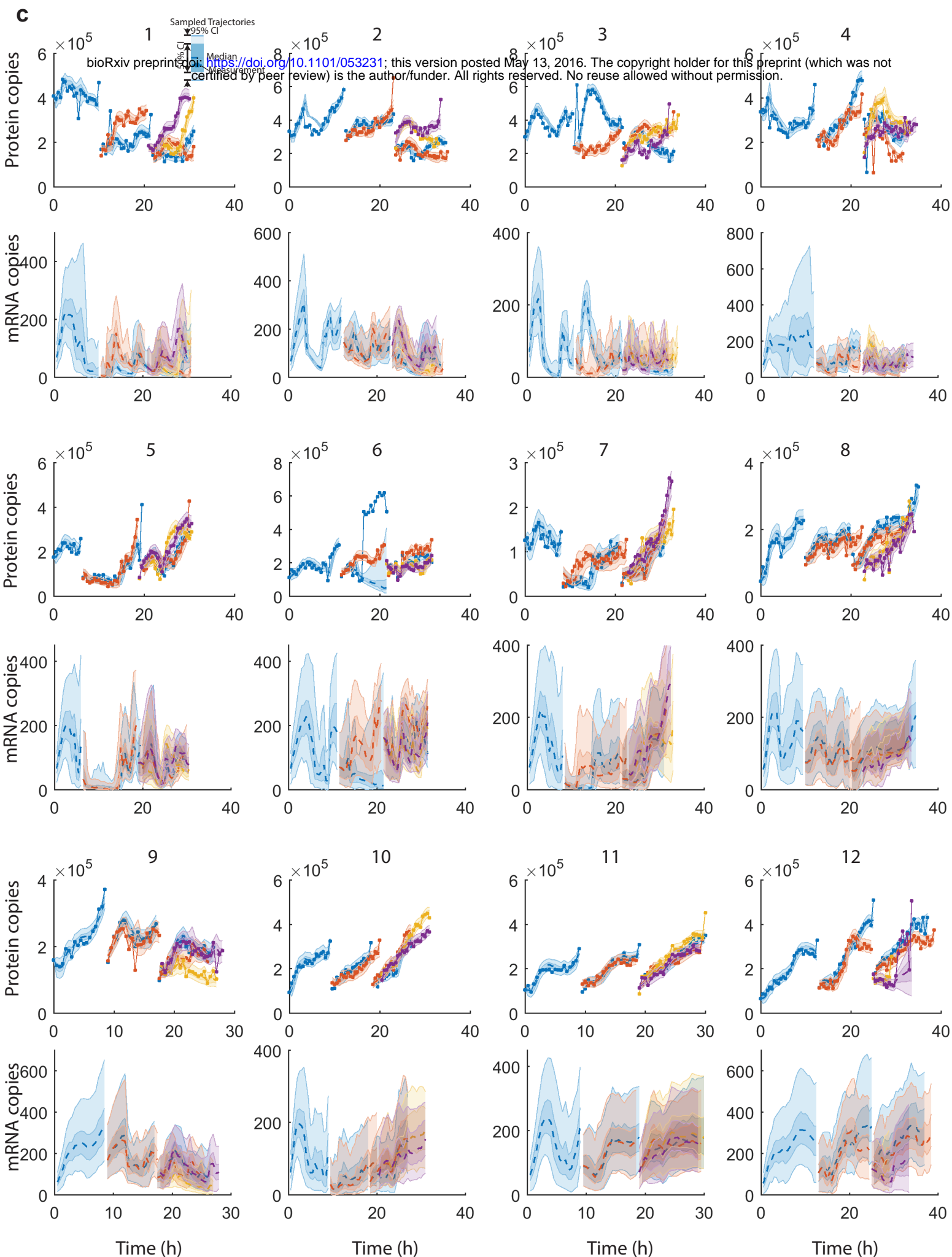
Figure S7

Figure S7

a No Feedback
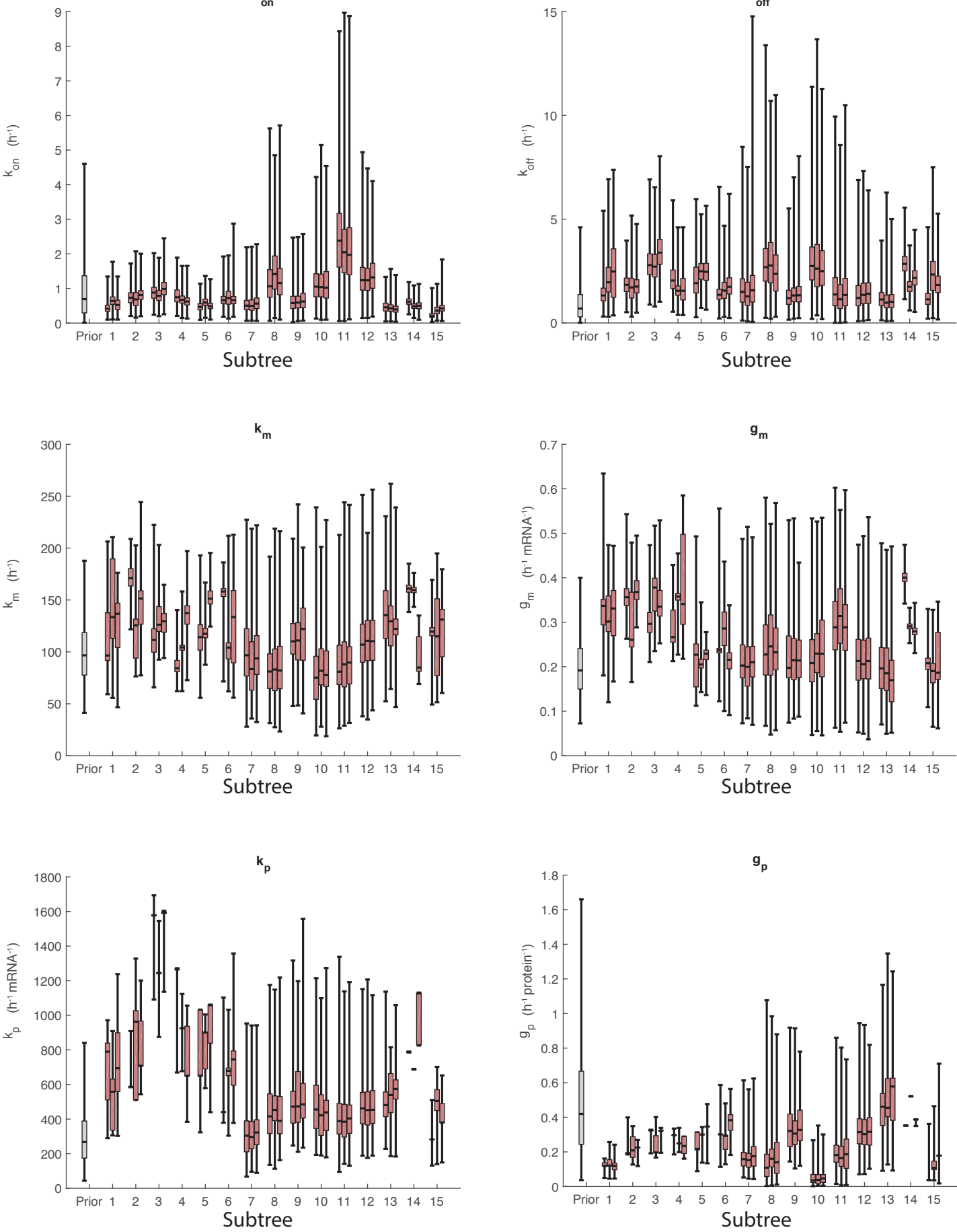
Figure S8

b Negative Feedback
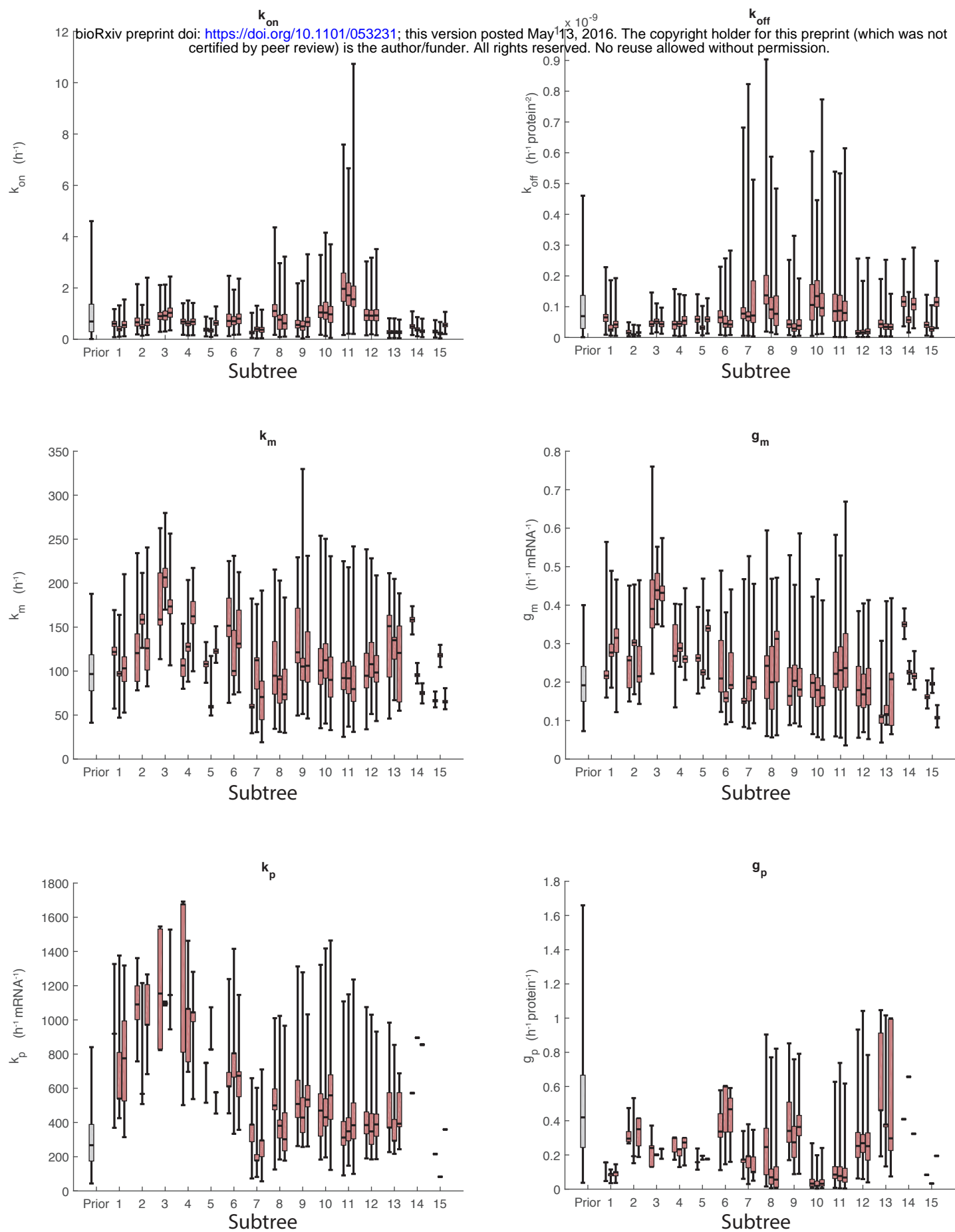
Figure S8

c   Positive Feedback
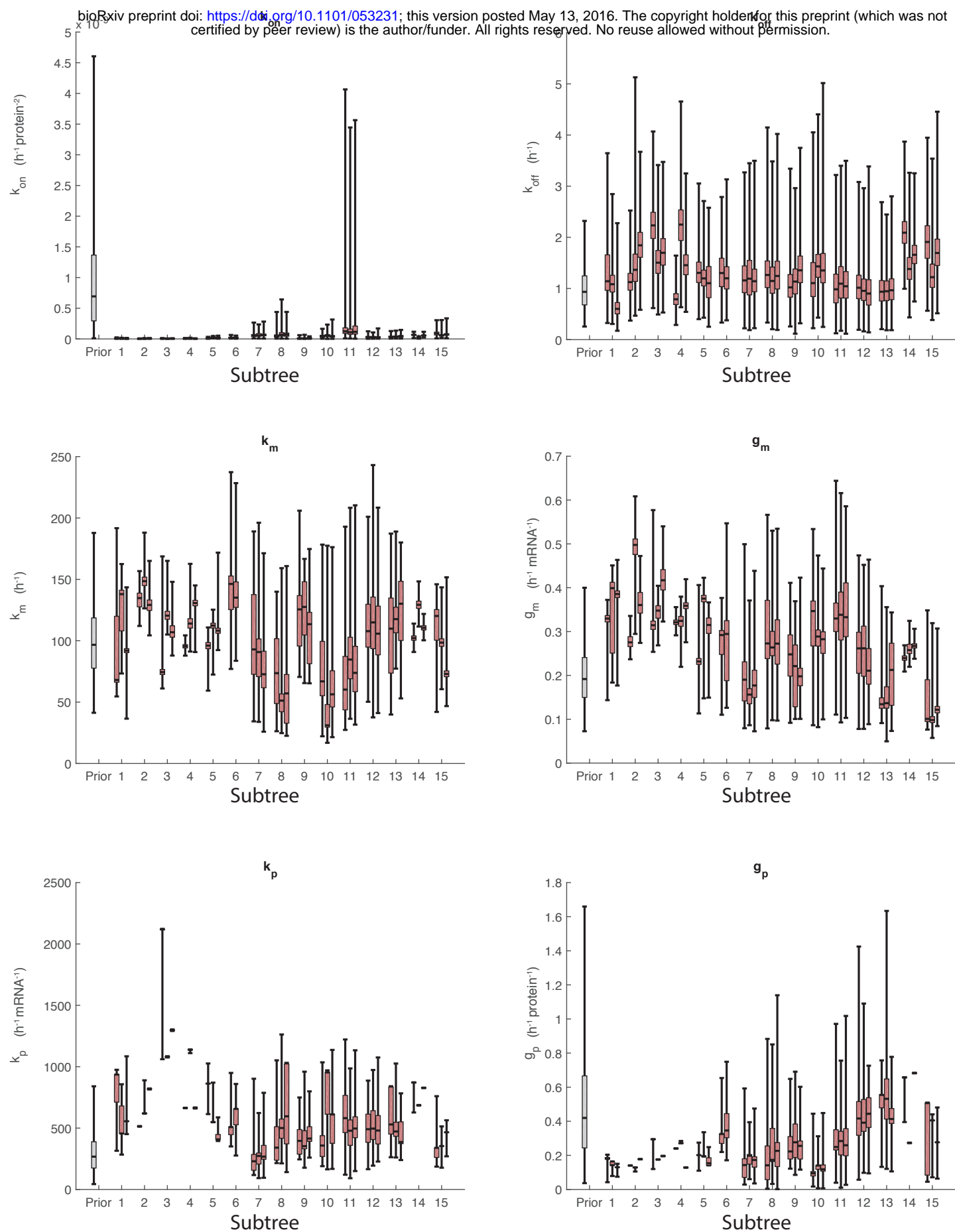
Figure S8

a

Figure S9
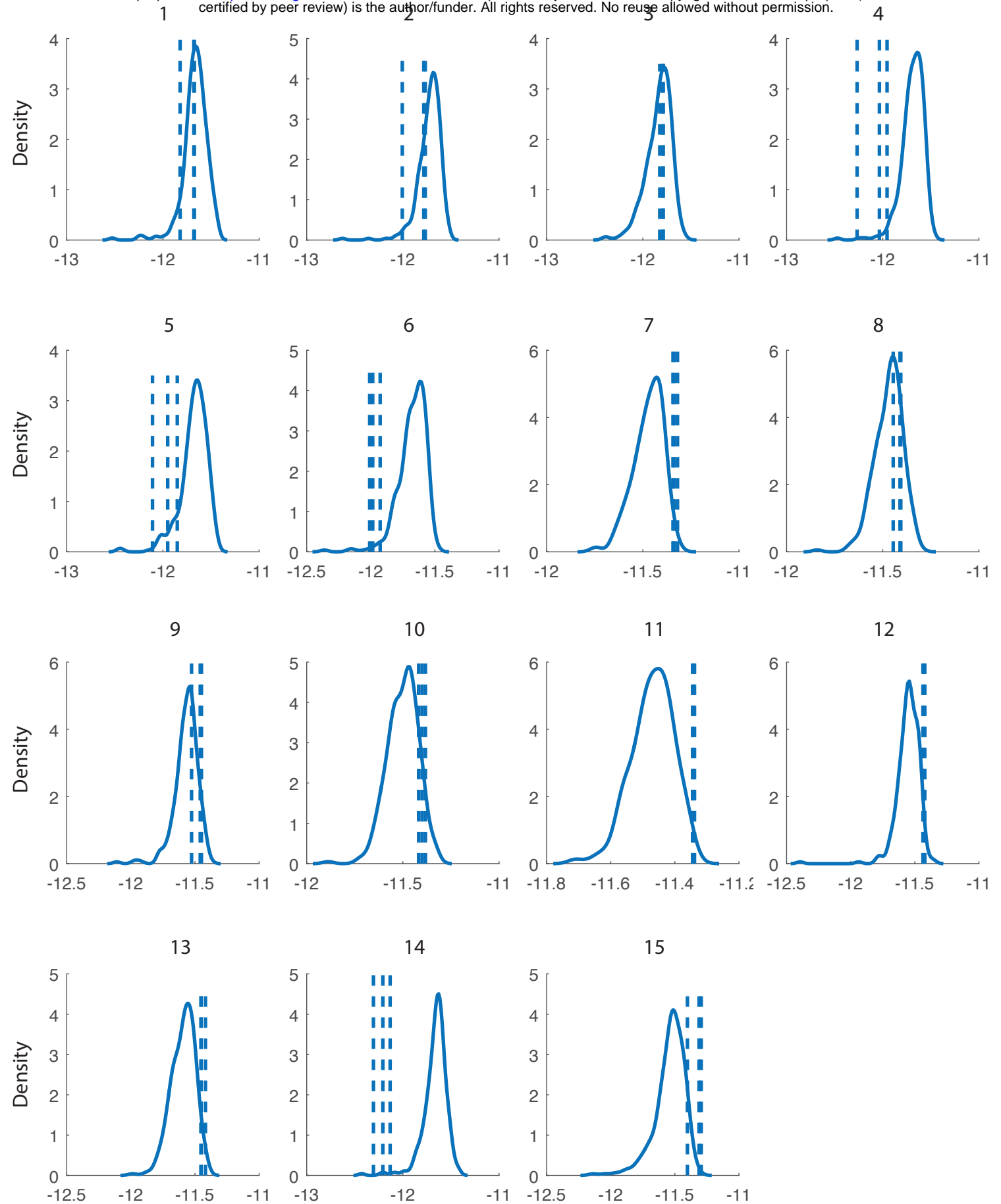
Average log likelihood per transition

b

Figure S9

Average log likelihood per transition

Figure S9

Average log likelihood per transition

Figure S10

a

b

c

d

e

Table S1

Parameter	Units	No Feedback	Negative Feedback	Positive Feedback
k_{on}	h^{-1}	1	10	5×10^{-7} protein^{-2}
k_{off}	h^{-1}	1	10^{-4} protein^{-2}	1
k_m	h^{-1}	40	100	40
g_m	h^{-1} mRNA^{-1}	3	3	3
k_p	h^{-1} mRNA^{-1}	300	2000	200
g_p	h^{-1} protein^{-1}	0.4	0.4	0.4

Table S2

parameter	No Feedback				Negative Feedback				Positive Feedback			
	α	β	mean	variance	α	β	mean	variance	α	β	mean	variance
k_{on}	5	2	2.5	1.25	5	0.8	4	3.2	10	1.2×10^7	8.33×10^{-7}	6.94×10^{-14}
k_{off}	5	2	2.5	1.25	7	10^5	7×10^{-5}	7×10^{-10}	14	20	0.7	0.035
k_m	12	0.2	60	300	12	0.2	60	300	12	0.2	60	300
g_m	7	1	7	7	7	1	7	7	7	1	7	7
k_p	4.3	0.005	860	1.72×10^5	4.3	0.005	860	1.72×10^5	4.3	0.005	860	1.72×10^5
g_p	5	5	1	0.2	5	5	1	0.2	5	5	1	0.2

Table S3

Fitted Model

a

No Feedback

Cell	No Feedback	Negative Feedback	Positive Feedback
1	0 (0.2105)	-9.3054 (0.2582)	-10.7013 (0.1581)
2	0 (0.1205)	-13.5696 (3.3602)	-5.935 (0.0862)
3	0 (0.0281)	-12.2594 (1.1507)	-7.3764 (0.1044)
4	0 (0.0909)	-15.0681 (1.3747)	-9.8305 (0.0782)
5	-1.1334 (0.121)	-33.2052 (6.1942)	0 (0.1186)
6	0 (0.0621)	-22.3497 (2.7166)	-6.9995 (0.141)
7	0 (0.0532)	-15.0969 (0.4353)	-5.1588 (0.1668)

log Bayes factor
(fitted vs. true)

0 weak

-50 strong

True Model

b

Negative Feedback

Cell	No Feedback	Negative Feedback	Positive Feedback
1	-4.131 (0.3035)	0 (0.1548)	-26.3066 (0.8125)
2	-2.502 (0.014)	0 (0.0777)	-14.6629 (0.1774)
3	-1.3918 (0.0288)	0 (0.0425)	-11.957 (0.1156)
4	0 (0.0426)	-4.1386 (0.5486)	-1.0796 (0.0182)
5	0 (0.0477)	-1.0327 (0.0177)	-8.6714 (0.1402)
6	0 (0.0782)	-5.2632 (2.1421)	-5.0105 (0.0225)
7	-0.2432 (0.031)	0 (0.0186)	-8.7574 (0.1)

Incorrect model preferred

c

Positive Feedback

Cell	No Feedback	Negative Feedback	Positive Feedback
1	-2.9141 (0.079)	-12.5306 (0.4929)	0 (0.0382)
2	-2.901 (0.243)	-14.1889 (1.3588)	0 (0.0643)
3	-0.9532 (0.0783)	-9.3542 (0.6612)	0 (0.021)
4	-4.4171 (0.0225)	-18.2459 (2.9465)	0 (0.0263)
5	-4.4039 (0.035)	-17.2991 (1.2285)	0 (0.0205)
6	-4.2933 (0.043)	-17.5176 (1.3442)	0 (0.0112)
7	-0.521 (0.0497)	-11.3935 (0.9244)	0 (0.0591)

Table S4

parameter	No Feedback				Negative Feedback				Positive Feedback			
	α	β	mean	variance	α	β	mean	variance	α	β	mean	variance
k_{on}	1	1	1	1	1	1	1	1	1	1.00E+09	1.00E-09	1.00E-18
k_{off}	1	1	1	1	1	1.00E+10	1.00E-10	1.00E-20	5	5	1	0.2
k_m	10	0.1	100	1000	10	0.1	100	1000	10	0.1	100	1000
g_m	8	40	0.2	0.005	8	40	0.2	0.005	8	40	0.2	0.005
k_p	3	0.01	300	30000	3	0.01	300	30000	3	0.01	300	30000
g_p	2	4	0.5	0.125	2	4	0.5	0.125	2	4	0.5	0.125

Table S5

a

Subtree	k_{on}	k_{off}	k_m	g_m	k_p	g_p
1	0.5278 [0.2494, 0.9398]	1.689 [0.7351, 4.511]	127.1 [78.92, 195.4]	0.3266 [0.1972, 0.4010]	631.0 [335.4, 946.9]	0.1194 [0.07609, 0.1619]
2	*(obscured by watermark)*	*(obscured)*	*(obscured)*	*(obscured)*	*(obscured)*	0.2080 [0.1675, 0.2982]
3	0.8809 [0.4867, 1.480]	2.951 [1.637, 5.037]	123.3 [93.08, 156.3]	0.3290 [0.2600, 0.4308]	1577. [1037., 1600.]	0.3221 [0.1955, 0.3268]
4	0.6741 [0.3988, 1.222]	1.707 [0.8542, 3.393]	105.3 [77.71, 149.3]	0.3413 [0.2466, 0.5089]	925.8 [648.8, 1268.]	0.2494 [0.1907, 0.2978]
5	0.5151 [0.2867, 0.8555]	2.361 [0.9045, 3.830]	125.0 [84.33, 175.1]	0.2209 [0.1384, 0.4380]	900.7 [441.3, 1060.]	0.3004 [0.08873, 0.4757]
6	0.6729 [0.3785, 1.225]	1.531 [0.7032, 3.342]	129.2 [68.45, 191.0]	0.2371 [0.1616, 0.3400]	650.6 [440.0, 1026.]	0.3012 [0.1543, 0.4495]
7	0.5217 [0.2093, 1.108]	1.449 [0.4071, 4.034]	92.63 [48.80, 167.6]	0.2045 [0.1058, 0.3587]	305.8 [152.0, 629.9]	0.1582 [0.05890, 0.3708]
8	1.204 [0.3767, 2.897]	2.610 [0.8905, 6.009]	82.06 [43.07, 153.6]	0.2346 [0.1041, 0.4177]	424.7 [208.3, 845.9]	0.1415 [0.02042, 0.5670]
9	0.5972 [0.2088, 1.389]	1.288 [0.5685, 2.953]	112.3 [62.40, 174.2]	0.2107 [0.1001, 0.4172]	472.2 [293.4, 899.2]	0.3185 [0.1324, 0.5748]
10	1.039 [0.3801, 2.799]	2.624 [0.7105, 6.255]	78.47 [34.25, 140.3]	0.2228 [0.09231, 0.3958]	439.8 [192.4, 864.5]	0.04076 [0.007483, 0.1525]
11	2.117 [0.6500, 4.721]	1.279 [0.2285, 4.058]	86.36 [45.60, 151.0]	0.2964 [0.1400, 0.4712]	388.9 [213.9, 784.5]	0.1781 [0.04347, 0.4186]
12	1.265 [0.5667, 2.539]	1.318 [0.4152, 3.668]	109.2 [65.54, 173.2]	0.2106 [0.1093, 0.3523]	454.5 [252.9, 863.8]	0.3121 [0.1523, 0.6088]
13	0.4223 [0.1992, 0.7883]	1.047 [0.4126, 2.373]	126.5 [78.50, 188.6]	0.1841 [0.1059, 0.3924]	520.3 [295.5, 870.4]	0.4732 [0.1807, 0.8521]
14	0.5335 [0.3118, 0.8082]	2.197 [1.234, 3.664]	157.2 [78.65, 168.6]	0.2929 [0.2640, 0.4238]	787.9 [687.5, 1129.]	0.3869 [0.3505, 0.5219]
15	0.3360 [0.1189, 0.6724]	1.642 [0.6390, 3.694]	119.3 [62.50, 163.7]	0.1978 [0.08838, 0.2973]	379.8 [212.8, 699.0]	0.1083 [0.03755, 0.4625]

b

Subtree	k_{on}	k_{off}	k_m	g_m	k_p	g_p
1	0.5216 [0.2561, 0.9515]	4.298e-11 [1.557e-11, 9.163e-11]	106.0 [60.36, 153.3]	0.2690 [0.1902, 0.4101]	810.1 [404.9, 1270.]	0.09880 [0.05760, 0.1564]
2	0.5837 [0.3210, 1.103]	1.338e-11 [6.942e-12, 2.876e-11]	139.7 [85.37, 181.2]	0.2674 [0.1660, 0.3442]	970.5 [508.9, 1264.]	0.2763 [0.1884, 0.4132]
3	0.9452 [0.5632, 1.497]	4.652e-11 [2.616e-11, 7.961e-11]	181.8 [133.7, 238.5]	0.4255 [0.3186, 0.5778]	1142. [826.4, 1538.]	0.2336 [0.1308, 0.2553]
4	0.6609 [0.3540, 0.9702]	4.628e-11 [1.111e-11, 8.545e-11]	126.0 [90.44, 196.6]	0.2725 [0.1914, 0.3671]	1064. [538.2, 1688.]	0.2395 [0.1765, 0.3013]
5	0.4161 [0.2137, 0.8372]	5.105e-11 [2.087e-11, 8.602e-11]	108.1 [56.33, 128.1]	0.2621 [0.2113, 0.3567]	747.4 [574.9, 829.0]	0.1749 [0.1573, 0.1948]
6	0.7412 [0.3428, 1.605]	4.966e-11 [2.000e-11, 1.509e-10]	138.2 [90.45, 198.9]	0.1853 [0.1141, 0.3616]	680.4 [357.8, 1143.]	0.4410 [0.1867, 0.6021]
7	0.3325 [0.1459, 0.6193]	7.212e-11 [2.743e-11, 2.761e-10]	70.52 [42.53, 119.2]	0.1868 [0.1119, 0.2970]	288.2 [110.8, 572.0]	0.1729 [0.07847, 0.3784]
8	0.8374 [0.2208, 2.281]	1.069e-10 [2.630e-11, 2.868e-10]	89.63 [53.23, 183.0]	0.2486 [0.09213, 0.4080]	413.3 [208.7, 967.1]	0.08476 [0.01174, 0.3864]
9	0.5748 [0.1812, 1.248]	3.685e-11 [1.303e-11, 1.119e-10]	110.7 [64.29, 192.6]	0.1937 [0.1017, 0.3446]	519.9 [258.1, 922.1]	0.3357 [0.08823, 0.6580]
10	1.020 [0.2756, 2.094]	1.123e-10 [2.867e-11, 2.970e-10]	101.5 [58.06, 162.0]	0.1742 [0.08430, 0.2964]	477.7 [188.4, 1076.]	0.03097 [0.008924, 0.1029]
11	1.737 [0.7700, 3.662]	8.337e-11 [1.324e-11, 2.949e-10]	89.78 [46.99, 168.7]	0.2281 [0.1028, 0.4001]	347.2 [161.1, 699.9]	0.07673 [0.003671, 0.2667]
12	0.9256 [0.4466, 1.652]	1.662e-11 [5.536e-12, 5.604e-11]	100.8 [59.09, 168.0]	0.1763 [0.08528, 0.3408]	380.9 [206.5, 704.1]	0.2599 [0.1138, 0.5157]
13	0.2737 [0.1365, 0.4713]	3.652e-11 [1.547e-11, 7.865e-11]	129.3 [59.63, 176.9]	0.1145 [0.05830, 0.2794]	380.3 [292.6, 957.8]	0.3785 [0.2116, 1.031]
14	0.3892 [0.2049, 0.6660]	9.569e-11 [3.942e-11, 1.647e-10]	95.43 [71.45, 163.9]	0.2285 [0.2021, 0.3632]	855.0 [571.3, 896.3]	0.4089 [0.3231, 0.6574]
15	0.3224 [0.1348, 0.7100]	4.340e-11 [1.460e-11, 1.498e-10]	67.20 [62.15, 122.1]	0.1613 [0.1004, 0.2071]	215.9 [82.53, 360.3]	0.08336 [0.03257, 0.1947]

c

Subtree	k_{on}	k_{off}	k_m	g_m	k_p	g_p
1	6.886e-12 [2.954e-12, 1.471e-11]	0.9715 [0.4093, 2.277]	92.67 [60.86, 150.4]	0.3517 [0.2226, 0.4212]	556.2 [327.4, 937.7]	0.1426 [0.1011, 0.1874]
2	5.027e-12 [2.328e-12, 9.829e-12]	1.406 [0.7829, 2.520]	136.5 [119.1, 160.5]	0.3561 [0.2584, 0.5338]	620.6 [513.4, 885.8]	0.1407 [0.1056, 0.1780]
3	5.302e-12 [2.539e-12, 9.259e-12]	1.788 [1.045, 2.821]	108.1 [70.41, 134.6]	0.3488 [0.2918, 0.4864]	1297. [1078., 2120.]	0.1960 [0.1754, 0.2945]
4	6.147e-12 [3.108e-12, 1.223e-11]	1.420 [0.5834, 2.862]	113.9 [92.67, 135.8]	0.3295 [0.2706, 0.3730]	664.1 [662.9, 1139.]	0.2402 [0.1283, 0.2732]
5	1.663e-11 [6.825e-12, 3.256e-11]	1.220 [0.6440, 1.860]	107.7 [90.55, 116.8]	0.3163 [0.2170, 0.3908]	549.2 [406.9, 863.3]	0.1952 [0.1416, 0.2017]
6	2.025e-11 [7.966e-12, 3.563e-11]	1.241 [0.7099, 1.989]	136.3 [102.4, 187.9]	0.2931 [0.1781, 0.4633]	509.3 [422.3, 856.5]	0.3257 [0.2372, 0.7476]
7	5.906e-11 [2.106e-11, 1.312e-10]	1.160 [0.5538, 2.086]	84.12 [50.13, 173.5]	0.1665 [0.1004, 0.3294]	264.9 [147.0, 443.0]	0.1493 [0.04987, 0.2877]
8	5.981e-11 [1.226e-11, 1.922e-10]	1.221 [0.6068, 2.317]	55.71 [27.60, 129.7]	0.2676 [0.1772, 0.4457]	449.4 [229.6, 1096.]	0.1735 [0.04880, 0.4815]
9	1.189e-11 [4.586e-12, 2.646e-11]	1.167 [0.5575, 2.124]	120.3 [74.46, 158.9]	0.2148 [0.1126, 0.3142]	401.9 [177.8, 727.5]	0.2557 [0.08608, 0.4413]
10	4.621e-11 [1.046e-11, 1.002e-10]	1.327 [0.5909, 2.391]	54.64 [27.88, 118.7]	0.2915 [0.1673, 0.4019]	561.9 [215.8, 956.2]	0.1182 [0.01787, 0.2674]
11	1.166e-10 [3.985e-11, 8.070e-10]	1.037 [0.4213, 2.051]	75.01 [37.27, 141.5]	0.3333 [0.1868, 0.4987]	519.5 [270.6, 973.3]	0.2662 [0.1131, 0.5989]
12	2.835e-11 [1.141e-11, 6.291e-11]	0.9565 [0.4372, 1.764]	110.3 [56.11, 180.1]	0.2452 [0.1185, 0.3760]	494.2 [271.8, 885.7]	0.4192 [0.1828, 0.7191]
13	3.752e-11 [1.752e-11, 7.549e-11]	0.9486 [0.4921, 1.673]	117.6 [66.48, 157.8]	0.1416 [0.07264, 0.3531]	473.0 [295.5, 835.0]	0.4783 [0.2177, 0.8186]
14	5.410e-11 [1.021e-11, 8.397e-11]	1.706 [0.9723, 2.579]	110.5 [98.44, 135.7]	0.2563 [0.2290, 0.2876]	827.7 [685.3, 871.5]	0.6567 [0.2727, 0.6832]
15	7.041e-11 [3.459e-11, 1.396e-10]	1.608 [0.8168, 2.680]	97.04 [66.62, 130.4]	0.1095 [0.08600, 0.2696]	353.8 [187.5, 560.3]	0.2776 [0.07192, 0.5078]

Table S6

Subtree	No Feedback	Negative Feedback	Positive Feedback
1	-1634.1 (0.4333)	-1636.3000 (0.9074)	-1641.6333 (0.8172)
2	-1814.7 (0.2646)	-1824.6000 (0.7211)	-1843.4667 (4.9320)
3	-1835.4 (0.5568)	-1834.6333 (1.1837)	-1865.3333 (4.3910)
4	-1700.3 (0.1528)	-1703.6333 (0.2906)	-1711.4000 (2.0075)
5	-1838.6 (0.4842)	-1843.9333 (1.5603)	-1848.7667 (2.1184)
6	-1597.1 (0.7126)	-1595.7000 (0.2000)	-1602.7858 (0.0231)
7	-1747.4 (0.1453)	-1753.1000 (0.7095)	-1754.5000 (0.1528)
8	-1820.4 (0.0882)	-1821.8667 (0.2603)	-1825.2333 (0.2333)
9	-1450.7 (0.0577)	-1454.8000 (0.1528)	-1453.7333 (0.2333)
10	-1554.4 (0.1732)	-1553.9000 (0.0000)	-1560.1000 (0.2517)
11	-1615.6 (0.0882)	-1615.1000 (0.0577)	-1617.6000 (0.1732)
12	-1591.0 (0.0577)	-1592.7333 (0.0667)	-1598.5333 (0.0882)
13	-1546.5 (0.1528)	-1551.8000 (0.1732)	-1554.8667 (0.6386)
14	-1714.6 (5.2129)	-1769.1000 (7.7253)	-1795.0667 (9.8660)
15	-1803.4 (0.4933)	-1832.0667 (0.2333)	-1810.9333 (0.7796)

Goodness-of-fit null distribution quantile

Table S7

Experiment	Subtree number	No Feedback	Negative Feedback	Positive Feedback
1	1	0.2978 (0.1125)	0.2033 (0.0996)	0.0033 (0.0033)
	2	0.1811 (0.0804)	0.2578 (0.0617)	0 (0)
	3	0.5478 (0.0473)	0.1444 (0.0307)	0 (0)
	4	0.0167 (0.0058)	0.0944 (0.0195)	0 (0)
2	5	0.0567 (0.0291)	0.0467 (0.0158)	0 (0)
	6	0.0222 (0.004)	0.0044 (0.0022)	0 (0)
	7	0.9867 (0.0058)	0.8478 (0.0478)	0.0533 (0.019)
	8	0.7422 (0.0713)	0.5322 (0.0356)	0.0267 (0.0051)
	9	0.8389 (0.0879)	0.6122 (0.0695)	0.0067 (0)
	10	0.9044 (0.0292)	0.59 (0.0386)	0.0867 (0.0102)
	11	0.9956 (0.0011)	0.9267 (0.0133)	0.16 (0.0084)
	12	0.9756 (0.0048)	0.9267 (0.0315)	0.0078 (0.0011)
3	13	0.97 (0.0133)	0.6011 (0.083)	0.02 (0.0033)
	14	0.0089 (0.0022)	0 (0)	0 (0)
	15	0.9789 (0.0211)	0.3689 (0.1529)	0.08 (0.0058)

Reject ($p < 0.01$ or $p > 0.99$)

Marginal ($p < 0.025$ or $p > 0.975$)

Accept

Supplementary Figure captions

Figure S1: Prior distributions for *in silico* testing. STILT was run using parameter prior distributions tailored to each model, chosen such that the true model parameter used for data generation is contained in the distribution, but not identical to the mode of the distribution. (A) No Feedback, (B) Negative Feedback and (C) Positive Feedback.

Figure S2: The particle filter provides estimates latent mRNA and DNA trajectories. Protein (top), mRNA (middle) and DNA (bottom) trajectories are estimated by STILT and show very good agreement between the true value (solid) and the resampled trajectories. The 50% and 95% confidence intervals of the resampled trajectories are shown as band plots, along with the median (dashed line). For DNA the true value (solid) is compared with the mean over the sampled histories (dashed) . The trajectories for each cell of the simulated lineage are plotted separately for improved visibility. In each case the correct model is assumed for the simulated data set. Results are shown for the (A) No Feedback, (B) Negative Feedback and (C) Positive Feedback models.

Figure S3: Posterior distributions of model parameters are robustly estimated in most cases. We estimate the posterior distribution of each model parameter for every combination of model used for data generation and model used for inference. Each combination is fit three times (red, 95% confidence interval) to provide an estimation of the robustness of the inference procedure, and compared against the prior distribution (gray). (A) Data generated with the No Feedback model. (B) Data generated with the Negative Feedback. (C) Data generated using the Positive Feedback model.

Figure S4: Parameter inference without including cellular lineage trees fails to converge to the correct model parameters. Single-cell-based inference was performed for each of the seven cells from each of the three synthetic datasets. The fractional error of each posterior is plotted and compared to the prior for each model parameter and dataset. The posteriors are robustly estimated, across the repeats of the inference procedure. However, STILT's tree-based inference shows improved parameter convergence to the true value compared to the single-cell-based inference for most parameters. Additionally, there is substantial variation among cells due to the difference in information content of their respective trajectories. (A) No Feedback, (B) Negative Feedback, and (C) Positive Feedback.

Figure S5: We pre-process quantified fluorescence lineage trees to remove inaccurate data. (A) Many cells show a substantial change in morphology, going from a flat (left) to round (middle) morphology just prior to division. This change often leads to an artificial jump in the quantified fluorescence intensity (right) at the last time point prior to division in many cells, and is thus censored. (B) Fluorescence signal at time points where cell nuclei overlap cannot be reliably quantified and are also censored. (C) Time points showing large fluctuations in fluorescence intensity due to contamination overlapping the segmented nuclei are likewise excluded.

Figure S6: We obtain 15 NanogVENUS subtrees of 7 cells from 3 experiments. 15 NanogVENUS subtrees of 7 cells each are fitted with each of the autoregulatory models. The subtrees are obtained from 7 microscopy positions from 3 independent experiments, obtained by dividing trees into non-overlapping subtrees of seven immediately-related cells. Unreliable data points (red) are censored (see Methods) and not used for inference.

Figure S7: The particle filter samples from latent trajectories for the protein (top) and mRNA (bottom) conditional on the observed protein measurements. The particle filter was performed for each of the NanogVENUS subtrees using the (A) No Feedback, (B) Negative Feedback and (C) Positive Feedback models.

Figure S8: We estimate the posterior distribution of all model parameters for every NanogVENUS subtree, fit with each of the three autoregulatory models. Each combination is performed in triplicate (red) to assess robustness with respect to the stochastic nature of the inference procedure. Priors distributions are shown in gray. Each subtree was fit with the (A) No Feedback, (B) Negative Feedback and (C) Positive Feedback models.

Figure S9: We use the goodness-of-fit test to determine which auto-regulatory models are compatible with which Nanog subtrees. We compute the goodness-of-fit quantiles of the real data with respect to simulations for the (A) No Feedback model, (B) Negative Feedback model and (C)Positive Feedback model.

Figure S10: We estimate autofluorescence and expression levels of endogenous Nanog reporters. (A) Top: Schematic Nanog overexpression construct. The NanogVENUS and iRFPnucmem proteins are translated at similar levels. iRFPnucmem allows direct comparison of the construct with an empty vector (no NanogVENUS) and Nanog alone (without VENUS). CAG = constitutive promoter; 2A = sequence for protein "cleavage"; iRFP (targeted to nuclear membrane) and VENUS = fluorescent proteins. Bottom: Schematic representation of cell lines. Cells express a fluorescently labeled Nanog protein (either VENUS or KATUSHKA) from one endogenous allele. Exogenous NanogVENUS was transiently transfected 2 days before analysis. (B) We estimate the autofluorescence of NanogVENUS (I_{neg}^{NV}) using wild-type mESCs.

We also estimate the 0.95 quantile of endogenous NanogVENUS (I_0^{NV}) in unperturbed NV cells. (C) We measure NanogVENUS levels and define compartments of exogenous Nanog as No Exogenous (below negative control levels); 1x, 2x, and 3x overexpression corresponding to up to 100%, 200% and 300%, respectively, of wild-type Nanog levels; and very high which has more than 300% wild-type Nanog expression. (D) We estimate the autofluorescence level (0.95 quantile) of NanogKATUSHKA (I_{neg}^{NK}) using the NanogVENUS cell line. The intensity distribution of unperturbed NanogKATUSHKA mESCs is shown for comparison. (E) We compare simulated (gray) and measured (white) down-regulation relative to the median of the No Exogenous overexpression compartment, for three experimental replicates. Distributions are of the relative expression of individual cells for both experiment and simulation.

Supplementary Table captions

Table S1: Model parameters used for generating the synthetic dataset. Parameters differ slightly between the No Feedback, Negative Feedback, Positive Feedback models so as to provide similar order of magnitude between trajectories generated from each model. The mRNA degradation (g_m) and translation (k_p) rate constants have units of per hour per count mRNA, and the protein degradation rate (g_p) per hour per count protein.

Table S2: Parameters of the gamma prior distributions $\Gamma(\alpha, \beta)$ used for inference of the synthetic datasets.

Table S3: Bayes Factor analysis shows that model selection is less robust for single-cell-based inference. The computed log Bayes Factors of each model indicate that the incorrect model is preferred (red boxes) for one cell in the (A) No Feedback dataset, and for 3 cells in the (B) Negative Feedback dataset. (C) The Positive Feedback model is inferred correctly for each of the Positive Feedback datasets. Each row indicates the difference of the marginal log likelihood (mean, s.d.; n=3) of each fitted model and the marginal log likelihood of the best model for that cell/dataset, i.e. a value of 0 indicates the best model for that cell/dataset.

Table S4: Parameters characterizing the gamma distributions $\Gamma(\alpha, \beta)$ used for parameter prior distributions for the NanogVENUS subtrees inference.

Table S5: We estimate the median (95% confidence interval) of the posterior distributions of each model parameter for every NanogVENUS subtree using the (A) No Feedback, (B) Negative Feedback, and (C) Positive Feedback models.

Table S6: Evidence of each subtree/model combination. We estimate the evidence (marginal log likelihood) of each model applied to each dataset using the particle filter (mean, s.e., n=3).

Table S7: We use the goodness-of-fit test to determine which autoregulatory models are compatible with the NanogVENUS subtrees. For each subtree and model we estimate the null distribution of the average marginal log likelihood per transition (see Figure S9). We use this empirical null distribution to compute the quantile of the average marginal log likelihood per transition of each dataset (mean, s.e.m., n=3 replicates). Each model is accepted if it is within the 95% confidence interval of the empirical distribution, marginally accepted if it is not accepted but within the 98% confidence interval, and rejected otherwise.

Online Methods to: Exact Bayesian lineage tree-based inference identifies Nanog negative autoregulation in mouse embryonic stem cells

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Contents

1   Chemical reaction networks

We consider the case of parameter inference and model comparison for stochastic models of gene regulation described by chemical reaction networks. A chemical reaction network consists of a set of chemical species (e.g. DNA, mRNA, protein, etc.) which may interact via a set of chemical reactions corresponding to synthesis, destruction, or modification.

Each reaction is defined by its stoichiometry, i.e. the quantity of each educt consumed and product produced by the reaction, and reaction rate. Reactions are presumed to take place stochastically as a function of the state of the system, i.e. the number of molecules of each species at a given point in time. The probability of a reaction occurring in infinitesimal time, called the reaction propensity, depends on the number of molecules of each educt available, the reaction volume (i.e. of the cellular compartment wherein the reaction takes place), and on a reaction constant. We consider reactions that are at most bimolecular, since reactions involving more than two species rarely occur in biology. Zeroth order reactions involve the production of a species with no dependence on an educt, for example due to constitutive production; their reaction propensities are constant. First order reactions proceed with propensity proportional to the number of available molecules of a single educt. Second order reactions involve two species, and their propensity is proportional to the abundances of both involved educts, and so on. The reaction constants k depend on the chemical species involved, temperature and reaction system volume. Reaction propensities are summarized in Table A1.

Reaction order	Reaction	Propensity function (a)
Zeroth	$\emptyset \to X$	k
First	$X \to Y$	kx
Second	$X + Y \to Z$	kxy
Second (same species)	$2X \to Y$	$kx(x-1)/2$
Third	$X + Y + Z \to A$	$kxyz$

Table A1: Reaction propensities for chemical reactions of zeroth, first, and second order. k denotes a kinetic constant and x, y, z the number of molecules of species X, Y and Z, respectively.

2 Inference of latent history and model parameters

2.1 Inference using bootstrap particle filtering

STILT builds upon the recursive, simulation-based particle filter first introduced by Pitt and Sheppard [1]. The particle filter approximates the posterior distribution of the latent history of all chemical species for each cell, and all model parameters by iteratively including new observations.

Consider a chemical reaction network with N_s chemical species, of which $N_o \leq N_s$ are observed via measurement. The vector of reaction constants governing the reactions of this network is denoted by $\boldsymbol{\theta}$. We denote by $\mathbf{Y}_{0:N} = (\mathbf{Y}_{t_0}, \dots, \mathbf{Y}_{t_N})$ the set of observations obtained at a series of N discrete measurement time points $t_0, \dots, t_N$. Each observation $\mathbf{Y}_t \in \mathbb{R}^{N_o}$ consists of measurements of N_o observed chemical species. We assume that the observations $\mathbf{Y}_t$ constitute noisy measurements of the true unknown state of the system at time t, denoted by $\mathbf{X}_t$. We denote by $\mathbf{X}_{[t_1, t_2]}$ the path (trajectory) of the random variable $\mathbf{X}_t$ from time t_1 to time t_2, and denote by $\mathbf{X}_{0:N} = (\mathbf{X}_{t_0}, \dots, \mathbf{X}_{t_N})$ the value of $\mathbf{X}_t$ at the measurement time points $t_0, \dots, t_N$.

The objective of the bootstrap particle filter is to sample from the posterior joint density $P(\mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta} | \mathbf{Y}_{0:N}, M)$ of latent trajectories $\mathbf{X}_{[t_0, t_N]}$ and parameters $\boldsymbol{\theta}$ for a model with index M, given the observed data $\mathbf{Y}_{0:N}$. We drop the model index M for simplicity; when comparing models we will again introduce this notation. The latent trajectories $\mathbf{X}_{[t_0, t_N]}$ are realizations of a stochastic process, and the data $\mathbf{Y}_{0:N}$ represent noisy observations of (a function of) the latent process obtained at discrete times. The posterior joint density depends on the likelihood $P(\mathbf{Y}_{0:N} | \mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta})$ and parameter prior probability distribution $\pi(\boldsymbol{\theta})$ according to Bayes' Law:

$$
\begin{aligned}
P(\mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta} | \mathbf{Y}_{0:N}) &= \frac{P(\mathbf{Y}_{0:N} | \mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta}) P(\mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta})}{P(\mathbf{Y}_{0:N})} \\
&= \frac{P(\mathbf{Y}_{0:N} | \mathbf{X}_{[t_0, t_N]}) P(\mathbf{X}_{[t_0, t_N]} | \boldsymbol{\theta}) \pi(\boldsymbol{\theta})}{P(\mathbf{Y}_{0:N})} \\
&= \frac{P(\mathbf{Y}_{0:N} | \mathbf{X}_{0:N}) P(\mathbf{X}_{[t_0, t_N]} | \boldsymbol{\theta}) \pi(\boldsymbol{\theta})}{P(\mathbf{Y}_{0:N})}.
\end{aligned}
\tag{1}
$$

The simplification on the right side of (1) is possible since the probability of observing data $\mathbf{Y}_{0:N}$ given a latent trajectory $\mathbf{X}_{[t_0, t_N]}$ depends only on its value at the measurement timepoints $\mathbf{X}_{0:N}$. Furthermore, it does not depend on the underlying parameters $\boldsymbol{\theta}$ of the stochastic process (measurement error is considered separately). The probability $P(\mathbf{X}_{[t_0, t_N]} | \boldsymbol{\theta})$ captures the evolution of the stochastic processes parameterized by $\boldsymbol{\theta}$.

The observations $\mathbf{Y}_{0:N}$ is related to $\mathbf{X}_{[t_0, t_N]}$ by a measurement function g with parameter $\boldsymbol{\eta}$: $P(\mathbf{Y}_{0:N} | \mathbf{X}_{0:N}) = g(\mathbf{Y}_{0:N}; \mathbf{X}_{0:N}, \boldsymbol{\eta})$. The function g depends on the measurement process and/or apparatus. For example, g might be a (multivariate) Gaussian in which case $\boldsymbol{\eta}$ contains the variance of the measurement process and potentially a scaling factor. We restrict ourselves to chemical reaction networks for which the stochastic process $\mathbf{X}_t$ is a Markov jump process on a subset of the integer lattice $\mathbb{N}^{N_s}$, corresponding to molecular copy numbers reachable by the chemical reactions of the network. For such a system, the exact likelihood of the latent trajectory $P(\mathbf{X}_{[t_0, t_N]} | \mathbf{X}_{t_0}, \boldsymbol{\theta})$ can be computed [2], and exact samples of $\mathbf{X}_{[t_0, t_N]} | \mathbf{X}_{t_0}, \boldsymbol{\theta}$ can be generated e.g. using Gillespie's algorithm [3]. Note that the transition density (i.e. $P(\mathbf{X}_{t'} | \mathbf{X}_t, \boldsymbol{\theta}), t' > t$) of the stochastic process is in general not known, but can be approximated for small systems, e.g. using the Finite State Projection [4].

Assuming uncorrelated errors in the observation function g, the likelihood $P(\mathbf{Y}_{0:N} | \mathbf{X}_{0:N})$ factorizes as:

$$
P(\mathbf{Y}_{0:N} | \mathbf{X}_{0:N}) = \prod_{i=0}^{N} P(\mathbf{Y}_{t_i} | \mathbf{X}_{t_i}).
\tag{2}
$$

for a series of N observations.

3

Furthermore, the stochastic process $\mathbf{X}_t$ is Markovian such that the probability $P(\mathbf{X}_s|\mathbf{X}_{[t_0,t]}) = P(\mathbf{X}_s|\mathbf{X}_t)$ for some $s \geq t$. The likelihood of the trajectory $\mathbf{X}_{[t_0,t_N]}$ therefore decomposes as:

$$P(\mathbf{X}_{[t_0,t_N]}|\boldsymbol{\theta}) = P(\mathbf{X}_{t_0}|\boldsymbol{\theta})\prod_{i=1}^{N}P(\mathbf{X}_{[t_{i-1},t_i]}|\mathbf{X}_{t_{i-1}},\boldsymbol{\theta}) \tag{3}$$

Following the derivation of Gordon *et al.* [5], we combine (2) and (3), and substitute into (1), to obtain a new expression for the posterior density:

$$
\begin{aligned}
P(\mathbf{X}_{[t_0,t_N]},\boldsymbol{\theta}|\mathbf{Y}_{0:N}) &= \prod_{i=1}^{N}\frac{P(\mathbf{Y}_{t_i}|\mathbf{X}_{t_i})P(\mathbf{X}_{[t_{i-1},t_i]}|\mathbf{X}_{t_{i-1}},\boldsymbol{\theta})}{P(\mathbf{Y}_{t_i})}P(\mathbf{X}_{t_0}|\boldsymbol{\theta})\pi(\boldsymbol{\theta}) \\
&= \frac{P(\mathbf{Y}_{t_N}|\mathbf{X}_{t_N})P(\mathbf{X}_{[t_{N-1},t_N]}|\mathbf{X}_{t_{N-1}},\boldsymbol{\theta})}{P(\mathbf{Y}_{t_N})} \\
&\quad \times \prod_{i=1}^{N-1}\frac{P(\mathbf{Y}_{t_i}|X_{t_i})P(\mathbf{X}_{[t_{i-1},t_i]}|\mathbf{X}_{t_{i-1}},\boldsymbol{\theta})}{P(\mathbf{Y}_{t_i})}P(\mathbf{X}_{t_0}|\boldsymbol{\theta})\pi(\boldsymbol{\theta}) \\
&= \frac{P(\mathbf{Y}_{t_N}|\mathbf{X}_{t_N})P(\mathbf{X}_{[t_{N-1},t_N]}|\mathbf{X}_{t_{N-1}},\boldsymbol{\theta})}{P(\mathbf{Y}_{t_N})}P(\mathbf{X}_{[t_0,t_{N-1}]},\boldsymbol{\theta}|\mathbf{Y}_{0:N-1})
\end{aligned}
\tag{4}
$$

This can be rewritten as

$$P(\mathbf{X}_{[t_0,t_N]},\boldsymbol{\theta}|\mathbf{Y}_{0:N}) = w_N\frac{P(\mathbf{X}_{[t_{N-1},t_N]}|\mathbf{X}_{N-1},\boldsymbol{\theta})}{P(\mathbf{Y}_{t_N})}P(\mathbf{X}_{[t_0,t_{N-1}]},\boldsymbol{\theta}|\mathbf{Y}_{0:N-1}) \tag{5}$$

where $w_N = P(\mathbf{Y}_{t_N}|\mathbf{X}_{t_N})$.

Hence, there is a simple update rule relating the posterior distribution using observations until timepoint t_{N-1} to the posterior distribution with the next observation at timepoint t_N. We note also that one can generate a sample from the posterior joint density at time t_i, $P(\mathbf{X}_{[t_0,t_i]},\boldsymbol{\theta}|\mathbf{Y}_{0:i})$, by first sampling a trajectory from the marginal distibution $P(\mathbf{X}_{[t_0,t_i]}|\mathbf{Y}_{0:i})$ and then sampling a parameter $\boldsymbol{\theta}|\mathbf{X}_{[t_0,t_i]}$, suggesting a Gibbs sampling approach.

These observations and the recursive factorization of the joint posterior (5) motivates the so-called bootstrap (recursive) particle filter [5], which iteratively generates samples (particles) from the posterior distribution conditioned on all prior observations:

Algorithm 1: Bootstrap particle filter

Data: A set of observed data points $\mathbf{Y}_{0:N}$ at timepoints $t_0, \ldots, t_N$, parameter prior $\pi : \mathbb{R}^d \to \mathbb{R}_{0,+}$, observation function $g(\mathbf{Y}; \mathbf{X}, \boldsymbol{\eta}) = P(\mathbf{Y}|\mathbf{X})$, number of particles K

Result: A set of particles $\left\{ \left(\mathbf{X}_{[t_0, t_N]}^{(k)}, \boldsymbol{\theta}^{(k)} \right) \right\}_{k=1}^{K}$ sampled from the posterior density $P(\mathbf{X}_{[t_0, t_N]}, \boldsymbol{\theta}|\mathbf{Y})$

1 Initialization;

2 **for** $k=1 \ldots K$ **do**

3 $\quad$ Sample parameter values from the prior: $\boldsymbol{\theta}^{(k)} \sim \pi(\boldsymbol{\theta})$;

4 $\quad$ Sample initial state conditional on first observed data point: $\mathbf{X}_{t_0}^{(k)} \sim \pi(\mathbf{X}_{t_0}|\mathbf{Y}_{t_0}, \boldsymbol{\eta})$;

5 $\quad$ Initialize particle weight to $w_0^{(k)} := 1/K$

6 Iterate over observation time points ;

7 **for** $i=1 \ldots N$ **do**

8 $\quad$ Generate a set of particle indices $\epsilon^{(k)} \in \{1, \ldots, K\}, k = 1, \ldots, K$ such that $P(\epsilon^{(k)} = a) = w_{i-1}^{(a)} / \sum_{\ell=1}^{K} w_{i-1}^{(\ell)}$;

9 $\quad$ **for** $k = 1 \ldots K$ **do**

10 $\quad\quad$ Generate a sample trajectory $\mathbf{X}_{[t_{i-1}, t_i]}^{(k)} \sim P(\cdot|\mathbf{X}_{t_{i-1}}^{(\epsilon^{(k)})}, \boldsymbol{\theta}^{(\epsilon^{(k)})})$;

11 $\quad\quad$ Concatenate to previously sampled trajectory: $\mathbf{X}_{[t_0, t_i]}^{(k)} := [\mathbf{X}_{[t_0, t_{i-1}]}^{(\epsilon^{(k)})}, \mathbf{X}_{[t_{i-1}, t_i]}^{(k)}]$;

12 $\quad\quad$ Set the weight of the kth particle to the likelihood: $w_i^{(k)} := P(\mathbf{Y}_{t_i}|\mathbf{X}_{t_i}^{(k)}) = g(\mathbf{Y}_{t_i}; \mathbf{X}_{t_i}^{(k)}, \boldsymbol{\eta})$;

13 $\quad\quad$ Generate a new set of parameters $\boldsymbol{\theta}^{(k)}$ from the conditional density: $\boldsymbol{\theta}^{(k)} \sim P(\boldsymbol{\theta}|\mathbf{X}_{[t_0, t_i]}^{(k)})$

14 Sample from the posterior ;

15 Generate a set of particle indices $\epsilon^{(k)} \in \{1, \ldots, K\}, k = 1, \ldots, K$ such that $P(\epsilon^{(k)} = a) = w_N^{(a)} / \sum_{\ell=1}^{K} w_N^{(\ell)}$;

16 Construct a sample of K particles from the posterior: $\left\{ \left(\mathbf{X}_{[t_0, t_N]}^{(\epsilon^{(k)})}, \boldsymbol{\theta}^{(\epsilon^{(k)})}|\mathbf{Y}_{0:N} \right) \right\}_{k=1}^{K}$

The recursive particle filter begins by sampling parameters $\boldsymbol{\theta}$ from the parameter prior distribution $\pi(\boldsymbol{\theta})$, and an initial state $\mathbf{X}_{t_0}$ from its prior, for an ensemble of K particles, i.e. each particle is a sample from the joint density of $\mathbf{X}_{t_0}$ and $\boldsymbol{\theta}$. At each iteration i, the particles are resampled according to their normalized weights $w_i^{(k)} / \sum_{\ell=1}^{K} w_i^{(\ell)}$, such that particles that have a state $\mathbf{X}_{t_i}^{(k)}$ for which the current observation $\mathbf{Y}_{t_i}$ is likely are sampled more frequently. After updating the latent histories $\mathbf{X}_{[t_0, t_i]}$, new samples are generated for the parameters conditional on those latent histories using a Gibbs sampling approach. Together the sample $(\mathbf{X}_{[t_i]}^{(k)}, \boldsymbol{\theta}^{(k)})$ is used to simulate a new trajectory on the interval $[t_i, t_{i+1}]$ using the stochastic simulation algorithm or variants [6, 7]. The result of the recursive particle filter at iteration i is an exact sample from the posterior joint density of $(\mathbf{X}_{[t_0, t_i]}, \boldsymbol{\theta}|\mathbf{Y}_{0:i})$, as shown in (4).

2.2 Gamma priors

We consider the case of chemical reaction networks, in which case each parameter $\theta_1, \ldots, \theta_d \in \boldsymbol{\theta}$ corresponds to the kinetic constant of a chemical reaction (see Table A1). The inference procedure is significantly simplified if one assumes that the prior of each parameter is gamma distributed, and that the prior distributions of all parameters are conditionally independent:

$$\pi(\boldsymbol{\theta}) = \prod_{p=1}^{d} \pi_p(\theta_p) = \prod_{p=1}^{d} \Gamma(\theta_p; \alpha_p, \beta_p) \tag{6}$$

where α_p and β_p are the hyperparameters for the distribution of $\theta_p, p = 1 \ldots d$, and $\Gamma(x; \alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} x^{\alpha-1} e^{-\beta x}$. The two parameters α and β of the gamma distribution can be chosen e.g. to match a target mean μ and variance σ^2:

$$\alpha \stackrel{!}{=} \mu^2/\sigma^2 \tag{7}$$

$$\beta \stackrel{!}{=} \mu/\sigma^2. \tag{8}$$

The assumption of conditional independence between model parameters is often justified, as information about the covariance of biological constants is often not available.

Using gamma priors for each model parameter, the likelihood $P(\mathbf{X}_{[t,t+\tau]}|\boldsymbol{\theta})$ of a particular (fully-observed) realization of the Markov jump process $\mathbf{X}_t$ on the interval $[t, t + \tau]$ is conjugate to the prior, such that the conditional density $P(\boldsymbol{\theta}|\mathbf{X}_{[t,t+\tau]})$ is also gamma distributed (see Wilkinson *et al.* [2], p. 281):

$$P(\boldsymbol{\theta}|\mathbf{X}_{[t,t+\tau]}) = \frac{P(\mathbf{X}_{[t,t+\tau]}|\boldsymbol{\theta})}{P(\mathbf{X}_{[t,t+\tau]})} \pi(\boldsymbol{\theta}) = \frac{P(\mathbf{X}_{[t,t+\tau]}|\boldsymbol{\theta})}{P(\mathbf{X}_{[t,t+\tau]})} \prod_{p=1}^{d} \Gamma(\theta_p; \alpha_p, \beta_p)$$
$$= \prod_{p=1}^{d} \Gamma(\theta_p; \alpha_p + r_p, \beta_p + G_p) \tag{9}$$

where r_p is the number of reaction firings of reaction p on the interval $[t, t + \tau]$. The term $G_p = \frac{1}{\theta_p} \int_t^{t+\tau} a_p(\mathbf{X}_s) ds$ is the integral of the reaction propensity a_p of the pth reaction (Table A1), rescaled by the reaction constant θ_p. The rescaling renders G_p dependent only on the instantaneous configuration of the system at all points along the trajectory, and not on the reaction constants. Hence, a new sample for $\boldsymbol{\theta}$ given the newly simulated trajectory (line 13 of Algorithm 1) can be generated by simply sampling from the updated gamma posterior (9); furthermore, the summary statistics r_p and G_p are sufficient for describing the posterior distribution of $\boldsymbol{\theta}_p$. Thus, the full trajectories do not need to be stored, but instead the new simulations can be used to merely update the parameters of the posterior distribution of $\boldsymbol{\theta}$ (i.e. set $\alpha_p \leftarrow \alpha_p + r_p, \beta_p \leftarrow \beta_p + G_p$), reducing storage requirements.

2.3   STILT: Stochastic Inference on Lineage Trees

The particle filtering strategy described in Algorithm 1 is suitable for inference of the latent history of a single cell. However, if the cellular lineage is known it is possible to exploit the tree structure to improve the performance of the inference algorithm, for instance by constraining the range of possible initial values for daughter cells at the moment of division according to the state of the mother cell. This is more informative than assuming arbitrary distributions for the initial conditions of latent species, as required in Algorithm 1. Moreover, when incorporating the tree structure, the inferred parameter values are required to generate trajectories that have a high likelihood for multiple cells simultaneously as the cells proliferate. Such an approach is more efficient than performing inference on all cells simultaneously while neglecting the chronological and genealogical order owing to the less constrained initial conditions and lack of convergence of the parameter distributions.

STILT performs tree-based inference as outlined in Algorithm 2. We consider a tree comprised of N_c total cells, with indices $j = 1, \ldots, N_c$. For the jth cell there is a series of N_j (possibly

6

multivariate) measurements obtained at times ${}^j t_1, \ldots, {}^j t_{N_j}$, corresponding to each of the N_o observed species, denoted by ${}^j\mathbf{Y}_{1:N_j} = ({}^j\mathbf{Y}_{{}^j t_1}, \ldots, {}^j\mathbf{Y}_{{}^j t_{N_j}})$, . The algorithm begins by initializing a set of K particles for the tree's founding cell with index $j = 1$, where each particle k comprises both a latent initial state ${}^1\mathbf{X}_{t_0}^{(k)}$ and a set of parameters $\boldsymbol{\theta}^{(k)}$. All particles are initially equally weighted as $1/K$. The algorithm then iterates through all of the measurement time points, where for simplicity we assume that measurements of all cells are obtained at a regular interval Δt (i.e. ${}^j t_\ell = n\Delta t \ \forall \ell, n \in \mathbb{N}$); however, the method is equally valid for irregular measurement time intervals. At each iteration i, particles are resampled with frequencies proportional to their weights, and cells that are alive/measured at the current timepoint $i\Delta t$ are simulated one time step using the generative stochastic process with the sampled parameters $\boldsymbol{\theta}^{(k)}$ to generate a sample ${}^j\mathbf{X}_{[i\Delta t,(i+1)\Delta t]}^{(k)}$ of the latent history of cell j over the time interval $[i\Delta t, (i + 1)\Delta t]$.

If a cell is observed to divide between this timepoint and the next, the cell's contents are allocated to the daughter cells. If both daughter cells are present, the total cellular contents of the mother cell must be conserved. For simplicity the division is assumed to take place just before the first observation of the two daughter cells at time $(i + 1)\Delta t$. Cells are ordered such that cell j gives rise to cells with indices $2j$ and $2j + 1$, with latent states ${}^{2j}\mathbf{X}_{t_{i+1}}^{(k)}$ and ${}^{2j+1}\mathbf{X}_{t_{i+1}}^{(k)}$, for the kth particle. The conservation relationship between mother and daughter cells is enforced by requiring that ${}^{2j}\mathbf{X}_{t_{i+1}}^{(k)} + {}^{2j+1}\mathbf{X}_{t_{i+1}}^{(k)} = {}^j\mathbf{X}_{t_{i+1}}^{(k)}$. However, some species may be presumed to be identical between mother and daughter cells, e.g. DNA in active or inactive conformation.

After each forward simulation or division step the likelihood $P({}^j\mathbf{Y}_{t_{i+1}}|{}^j\mathbf{X}_{t_{i+1}}^{(k)}) = g({}^j\mathbf{Y}_{t_{i+1}}; {}^j\mathbf{X}_{t_{i+1}}^{(k)}, \boldsymbol{\eta})$ of each latent history is computed according to the observation function g, and used to reweight the particles. The observations of each cell are presumed independent conditional on the latent state, thus the likelihood of the complete set of observed cells is the product of the likelihoods of each cell, and the total weight of particle k is given by the product of the weights of each observed cell at that time point.

Assuming conditionally independent gamma priors $\pi(\theta_p) = \Gamma(\theta_p; \alpha_p, \beta_p)$ for each parameter θ_p, the posterior probability of the model parameters conditional on the sampled latent histories until the current time point is shifted similarly to in (9), where α_p increases by the summed number of reaction firings and β_p by the summed integrals of the (rescaled) propensity functions, over *all* newly simulated trajectories on the interval $[i\Delta t, (i + 1)\Delta t]$. We define the set $\mathcal{A}_i$ to be the set of indices of all cells observed at any point on the interval $[0, i\Delta t]$:

$$\mathcal{A}_i = \left\{ j | {}^j t_1 \le i\Delta t \right\} \tag{10}$$

Let ${}^j r_p(i\Delta t)$ be the number of firings of reaction p in cell j at all times $t \le i\Delta t$ and ${}^j G_p(i\Delta t) = \frac{1}{\theta_p} \int_{{}^j t_1}^{\min({}^j t_{N_j}, i\Delta t)} a_p({}^j\mathbf{X}_s)ds$ be the integral of the rescaled propensity function of reaction p for cell j until time $i\Delta t$, for a particular realization of the stochastic process for cell j. With these definitions, the posterior joint density of model parameters $\boldsymbol{\theta}$ is given by:

$$P(\boldsymbol{\theta}|\mathcal{B}_i) = \prod_{p=1}^{d} \Gamma(\theta_p; \alpha_p + \sum_{a \in \mathcal{A}_i} {}^a r_p(i\Delta t), \beta_p + \sum_{a \in \mathcal{A}_i} {}^a G_p(i\Delta t)) \tag{11}$$

where the set $\mathcal{B}_i = \left\{ {}^a\mathbf{X}_{[{}^a t_1, \min({}^a t_{N_a}, i\Delta t)]} \right\}_{a \in \mathcal{A}_i}$ gives the set of realizations of the stochastic process for all cells observed at or before time $i\Delta t$. Eq. (11) provides the means to generate samples $\boldsymbol{\theta}^{(k)}$ from the probability density of model parameters conditional on a particular sampled complete genealogy $\mathcal{B}_i$. The parameter samples $\boldsymbol{\theta}^{(k)}$ for each particle k are obtained by substituting the sampled trajectories for that particle into all expressions, i.e. ${}^a\mathbf{X}$ becomes ${}^a\mathbf{X}^{(k)}$, ${}^a r_p$ becomes ${}^a r_p^{(k)}$, and ${}^a G_p$ becomes ${}^a G_p^{(k)}$. Since only the summary statistics are necessary to compute the posterior of the parameters, the full trajectories do not need to be saved, leading to a significant reduction in storage requirements. Finally, after iterating through all timepoints,

188 the particles are resampled according to their weights yielding a set of K latent trajectories
189 (if stored) and parameter sets. Thus the tree-based inference algorithm extends the single-cell-
190 based inference algorithm (Algorithm 1) by establishing continuity between mother and daughter
191 cells and initializing new latent trajectories for daughter cells according to the division process.

Algorithm 2: STILT algorithm

Data: A set of observations $\mathcal{Y} = \left\{ \left({}^j\mathbf{Y}_0, \ldots, {}^j\mathbf{Y}_{N_j} \right) \right\}_{j=1}^{N_c}$ of N_c cells observed at timepoints $\mathcal{T} = \left\{ {}^1\mathbf{T}, \ldots, {}^{N_c}\mathbf{T} \right\} = \left\{ \left({}^j t_1, \ldots, {}^j t_{N_j} \right) \right\}_{j=1}^{N_c}$; parameter prior $\pi : \mathbb{R}^d \to \mathbb{R}_{0,+}$; observation function $g(\mathbf{Y}; \mathbf{X}, \boldsymbol{\eta}) = P(\mathbf{Y}|\mathbf{X})$; number of particles K; measurement time interval Δt

Result: A set of particles $\left\{ \left(\left\{ {}^1\mathbf{X}^{(k)}, \ldots, {}^{N_c}\mathbf{X}^{(k)} \right\}, \boldsymbol{\theta}^{(k)} \right) \right\}_{k=1}^{K}$ sampled from the posterior density $P(\left\{ {}^1\mathbf{X}, \ldots, {}^N\mathbf{X} \right\}, \boldsymbol{\theta}|\mathcal{Y}, \mathcal{T})$

1 initialization;
2 **for** $k=1\ldots K$ **do**
3   Sample parameter values from the prior: $\boldsymbol{\theta}^{(k)} \sim \pi(\boldsymbol{\theta})$;
4   Sample initial state conditional on first observed data point: ${}^1\mathbf{X}_{t_0}^{(k)} \sim \pi(\cdot|{}^1\mathbf{Y}_{t_0})$;
5   Initialize particle weight to $w_0^{(k)} := 1/K$
6 Generate a set of particle indices $\epsilon^{(k)} \in \{1, \ldots, K\}, k = 1, \ldots, K$ such that $P(\epsilon^{(k)} = a) = w_0^{(a)} / \sum_{\ell=1}^K w_0^{(\ell)}$;
7 compute maximum of all timepoints: $t_{\max} = \max(\mathcal{T})$;
8 loop over all observed timepoints;
9 **for** $i = 0 : \lceil t_{\max}/\Delta t \rceil$ **do**
10   determine cells alive at this timepoint;
11 $\boldsymbol{\sigma} = \left\{ j | i\Delta t \in {}^j\mathbf{T} \right\}$;
12   loop over particles ;
13   **for** $k = 1\ldots K$ **do**
14   loop over cells at current timepoint ;
15   **for** $j \in \boldsymbol{\sigma}$ **do**
16   Get index of current timepoint for cell j;
17 $\ell = \text{find}({}^j t_\ell = i\Delta t)$;
18   Compute the partial weight of particle k for the jth cell: ${}^j w_i^{(k)} = P({}^j\mathbf{Y}_{{}^j t_\ell}|{}^j\mathbf{X}_{t_i}^{(k)}) = g({}^j\mathbf{Y}_{{}^j t_\ell}; {}^j\mathbf{X}_{t_i}^{(k)}, \boldsymbol{\eta})$;
19   Generate a sample trajectory ${}^j\mathbf{X}_{[i\Delta t, (i+1)\Delta t]}^{(k)} \sim P(\cdot|{}^j\mathbf{X}_{t_i}^{(\epsilon^{(k)})}, \boldsymbol{\theta}^{(\epsilon^{(k)})})$;
20   **if** $(i+1)\Delta t \notin {}^j\mathbf{T}$ **then**
21   Initialize daughter cells;
22 $\left({}^{2j}\mathbf{X}_{t_{i+1}}^{(k)}, {}^{2j+1}\mathbf{X}_{t_{i+1}}^{(k)} \right) \sim P(\cdot, \cdot|{}^j\mathbf{X}_{t_{i+1}}^{(k)})$;
23   **else**
24   Concatenate to previously sampled trajectory: ${}^j\mathbf{X}_{[{}^j t_1, (i+1)\Delta t]}^{(k)} := [{}^j\mathbf{X}_{[{}^j t_1, i\Delta t]}^{(\epsilon^{(k)})}, {}^j\mathbf{X}_{[i\Delta t, (i+1)\Delta t]}^{(k)}]$;
25   Compute the total weights for particle k: $w_i^{(k)} = \prod_{j \in \boldsymbol{\sigma}} {}^j w_i^{(k)}$;
26   Generate a set of particle indices $\epsilon^{(k)} \in \{1, \ldots, K\}, k = 1, \ldots, K$ such that $P(\epsilon^{(k)} = a) = w_{i+1}^{(a)} / \sum_{\ell=1}^K w_{i+1}^{(\ell)}$;
27   Sample new parameters $\boldsymbol{\theta}^{(k)}$ from the conditional density:
28 $\boldsymbol{\theta}^{(k)} \sim P\left(\boldsymbol{\theta}| \left\{ {}^j\mathbf{X}_{[{}^j t_1, i\Delta t]}^{(\epsilon^{(k)})} \right\}_{j=1}^{N_c} \right)$;
29 Construct a sample of K particles from the posterior:
$\left\{ \left(\left\{ {}^j\mathbf{X}_{[{}^j t_1, {}^j t_{N_j}]}^{(\epsilon^{(k)})} \right\}_{j=1}^{N_c}, \boldsymbol{\theta}^{(\epsilon^{(k)})}|\mathcal{Y}, \mathcal{T} \right) \right\}_{k=1}^K$

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2.4   Single cell versus tree-based inference

In the previous sections we presented two algorithms for inferring model parameters using the bootstrap particle filter. Algorithm 1 treats each cell individually while Algorithm 2 explicitly incorporates the known cellular lineage tree. As an alternative to Algorithm 2, it is also possible to fit all cells by simply discarding lineage knowledge, artificially synchronizing all cells to start at the same time point, and fitting cells in parallel. However, testing revealed that this approach quickly converges to local optima due to the inability to fit all cells simultaneously without information about their initial conditions. In contrast, Algorithm 2 benefits from exploiting the initial iterations of the algorithm with fewer cells in order to pre-converge the parameter distributions, and provides good estimates for the initial conditions of daughter cells upon division of the mother cell under the assumed division process.

The single-cell based inference performed consistently worse than the tree-based inference using STILT on synthetic data (Table S3, Figure S4), in terms of model identification and parameter estimates. This is likely because the single cell-based inference does not exploit the lineage structure to improve the estimation of the initial conditions (i.e. by enforcing conservation of inherited cellular material between mother and daughter cells), and because it is not obvious how to combine the inference results of individual cells in order to provide a better estimate of the overall population parameters.

3   Model assumptions

3.1   Cell division

We assume that at the time of division, each mother cell allocates its contents (mRNA and protein) randomly with equal probability to each daughter cell. Thus the number of mRNA molecules are distributed as:

$$P(M_1 = m_1, M_2 = m_2 | M_0 = m_0) = \frac{0.5^{m_0} m_0!}{(m_0 - m_1)! m_1!} \delta_{m_0 - m_1, m_2} \tag{12}$$

where M_1, M_2 are the number of mRNA molecules of the two daughter cells upon division, and M_0 that of the mother cell; $\delta_{x,y}$ is the Kronecker delta. The protein contents are allocated analogously, although for numerical reasons the binomial distribution is approximated by a normal distribution with equivalent mean and variance.

The conformation of the DNA (i.e. active or inactive) for each gene is assumed to persist from mother cell to daughter cell at division. This assumption is motivated by the observation that progeny of a cell typically resemble the ancestor cell in terms of gene activity. However, due to the stochastic nature of the model, some simulated trajectories may still switch activation state shortly after division, effectively permitting cells to also switch activation state upon division if this trajectory exhibits high likelihood. We note however that this is not an essential assumption of the inference procedure and can be easily changed for alternative scenarios.

3.2   Feedback models

In the feedback models, the DNA activation and inactivation rates are modified by the protein abundance. For the Negative Feedback model the amount of protein modulates the rate of DNA inactivation and for the Positive Feedback model protein modulates the rate of DNA activation. We consider the case of switch-like activation/inactivation of the DNA with increasing concentration of protein. We achieve this by assuming that the propensity of DNA activation in the Positive Feedback model is given by $a_{\text{on}} = k_{\text{on}} P^2$ and of DNA inactivation by $a_{\text{off}} = k_{\text{off}} P^2$ in the Negative Feedback model.

10

We assume fast binding and dissociation of protein to the DNA relative to protein production and degradation, such that the protein abundance can be treated as approximately constant on the time scale of binding dynamics. With this assumption, the probability of DNA being in either the active (DNA^*) or inactive state (DNA) evolves for the Negative Feedback model according to the chemical master equation:

$$\dot{P}(\mathrm{DNA}^*, t) = P(\mathrm{DNA}, t)k_{\mathrm{on}} - P(\mathrm{DNA}^* dt, t)k_{\mathrm{off}}P^2 \tag{13}$$

$$\dot{P}(\mathrm{DNA}, t) = -P(\mathrm{DNA}, t)k_{\mathrm{on}} + P(\mathrm{DNA}^*, t)k_{\mathrm{off}}P^2. \tag{14}$$

Requiring that $P_{\mathrm{SS}}(\mathrm{DNA}^*) + P_{\mathrm{SS}}(\mathrm{DNA}) = 1$, the steady state solution gives:

$$P_{\mathrm{SS}}(\mathrm{DNA}) = \frac{P^2}{\frac{k_{\mathrm{on}}}{k_{\mathrm{off}}} + P^2} \tag{15}$$

$$P_{\mathrm{SS}}(\mathrm{DNA}^*) = \frac{\frac{k_{\mathrm{on}}}{k_{\mathrm{off}}}}{\frac{k_{\mathrm{on}}}{k_{\mathrm{off}}} + P^2}. \tag{16}$$

Thus the probability of DNA being inactive is a sigmoidally increasing function of the number of proteins. This activation function is a Hill function with coefficient 2, corresponding to cooperative binding of two Nanog molecules at the promoter/enhancer. The quantity $(k_{\mathrm{off}}/k_{\mathrm{on}})^{1/2}$ determines the protein abundance for which the DNA has 50% probability of being active.

Similarly, for the Positive Feedback model, the probability of the DNA states evolves as:

$$\dot{P}(\mathrm{DNA}^*, t) = P(\mathrm{DNA}, t)k_{\mathrm{on}}P^2 - P(\mathrm{DNA}^*, t)k_{\mathrm{off}} \tag{17}$$

$$\dot{P}(\mathrm{DNA}, t) = -P(\mathrm{DNA}, t)k_{\mathrm{on}}P^2 + P(\mathrm{DNA}^*, t)k_{\mathrm{off}} \tag{18}$$

for which the steady state solution gives:

$$P_{\mathrm{SS}}(\mathrm{DNA}) = \frac{\frac{k_{\mathrm{off}}}{k_{\mathrm{on}}}}{\frac{k_{\mathrm{off}}}{k_{\mathrm{on}}} + P^2} \tag{19}$$

$$P_{\mathrm{SS}}(\mathrm{DNA}^*) = \frac{P^2}{\frac{k_{\mathrm{off}}}{k_{\mathrm{on}}} + P^2}. \tag{20}$$

which is a Hill function with coefficient 2 for the probability of DNA activation.

3.3 Biallelic expression

In the synthetic data sets we consider expression dynamics of a single allele only. Thus, there are precisely four species: DNA in active and inactive conformations, mRNA and protein. In the NanogVENUS subtree modeling, the fluorescent fusion protein NanogVENUS is also expressed only in a single allele [8]. Hence we apply the same models as for the synthetic data. However, there is also the possibility of expression in the other, unlabeled Nanog allele. Since we cannot quantify this allele, we assume that its expression is highly correlated to the observed allele, which has previously been reported for the same system [9]. Assuming equal proportions of observed and unobserved Nanog protein, the total amount is roughly double, which translates to a four-fold rescaling of the estimated rate constants k_{on} and k_{off} for the Positive and Negative Feedback models, respectively. The inference procedure is otherwise not affected.

3.4 Cellular compartments

For simplification, we do not explicitly model cellular compartments such as cytoplasm or nucleus. Thus nuclear translocation effects are implicitly captured by the estimated rate constants. The

259 NanogVENUS experiments analyzed [8] quantify only nuclear protein. Thus the model pertains
260 only to the expression dynamics of nuclear Nanog. The estimated protein degradation rate also
261 captures both degradation and implicitly the dilution to the cytoplasmic compartment.

4 Model specifications

4.1 Measurement function

STILT requires the specification of an observation function that yields the likelihood of a particular observation $\mathbf{Y}_{t_k}$ given the state of the latent history $\mathbf{X}_{t_k}$ at some time t_k, this function is referred to as g in Section 2 and corresponds to the measurement process. In the case of time-lapse fluorescence microscopy one typically assumes that the fluorescence intensity is proportional to the abundance of fluorophores. Assuming that the measurement process induces some small error ε, this gives the simple linear relation

$$\mathbf{Y}_{t_k} = \lambda \mathbf{X}_{t_k} + \varepsilon. \tag{21}$$

264 where λ is the mean fluorescence intensity per molecule. In the analysis of the synthetic lineage
265 trees (Figure 2), no conversion between proteins and fluorescence intensity was necessary, i.e. $\lambda = 1$.
266 We let $\varepsilon \sim \mathcal{N}(0, \sigma^2)$ with standard deviation $\sigma = 200$ proteins. This is the same as was used for
267 generating the noisy observations of the synthetic data.
268   In the analysis of NanogVENUS fluorescence lineage trees, we estimate $\lambda \approx 10^5$ proteins per
269 unit fluorescence intensity based on comparison of mean concentration estimated from Western
270 blot and mean fluorescence intensity of unbiased NanogVENUS lineage trees (see Section 7.2). We
271 likewise assume Gaussian measurement noise, and use the NanogVENUS lineage trees to estimate
272 the standard deviation to be approximately $\sigma = 2 \times 10^4$ based on the small signal fluctuations.
273 We note that the exact value of the measurement error should not bias the inference results, but
274 rather, too small a value will lead to non-robust estimation of parameters as there is a higher
275 risk of too many particles being discarded due to low likelihood, and too high a value leads to a
276 poorer ability to infer model parameters as too few particles are discarded. However, the robust
277 estimation of model parameters and apparent divergence from the prior (see Figure S8) seems to
278 indicate an adequate choice for the magnitude of the measurement error σ.

4.2 Prior distributions

280 STILT is a Bayesian inference technique and thus requires specification of prior distributions for
281 model parameters. We utilize Gamma priors distributions for each parameter, which greatly
282 simplifies the sampling procedure (see 2.2). For the *in silico* experiments, the true model parameter
283 were known. In this case, the priors distributions were chosen so that they i) contain the true model
284 parameters, and ii) allow for easy visual assessment of convergence to the true model parameters.
285   For the investigation of the Nanog subtrees, the prior distributions were obtained as follows.

mRNA degradation   The half-life of Nanog mRNA in mouse ES cells cultured in serum/LIF
287 has been estimated as 6.8 h [10], and 3.9-6.4 h [11]. We thus chose $\alpha = 8$ and $\beta = 40$ for which
288 the 95% confidence interval of the half-life is (1.9 h, 8.0 h).

Transcription   The Nanog mRNA transcription rate was recently estimated as approximately
290 125 molecules/h in serum/LIF [10]. Moreover, the number of Nanog mRNA molecules in mouse ES
291 cells under serum/LIF conditions is approximately 300 or fewer, rarely exceeding 400 [12, 13]. Using
292 the mean estimated degradation rate of 0.2 h^{-1}, and assuming DNA remains active, the expected
293 number of mRNAs (given by k_m/g_m) would thus be approximately 625 molecules which is more
294 than typically expected. We therefore set the prior distribution constants to be $\alpha = 10, \beta = 0.1$

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for which the 95% confidence interval of the transcription rate becomes $[47.95, 170.85]$ h^{-1}, and the expected number of transcripts is approximately 500. This number is somewhat reduced by the fact that the DNA is typically not persistently active, and by the cell division process which reduces the mRNA count by a factor of approximately 2.

Protein degradation The half-life of Nanog has been reported as approximately 2.1 ± 0.8 h [14]. Nanog's half-life was also measured in the analyzed data set and found to be closer to 5 h [8]. We therefore conservatively set the prior distribution constants to be $\alpha = 2, \beta = 4$ such that the 95% confidence interval of the half-life is approximately $0.5 - 11.5$ h.

Translation The translation rate of Nanog is not well characterized. However, the estimated mean number of Nanog molecules per cell is approximately 350,000, the mean degradation rate approximately 0.2 h^{-1}, and mean number of mRNA molecules roughly 200. In the deterministic limit, the expected number of proteins is given by $\langle p \rangle = \frac{k_m}{g_m} \langle m \rangle$, where $\langle p \rangle$ and $\langle m \rangle$ denote the mean protein and mRNA counts, respectively. Substituting our estimates, we obtain approximately 350 mRNA^{-1} h^{-1}. We thus chose $\alpha = 3, \beta = 0.01$ such that the mean (std.) translation rate is 300 ± 173 mRNA^{-1} h^{-1}. We note that this is in rough agreement with the mean estimated translation rate of 478 mRNA^{-1} h^{-1} over all analyzed genes in mouse fibroblasts (maximum estimated rate of 1000 mRNA^{-1} h^{-1}) [15].

DNA activation and inactivation The rate of DNA activation and inactivation for Nanog is not well studied. By inspecting the analyzed NanogVENUS subtrees, we surmise that periods of rapid fluorescence intensity likely correspond to periods of DNA activity, and periods of decline to DNA inactivity. Thus activation and inactivation presumably proceeds with expected waiting time on the order of hours and not days or longer. Consistent with this, Sokolik *et al.* estimated active/inactive switching times to be approximately 3.8 ± 1.2 h [14]. Since the autoregulation models studied differ in the form of their activation/inactivation rates, it was necessary to choose priors for each separately. For each of the three models, the prior distributions for k_{on} and k_{off} were chosen such that the waiting times for activation/inactivation were on the order hours, and such that trees simulated with these parameters produced reasonable dynamics, i.e. observed DNA state switching, and approximately correct order of magnitude for number of proteins.

4.3   Initial conditions

The initial state of the founder cell of the cellular lineage trees is unknown. In the considered models DNA and mRNA are entirely latent, while protein is observed with noise. For both the *in silico* experiments and the NanogVENUS subtrees, we initialized each cell's DNA state to be active or inactive with 50% probability, and to have an initial mRNA count uniformly sampled from $[0, 50]$. The protein copy number was sampled from a Gaussian distribution centered on the first observation, with standard deviation specified by the measurement function (see Section 4.1).

4.4   Number of particles

All implementations of the bootstrap particle filter require specification of the number of particles to use for approximating the latent history and posterior parameter distributions. The accuracy of the approximation improves in the Monte Carlo sense as the number of particles is increased. However, the incurred computational overhead increases proportionally. We used 7×10^5 particles for inference of the synthetic lineage trees, 10^5 for each synthetic cell for the single-cell-based algorithm, and 10^6 particles for the NanogVENUS subtrees. We determined the number of particles to use based on robustness of convergence of the parameter posteriors, and run-time. Inference

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338 typically completed on a multicore machine in approximately 10h for 10^6 particles for a single
339 subtree.

5   Implementation

341 STILT (see Algorithm 2) was implemented using Matlab 2015a. It includes code for importing
342 SBML models and fast, parallel stochastic forward simulations for the system state using Matlab's
343 parallel computing toolbox.

5.1   Model definition via SBML

345 Our implementation supports the import of biochemical network models from SBML using libS-
346 BML 5.12.0 [16], but can also be specified directly in Matlab. Species, reactions and their param-
347 eters are translated into a stoichiometric matrix and vectorized Matlab functions for computing
348 reaction propensities (Section 1).

5.2   Simulation

350 The stochastic simulation code was implemented using explicit, adaptive τ-leaping [17, 18], which
351 generates approximate samples from the exact stochastic process. In general, τ-leaping approxi-
352 mates the Markov jump process by a Poisson process with the same expected number of reactions
353 firing for time intervals where the reaction propensities remain relatively constant. Such an ap-
354 proximation is generally necessary when the system becomes stiff, i.e., when there exist reactions
355 with widely varying time scales such as is the case for the protein production and degradation
356 compared to DNA activation and inactivation. As for ref. [17] our implementation distinguishes
357 between critical and non-critical reactions (based on current educt availability, the parameter N_c is
358 set to 10) and performs explicit τ-leaping (with parameter $\epsilon = 0.03$) for non-critical reactions with
359 error bounding implemented for first, second and third order reactions. The simulation code was
360 implemented completely vectorized and provides the approximated integrated reaction propensi-
361 ties (for mass action propensities only) and the number of reactions firing, which are required for
362 inference (see Section 2). The forward simulation code can be further accelerated by converting the
363 entire function or only the Poisson random number generation to C code, which lead to significant
364 speedup for the studied systems.

5.3   Data structure

366 Measurement data are specified using a generic Matlab structure containing measurement times,
367 cell number and an indicator for censoring (e.g. for inaccurate or missing data) as well as measure-
368 ments and their respective measurement errors. Field names of measurements are automatically
369 matched to SBML species. Parameter priors, model specifications (e.g. behaviour on cell division),
370 compilation behavior and other user configurations are provided via an options structure.

6   Model evaluation

6.1   Marginal likelihoods and Bayes Factors

The particle filtering approach presented above can be used for performing model comparison via
Bayes Factors, i.e. by computing $\frac{P(M_1|\mathbf{Y}_{0:N})}{P(M_2|\mathbf{Y}_{0:N})}$, the ratio of the posterior probabilities of Model 1
(M_1) to Model 2 (M_2) for any two models. As before, we denote the series of observations at

times $t_0, \ldots, t_N$ by $\mathbf{Y}_{0:N} = (\mathbf{Y}_{t_0}, \ldots, \mathbf{Y}_{t_N})$. Using Bayes' law, one can reformulate the marginal posterior probability of a model M as:

$$P(M|\mathbf{Y}_{0:N}) = \frac{P(\mathbf{Y}_{0:N}|M)P(M)}{P(\mathbf{Y}_{0:N})} \tag{22}$$

Following Wilkinson *et al.* [2], p. 294, we can approximate the marginal likelihood of the model $P(\mathbf{Y}_{0:N}|M)$ using the sampled particles at each iteration i. Firstly, the distribution of the observed data at time t_{i+1} depends only observations up to t_i: $P(\mathbf{Y}_{t_{i+1}}|\mathbf{Y}_{0:N}, M) = P(\mathbf{Y}_{t_{i+1}}|\mathbf{Y}_{0:i}, M)$. Moreover, this probability is approximated by the expectation of the likelihood, or weights $w^{(k)}$, of the particles:

$$\begin{aligned} P(\mathbf{Y}_{t_{i+1}}|\mathbf{Y}_{0:i}, M) &= \int P(\mathbf{Y}_{t_{i+1}}|\mathbf{X}_{t_{i+1}})P(\mathbf{X}_{t_{i+1}}|\mathbf{Y}_{0:i}, M)d\mathbf{X}_{t_{i+1}} \\ &\approx \frac{1}{K}\sum_{k=1}^{K}\underbrace{P(\mathbf{Y}_{t_{i+1}}|\mathbf{X}_{t_{i+1}}^{(k)})}_{w_{i+1}^{(k)}} \end{aligned} \tag{23}$$

373 where the $\mathbf{X}_{t_{i+1}}^{(k)}$ are sampled (via the particle filter) from the marginal posterior up to time t_{i+1}
374 given by $P(\mathbf{X}_{t_{i+1}}|\mathbf{Y}_{0:i}, M)$. This is nothing more than a Monte Carlo approximation of the integral,
375 which provides an unbiased approximation of $P(\mathbf{Y}_{t_{i+1}}|\mathbf{Y}_{0:i}, M)$ with variance decreasing as K^{-1}
376 [19].

Next, since the distribution of each observation depends only on previous observations, the marginal probability of the entire set of observations $P(\mathbf{Y}_{0:N}|M)$ is given by the product:

$$P(\mathbf{Y}_{0:N}|M) = P(\mathbf{Y}_{t_0})\prod_{i=0}^{N}P(\mathbf{Y}_{t_{i+1}}|\mathbf{Y}_{0:i}, M). \tag{24}$$

377 Assuming *a priori* equally likely models, the factor of $P(M)$ in (22) cancels between the two
378 models and the Bayes Factor reduces to the ratio of marginal likelihoods. In the analysis presented
379 in this work we primarily utilize log Bayes Factors and marginal log likelihoods due to their superior
380 numerical performance.

381 6.2 Goodness-of-fit test

382 To assess the extent to which a particular model agrees with an observed data set, we developed
383 a simple goodness-of-fit (GOF) test. The GOF test utilizes an estimate for model parameters
384 obtained from the particle filter to generate many synthetic datasets, which are then compared
385 against the measured data. Specifically, we use the assumed model to generate many synthetic
386 lineage trees of the same number of generations as the observed data using the median posterior
387 parameter estimate of each parameter. For each newly simulated data set, we approximate its log
388 likelihood conditioned on the parameter set that was used to generate that data. The conditional
389 log likelihood (CLL) is approximated again via a particle filter, where the parameters are fixed.
390 This conditional particle filter only samples from the latent history of all state variables while
391 keeping the parameters fixed, and is essentially the same as in Algorithm 2 omitting the parameter
392 resampling step.

393 To compensate for the fact that the simulated datasets and the measured dataset do not neces-
394 sarily contain the same number of transitions, we normalize the estimated CLL of each simulation
395 by the number of simulated transitions (i.e. between measurement time points). We likewise
396 normalize the CLL of the actual data by the number of transitions (subtracting censored observa-
397 tions), to obtain the average CLL per transition. Without this compensation the CLL is always

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decreasing with the number of transitions since the log likelihood is never greater than zero, which could potentially bias the CLL depending on the random lifetime of each simulated cell.

In all applications of the GOF we used 300 samples to approximate the null distribution of the CLL, and 500 particles per sample to approximate the CLL. The GOF test approximates the null distribution of the CLL, i.e. the distribution of CLL values yielded by the particle filter when the parameters and model utilized are known to be true. We compute the CLL of the actual dataset using the same parameter values and compare it with the null distribution of the CLL. If it lies within this distribution, then with high probability the dataset could have been produced by the chosen mechanistic model and parameter set, and the model cannot be rejected. Conversely, if the CLL of the observed dataset lies outside the null distribution, the model and parameters are unlikely to have produced this dataset. Thus, we define three categories of model agreement with the null distribution: reject ($p < 0.01$ or $p > 0.99$), marginal ($p < 0.025$ or $p > 0.975$), and accept, otherwise. Empirical p-values are estimated using the empirical cumulative distribution function of the estimated CLL.

7   Time-lapse fluorescence microscopy data

7.1   Pre-processing

We obtained quantified time-lapse fluorescence microscopy movies of NanogVENUS in mouse embryonic stem cells from the data set of Filipczyk *et al.* [8] and converted fluorescence intensities to protein numbers as described in Section 4.1.

Since the time-lapse fluorescence microscopy quantification introduces error due to variability in the cellular (nuclear) segmentations, background correction, etc., we performed a data cleaning step prior to analysis. We censored measurements for all automatically segmented cells that could not be manually verified, e.g. if the cells were too densely packed or overlapping to be reliably quantified. We further censored very large jumps (the top 5% of absolute change in intensity) in the quantified intensity of individual cells, which result from either contamination due to microscopic debris, errors in cell segmentation, and in some cases jumps in the intensity at the last time point before cell division which presumably arise due to a sudden change in the cellular morphology preceding division that leads to a large overlap of cytoplasmic and nuclear volumes (see Supplementary Fig. 5 for examples). Censored measurements affect the inference by rendering all simulated particles equally likely at that iteration; the algorithm otherwise proceeds as normal.

After cleaning and selecting data sets, we obtained a total of 7 quantified cellular genealogies from 3 different experiments. To improve computational efficiency, and for comparison with the synthetic data, we subdivided these large trees into smaller subtrees each containing 7 cells with no overlap between subtrees, thus obtaining 4 subtrees from the first experiment, 8 subtrees from 3 different parent trees of the second experiment, and 1 subtree from each of 3 parent trees of the third experiment; in total 15 subtrees were used for further analysis (see Supplementary Fig. 7).

7.2   Estimation of fluorescence intensity conversion factor

To estimate the absolute number of NanogVENUS molecules per cell, we performed Western Blots experiments on 10% polyacrylamide gels. We compared Western Blots with a known quantity of NanogGFP single knock-in fusion ESCs and with different quantities of recombinant GFP (Catalogue number: 632373, Clonetech, CA, USA). Both NanogGFP and GFP proteins were detected using an anti-GFP primary antibody consisting of two monoclonal clones (Catalogue number: 1181460001, Roche, Mannheim, Germany). Western Blot band intensities were quantified by using the Gel Analyser tool in FIJI to gate on protein lanes and quantify band intensities over background. We found that the relationship between the GFP quantities x and the corresponding

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intensity y is best described by a sigmoid function:

$$y(x) = \left(\frac{\lambda x^n}{K^n + x^n} \right) \cdot \epsilon \tag{25}$$

The model parameters λ_j, K_j, n_j were obtained by local optimization using multiple restarts initialized according to Latin-hypercube sampling. The exponent n determines the shape of the sigmoid function, K sets the inflection point, λ is the maximum of the curve and ϵ is a log-normally distributed error term with expectation 1 and standard deviation σ, as is suggested for Western Blot data [20]. We compared this model against linear models both with and without intercept and found it to be superior according to both the Bayesian Information Criterion and coefficient of variation between replicates. We solve Eq. (25) for x to obtain

$$x = \frac{K_j}{\left(\frac{\lambda_j}{y_j} - 1 \right)^{\frac{1}{n_j}}} . \tag{26}$$

The total quantity of protein x is related to the cellular average P_j as

$$x = P_j \cdot c \cdot w. \tag{27}$$

where c is the number of loaded cells and w is the molecular weight for the protein of interest. Thus we determined the number of proteins P_j per cell from the sample intensity y_j of each Western Blot replicate j by first computing x from the observed intensity y according to Eq. (25), and then substituting into Eq. (27).

As P_j is a combination of uncertain variables, we obtained error bars for each P_j individually by applying standard error propagation to account for uncertainties in the number of cells c (we assume a standard deviation of 10%) and uncertainties in the model (estimated via the standard deviation σ of our noise model). However, we find that the uncertainties for each individual replicate P_j are always smaller than the inter-replicate standard deviations by a factor of 0.3 or smaller. Therefore, we only consider the standard deviation across replicates, as this is the dominant source of uncertainty in our procedure. Finally, we determined the fold-change between NanogVENUS and NanogGFP from three Western Blots. Uncertainty of protein abundance over replicates was estimated by simple error propagation. All above experiments and analysis were performed in triplicate.

The resulting estimate is of approximately $350,000 \pm 72,000$ molecules of NanogVENUS expressed in each cell. Using the distribution of NanogVENUS fluorescence intensities over unsorted mESCs, we obtain a median intensity of approximately 3.5, from which we determine the calibration factor of NanogVENUS fluorescence intensity to NanogVENUS molecules count to be approximately 100,000.

8 Experimental validation of Negative Feedback model

8.1 Exogenous Nanog construct

8.1.1 ESC culture

Mouse ESCs were of R1 background and report endogenous Nanog protein levels from one allele by fluorescent fusion proteins, either NanogVENUS (NV) or NanogKATUSHKA (NK). ESCs were cultured in DMEM (Catalogue number: D1145 Sigma, MO, USA) supplemented with 2mM GlutaMAX (Catalogue number: 35050-038, Gibco, USA),1% Non-essential amino acids (Catalogue number: 11140-035, Gibco, CA, USA), 1mM Sodium Pyruvate (Catalogue number: S8636, Sigma, MO, USA), 50uM b-mercaptoethanol (Catalogue number: M6250, Sigma-Aldrich, USA), 10% FCS

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463 (Catalogue number: 2602P250915, PAN, Aidenbach, Germany) and 10ng/ml LIF (GFM200, Cell
464 Guidance Systems, Cambridge, UK) on 0.1% porcine gelatin (Sigma, Catalogue number: G1890-
465 100G).

8.1.2 Nanog overexpression experiments

467 30000 cells were seeded in a well of a 24w plate and transfection was performed 5-7h after seeding.
468 For transfections, 250ng plasmid, 1ul Lipofectamine 2000 (11668-019, Life Technologies) and 50ul
469 Opti-MEM (31985-062; Life Technologies) were mixed and added to the cells. Cells were analyzed
470 by flow cytometry 46h after transfection using a BD LSR Fortessa (BD Biosciences, CA, USA)
471 and data were analysed with FlowJo (OR, USA). Cells were gated for non-debris and singlets using
472 FCS-A, SSC-A and FCS-W channels. Fluorescence channels were compensated using controls that
473 only expressed one of each fluorescent protein. R1 wild-type cells were used as control for cellular
474 autofluorescence. All experiments have been performed as triplicates.

8.1.3 Expression plasmids

476 The Nanog coding sequence was cloned in several variants as a 2A construct into a piggybac
477 vector that has been modified to express a fluorescent nuclear membrane tag (iRFPnucmem) from
478 the CAG promoter using the In-Fusion system (Catalogue number: 638911, Takara, Japan). The
479 resulting constructs are supposed to express iRFPnucmem and Nanog proteins in equal abundances.
480 The plasmid CAG.iRFPnucmem-P2A-NanogVENUS was used in overexpression experiments to
481 allow for comparison of exogenous NanogVENUS levels with endogenous NanogVENUS levels
482 of the R1 NanogVENUS cell line. The NanogVENUS plasmid performed identically to positive
483 control plasmids (CAG.iRFPnucmem-P2A-Nanog; with or without ATG for Nanog). An empty
484 vector control (CAG.iRFPnucmem-P2A) was also used during experiments.

8.2 Exogenous NanogVENUS expression compartments

486 Using the wild-type cell line which expresses no NanogVENUS, we obtained the NanogVENUS
487 intensity distribution due only to autofluorescence (Figure S10A), from which we deduce the 0.95
488 quantile of NanogVENUS autofluorescence, denoted I_{neg}^{NV}. We then used the expression distribution
489 of a cell line which expresses NanogVENUS at one endogenous allele (NV cell line, see Section 8.1)
490 to derive the 0.95 quantile of unperturbed NanogVENUS expression, denoted I_0^{NV} (Figure S10A).
491 We define the NanogVENUS No Exogenous compartment as NanogVENUS fluorescence inten-
492 sities that are below I_{neg}^{NV}. Since NanogVENUS is only expressed on one allele of the NV cell line,
493 the total quantity of Nanog in the cell is approximately twice this amount. Based on this we define
494 the 1x overexpression (OE) compartment to be intensities that are above the No Exogenous com-
495 partment but below 200% of the normal level I_0^{NV}. The 2x OE compartment has NanogVENUS
496 intensities I^{NV} between 2-4 times normal, and the 3x OE compartment between 4-6 times normal.
497 Cells with higher NanogVENUS intensities fall into the "very high" intensity compartment.

8.3 Downregulation of endogenous Nanog levels

499 To investigate negative feedback, we utilize the NK cell line (see Section 8.1), and compute
500 the expression levels of endogenous NanogKATUSHKA for different levels of exogenous trans-
501 genic NanogVENUS expression. We first obtain the autofluorescence intensity distribution on
502 the NanogKATUSHKA channel using NV cells which express no KATUSHKA, from which we
503 estimate the 0.95 quantile of intensity of the KATUSHKA negative compartment, denoted I_{neg}^{NK}
504 (Figure S10B). We first normalize NanogKATUSHKA fluorescence relative to background by sub-
505 tracting I_{neg}^{NK} from the measured intensities. We then compute the median fold-change, for each
506 overexpression compartment k, of normalized expression of NanogKATUSHKA relative to that

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k	NanogVENUS compartment	Intensity range ($\mathcal{I}_k^{NV}$)	NanogVENUS median expression (I_{med}^{NV}, % of I_0^{NV})
1	No Exogenous	$(-\infty, I_{\mathrm{neg}}^{NV})$	9.55%
2	1x OE	$[I_{\mathrm{neg}}^{NV}, 2 \times I_0^{NV})$	56.56%
3	2x OE	$[2, 4) \times I_0^{NV}$	263.87%
4	3x OE	$[4, 6) \times I_0^{NV}$	482.38%
5	very high	$[6 \times I_0^{NV}, \infty)$	1254.41%

Table A2: NanogVENUS compartments. Intensities are defined relative to the 0.95 quantile of NanogVENUS expression in the NV cell line I_0^{NV}, and the 0.95 quantile of NanogVENUS expression in the WT line, I_{neg}^{NV}. For each NanogVENUS intensity compartment we compute the median NanogVENUS intensity I_{med}^{NV} relative to I_0^{NV}.

of the No Exogenous compartment (see Figure 4E, Table A2). Denoting the NanogKATUSHKA expression of a cell with index j by I_j^{NK}, and its NanogVENUS expression by I_j^{NV}, the median fold-change for compartment k is given by:

$$\mathrm{FC}_k^{NK} = \frac{\displaystyle\operatorname*{median}_{\{j : I_j^{NV} \in \mathcal{I}_k^{NV}\}} \left(I_j^{NK} - I_{\mathrm{neg}}^{NK}\right)}{\displaystyle\operatorname*{median}_{\{j : I_j^{NV} \in \mathcal{I}_1^{NV}\}} \left(I_j^{NK} - I_{\mathrm{neg}}^{NK}\right)} \tag{28}$$

8.3.1 Comparison of experimental replicates

The NanogVENUS overexpression experiment described above was performed three times. To compensate for batch effects, the distributions in each experiment were normalized relative to the first experiment. Specifically, for each replicate, the fluorescence intensity of endogenous NanogKA-TUSHKA was scaled linearly so that the median intensity of cells matches to the median intensity of the first experiment. The same NanogKATUSHKA background level I_{neg}^{NK} was used for each of the three replicates (see Section 8.3).

8.4 *In silico* perturbation experiment

We replicate the experimental setup by extending the Negative Feedback model to include exogenous Nanog (P_{ex}), such that the propensity of DNA inactivation becomes

$$a_{\mathrm{off}} = k_{\mathrm{off}}(P_{\mathrm{en}} + P_{\mathrm{ex}})^2. \tag{29}$$

From the time-lapse fluorescence microscopy movies of NanogVENUS subtrees we obtain estimates of posterior distributions of parameters for the Negative Feedback model (Table S5b). We compute the median of the posterior for each parameter and subtree, and then the mean of the medians for each parameter over the subtrees (Table A3). We then perform *in silico* perturbation experiments using these mean parameter values and various levels of exogenous Nanog.

To mimic the experimental setup, we sampled intensity values I_{ex}^{NV} directly from the measured distributions of exogenous NanogVENUS for each overexpression compartment separately. We convert the sampled intensities into a specific number of molecules by computing the overexpression relative to wild-type NV cells. Since the fluorescent reporter is expressed only on one allele, a 100% increase of NanogVENUS corresponds to an approximately 50% increase in total Nanog levels. We assume approximately 2×10^5 NanogVENUS molecules in a cell with no exogenous perturbation (see Figure S7). We thus compute the sampled amount of exogenous NanogVENUS molecules as $P_{\mathrm{ex}} = \frac{1}{2} \frac{I_{\mathrm{ex}}^{NV}}{I_0^{NV}} (2 \times 10^5)$.

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Parameter	Value
k_{on}	0.6854
k_{off}	5.690×10^{-11}
k_m	110.3
g_m	0.226
k_p	619.5
g_p	0.220

Table A3: Parameter values used for simulation of exogenous Nanog

For each sampled quantity of exogenous NanogVENUS, we generated 50 synthetic lineage trees of 5 generations each. The founder cell of each lineage tree had DNA initially active, between 0 and 150 mRNA molecules (uniformly sampled), and between 10^5 and 2×10^5 Nanog molecules (uniformly sampled). The exogenous Nanog levels were held fixed at the sampled value for the duration of the simulation.

8.5   Comparison to simulations

The distribution of endogenous Nanog following perturbation was computed for each overexpression compartment after 46h of simulated time. The fold-change of endogenous Nanog expression relative to expression with no perturbation was computed analogously to (28):

$$\text{FC}_{j,k}^{\text{sim}} = \frac{N_{j,k}^{\text{sim}}}{\text{median}(N_{j,1}^{\text{sim}})} \tag{30}$$

where $N_{j,k}^{\text{sim}}$ denotes the number of endogenous Nanog molecules of cell j, 46 hours after the perturbation corresponding to compartment k.

In Figure 4E, we plot the distribution of the fold-change of simulated cells with respect to the No Exogenous compartment as a box-and-whiskers plot (median shown as red line). We compare this against the median (mean, s.e.m., n=3 experimental replicates) fold-change computed for the experimental data, see Eq. (28). The comparisons against each experimental replicate individually are shown in Figure S10E.

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